

TOPICS IN D -MODULES.

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1. INTRODUCTION: LOCAL SYSTEMS.

1.1. **Local Systems.** Consider the differential equation (DE)

$$\frac{d}{dz}u(z) = \frac{\lambda}{z}u(z), \quad \lambda \in \mathbb{C} \text{ a constant.}$$

An undergraduate might say that a solution to this is z^λ – but what does this mean for λ non-integral?

$$u(z) = z^\lambda = e^{\lambda \log(z)} \text{ for a branch of log.}$$

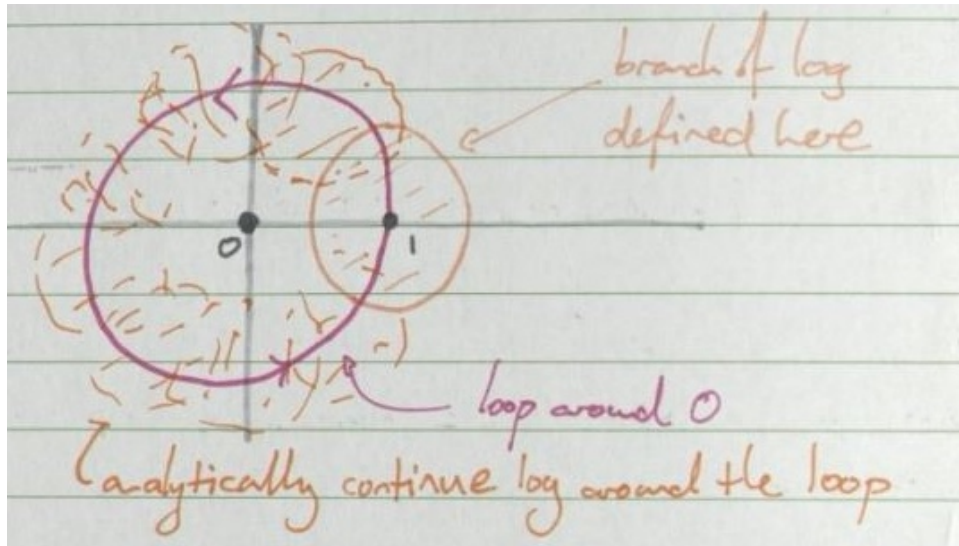


FIGURE 1. Analytic continuation of a solution of a DE around a loop.

The analytic continuation changes

$$\left. \begin{array}{l} \log(z) \mapsto \log(z) + 2\pi i \\ z^\lambda \mapsto e^{2\pi i \lambda} z^\lambda \end{array} \right\} \text{“monodromy”}$$

Could say that z^λ is a multivalued function. The space of *local* solutions form a *local system*. We will see various definitions of local systems shortly.

Let X be a (reasonable) topological space, and $\text{Op}(X)$ the lattice of open sets; i.e. a category with a unique morphism $U \rightarrow V$ if $U \subset V$.

Definition 1. A *presheaf* (of vector spaces) \mathcal{F} is a functor

$$\mathcal{F} : \text{Op}(X)^{\text{op}} \rightarrow \text{Vect} = \text{vector spaces over } \mathbb{C}.$$

I.e. for every $U \subset X$ open, $\mathcal{F}(U)$ is a vector space, and if $U \subset V$ there is a unique linear map (think “restriction”) $\mathcal{F}(V) \rightarrow \mathcal{F}(U)$. We call $\mathcal{F}(U) = \Gamma(U; \mathcal{F}) = \text{“sections of } \mathcal{F} \text{ of } U\text{”}$.

Definition 2 (Non-precise). A presheaf \mathcal{F} is a *sheaf* if sections of \mathcal{F} on U are “precisely determined by their restriction to any open cover.”

Definition 3 (Formal). If $\{U_i\}$ is an open cover of U ,

$$\mathcal{F}(U) \rightarrow \prod_i \mathcal{F}(U_i) \rightrightarrows \prod_{i,j} \mathcal{F}(U_i \cap U_j)$$

is an equaliser diagram.

Example 1. Various kinds of functions form sheaves:

- all functions;
- C_X the sheaf of continuous functions on X ;
- C_X^∞ smooth functions (if X is a smooth manifold);
- $\mathcal{O}_X^{\text{an}}$ holomorphic functions (if X is a complex manifold).

Example 2. The functor $\mathbb{C}_X^{\text{pre}}$ of constant functions on X is *not* a sheaf (consider the two point space with the discrete topology).

Example 3. We can improve the above example so that it becomes a sheaf by instead considering the **locally** constant functions \mathbb{C}_X . We call this a *constant sheaf*.

Remark Presheaves form a category (functor category); sheaves are contained in this as a full subcategory.

Definition 4. A sheaf is *locally constant of rank r* if there is an open cover $\{U_i\}$ of X such that

$$\mathcal{F}|_{U_i} \cong \mathbb{C}_{U_i}^{\oplus r}.$$

Example 4. The solutions to the DE at the start of this section form a locally constant sheaf. On contractible sets not containing 0 the solutions form a 1d vector space, and there are no global sections.

Definition 5 (One definition of a local system). A *local system* is a locally constant sheaf.

Definition 6. The *stalk* of a sheaf \mathcal{F} at a point x is

$$\mathcal{F}_x = \frac{\text{colim}}{\text{open } U \ni x} \mathcal{F}(U).$$

We sometimes call elements of the stalk *germs of sections of \mathcal{F} near x* .

I.e. the stalk is sections on $\mathcal{F}(U \ni x)$ where $s_U \in \mathcal{F}(U)$ and $s_V \in \mathcal{F}(V)$ are equivalent if there is $W \subset U \cap V$ containing x such that $s_U|_W = s_V|_W$.

If \mathcal{F} is locally constant,

$$\mathcal{F}_x = \mathcal{F}(U) \cong \mathbb{C}^r \text{ for some small enough open set } U \ni x.$$

Since the rank of a locally constant sheaf is constant on components, if x and y are in the same component, $\mathcal{F}_x \cong \mathcal{F}_y$. How can we realize this isomorphism?

If $\gamma : [0, 1] \rightarrow X$ is a path with $\gamma(0) = x$ and $\gamma(1) = y$, and \mathcal{F} is a locally constant sheaf, we can make the following observation:

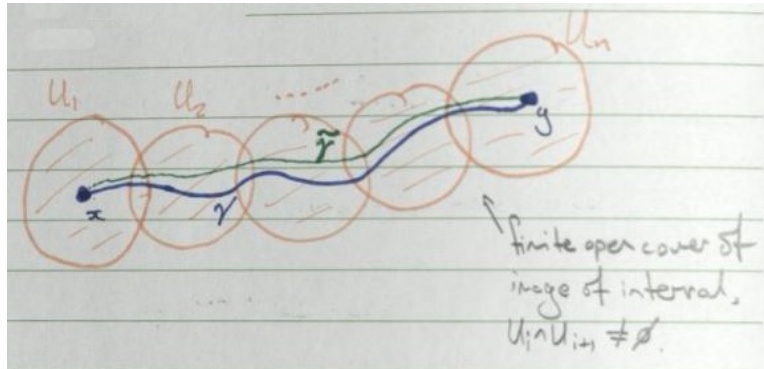


FIGURE 2. Parallel transport of a section along a path.

Proposition 1.1. *There is an isomorphism $t_\gamma : \mathcal{F}_x \xrightarrow{\sim} \mathcal{F}_y$.*

Proof. The isomorphism t_γ is given by the chain of isomorphisms

$$\mathcal{F}_x \xleftarrow{\sim} \mathcal{F}(U_1) \xrightarrow{\sim} \mathcal{F}(U_1 \cap U_2) \xleftarrow{\sim} \mathcal{F}(U_2) \rightarrow \cdots \rightarrow \mathcal{F}(U_{n-1} \cap U_n) \xleftarrow{\sim} \mathcal{F}(U_n) \xrightarrow{\sim} \mathcal{F}_y.$$

□

Proposition 1.2. *If γ is homotopic to $\tilde{\gamma}$ then $t_\gamma = t_{\tilde{\gamma}}$.*

Proof. Can contain both paths in a compact contractible set, then run a similar proof to above.

□

Definition 7. The *fundamental groupoid* of X , denoted $\Pi_1(X)$, is a category with

- Objects: the points of X ,
- Morphisms: {paths from x to y }/homotopy.

Observe that this really is a groupoid (not difficult).

Theorem 1.3. *There is an equivalence of categories*

$$\begin{aligned} \{\text{Locally constant sheaves on } X\} &\xrightarrow{\sim} \{\text{Functors } \Pi_1(X) \rightarrow \text{Vect}^{fd}\} \\ \mathcal{F} &\longmapsto \left\{ \begin{array}{ll} x & \mapsto \mathcal{F}_x \\ t_\gamma : \mathcal{F}_x & \rightarrow \mathcal{F}_y \end{array} \right\} \end{aligned}$$

This gives us another perspective on local systems. In particular, they are a homotopic invariant, not a homeomorphism invariant.

1.1.1. *Another perspective: Where do local systems come from?* If X is a smooth manifold and $\pi : E \rightarrow X$ is a smooth vector bundle, we can functorially produce the *sheaf of sections* \mathcal{E} ,

$$\mathcal{E}(U) = \Gamma(U; E) \ni (s : U \rightarrow E : \pi \circ s = \text{id}).$$

How can we make sense of local constancy? **Connections.** Write $\Gamma(E) = \Gamma(X; E) = \mathcal{E}(X)$ for *global* sections, and let $\nabla : \Gamma(E) \rightarrow \Omega^1(E)$ be a connection.

Remark Can properly think of this as a map of sheaves $\mathcal{E} \rightarrow \Omega^1(\mathcal{E})$ – we get away with conflating bundles with sheaves because our sheaves have nice properties (in particular we have partitions of unity at our disposal).

What is the candidate for local constancy? *Horizontal sections*:

$$\ker(\nabla) = \{s \in \Gamma(E) \mid \nabla s = 0\}.$$

When does this behave nicely? This goes back to Frobenius: for concreteness let's work locally with local coordinates x_1, \dots, x_n on X and s_1, \dots, s_r a basis of (local) sections of E . Then

$$\nabla_{\frac{\partial}{\partial x_i}}(s_j) = \sum_k a_{ijk} s_k,$$

where a_{ijk} is the connection matrix. Write $s = \sum f_j s_j$. Then

$$\nabla s = 0 \iff \left\{ \frac{\partial f_j}{\partial x_i} + \sum_k a_{ijk} f_k = 0 \right\} \text{ system of PDEs.}$$

What then does it mean to have a locally constant sheaf? Morally: “Given an initial condition at a point, there is a unique solution to this system of PDEs on some contractible neighbourhood.” Let's phrase this in a more precise and familiar way. Write $\nabla_i := \nabla_{\frac{\partial}{\partial x_i}}$.

Theorem 1.4 (Frobenius Theorem). *If $\nabla_i \nabla_j = \nabla_j \nabla_i$ for all i, j , then the sheaf $\ker(\nabla)$ is locally constant. We then say that the connection is flat, or integrable.*

Remark Globally this is phrased as $\nabla_X \nabla_Y - \nabla_Y \nabla_X = \nabla_{[X, Y]}$ where X, Y are vector fields.

Thus we can expand on the previous theorem.

Theorem 1.5. *There is an equivalence of categories*

$$\{\text{Locally constant sheaves on } X\} \xleftarrow{\sim} \{\text{Functors } \Pi_1(X) \rightarrow \text{Vect}^{fd}\} \xleftarrow{\sim} \{\text{Integrable/flat connections on } X\}$$

2. SHEAVES.

Fix X a topological space. Recall that a presheaf on X is a functor $\text{Op}(X)^{\text{op}} \rightarrow \text{Vect}$; or more generally we could take

$$\mathcal{F} : \text{Op}(X)^{\text{op}} \rightarrow \begin{cases} \text{Set} \\ \text{Ab} \\ \text{Rings} \\ \text{etc.} \end{cases}$$

\mathcal{F} is a *sheaf* if “sections can be defined locally”.

Example 5. Given $\pi : Y \rightarrow X$ a continuous map of spaces, *sections of Y over X* , $\mathcal{S}_{Y/X}$ is a presheaf defined by

$$\mathcal{S}_{Y/X}(U) = \{s : U \rightarrow Y \mid \pi s(x) = x\}.$$

This is a presheaf of *sets*.

Claim: $\mathcal{S}_{Y/X}$ is a sheaf.

Proof. Suppose $\{U_i\}$ is an open cover of $U \subset X$, U open.

- (1) If $s, s' \in \mathcal{S}_{Y/X}(U)$ such that $s|_{U_i} = s'|_{U_i}$ for all i , then it is clear that $s = s'$ (functions are defined pointwise).
- (2) If $s_i \in \mathcal{S}_{Y/X}(U_i)$ such that $s_i|_{U_i \cap U_j} = s_j|_{U_i \cap U_j}$ for all i, j , we can define

$$s \in \mathcal{S}_{Y/X}(U) \quad \text{by} \quad s(x) = s_i(x) \text{ if } x \in U_i.$$

□

This example is very important – it gives us a huge variety of examples, and in some sense it gives us *all* sheaves (we will make this precise soon).

Example 6. If $Y = X \times Z \xrightarrow{\pi_1} X$,

$$\mathcal{S}_{X \times Z/X}(U) = C(U, Z) = \{\text{cts. functions } U \rightarrow Z\}.$$

Example 7. If $Z = \mathbb{C}$ with the Euclidean topology, $\mathcal{S}_{X \times \mathbb{C}/X} = C_X$, continuous complex valued functions on X . Observe that we can consider this as a sheaf of sets, vector spaces, rings, etc.

Example 8. If $Z = \mathbb{C}^{\text{disc}}$, \mathbb{C} with the discrete topology, then

$$\mathcal{S}_{X \times \mathbb{C}^{\text{disc}}/X} = \mathbb{C}_X,$$

locally constant functions on X (constant sheaf).

Example 9. If $E \xrightarrow{\pi} X$ is a complex vector bundle, i.e. there is an open cover $\{U_i\}$ of X such that

$$E|_{U_i} = \pi^{-1}(U_i) \cong U_i \times \mathbb{C}^r,$$

commuting with projection

$$\begin{array}{ccc} \pi^{-1}(U_i) & \xleftarrow{\cong} & U_i \times \mathbb{C}^r \\ & \searrow & \swarrow \\ & U_i & \end{array}$$

such that

$$\pi^{-1}(x) = E_x \xrightarrow{\sim} \{x\} \times \mathbb{C}^r.$$

Then $\mathcal{S}_{E/X} = \mathcal{E}$ is a sheaf of vector spaces – but in fact it is even more than that:

$$\underline{\mathcal{E} \text{ is a sheaf of modules for the sheaf of rings } C_X}.$$

Definition 8. A *bundle of groups with fibre/structure group* G is a map $E \rightarrow X$ of spaces such that there is an open cover U_i such that $E|_{U_i} \cong U_i \times G$.

Example 10. What is a bundle of sets? A set is a discrete topological space, so a bundle of sets is a covering space.

Example 11. A bundle of topological spaces is a fibre bundle.

Example 12. This is slightly subtle: a bundle of discrete vector spaces is **not** a vector bundle! Sections here are somehow ‘locally constant’. This will give us another way to think about local systems.

Claim: If $Y \rightarrow X$ is a covering space, then $\mathcal{S}_{Y/X}$ is a locally constant sheaf of sets. I.e., locally it looks like the sheaf of locally constant functions.

We would like a converse to this: given a locally constant sheaf, produce a covering space. We will actually consider a more general construction.

2.1. **Étalé spaces.** Given a sheaf \mathcal{F} on X , define the *étalé space* $\acute{\text{E}}t(\mathcal{F})$ as follows:

- As a set, it is the collection of germs of sections of \mathcal{F} ,

$$\acute{\text{E}}t(\mathcal{F}) = \coprod_{x \in X} \mathcal{F}_x.$$

- Topology: If $U \subset X$ is open, $s \in \mathcal{F}(U)$, we have $s_x \in \mathcal{F}_x$ for all $x \in U$. Then declare the sets $\{s_x | x \in U\} \subset \acute{\text{E}}t(\mathcal{F})$ to be open, and $\{s_x | x \in U\} \leftrightarrow U$ a homeomorphism.

We have a map $\acute{\text{E}}\text{t}(\mathcal{F}) \xrightarrow{\pi} X$ with $\mathcal{F}_x = \pi^{-1}(x)$. In fact, π is a local homeomorphism. I.e. if $s_x \in \acute{\text{E}}\text{t}(\mathcal{F})$ then there exists $U \ni s_x$ open in $\acute{\text{E}}\text{t}(\mathcal{F})$ such that $\pi|_U$ is a homeomorphism onto its image.

Claim: $\mathcal{S}_{\acute{\text{E}}\text{t}(\mathcal{F})/X} \cong \mathcal{F}$.

For each $x \in X$, need to give an element of \mathcal{F}_x (to define a section $\acute{\text{E}}\text{t}(\mathcal{F}) \rightarrow X$). Then we want to show that given the defined topology, the stalks glue to a legitimate section of \mathcal{F} .

A little clearer: check that the assignment

$$\begin{aligned} \mathcal{F} &\rightarrow \mathcal{S}_{\acute{\text{E}}\text{t}(\mathcal{F})/X} \\ s \in \mathcal{F}(U) &\mapsto \{x \mapsto s_x\} \end{aligned}$$

is continuous. So: this gives an equivalence of categories

$$\begin{aligned} \{\text{Local homeomorphisms over } X\} &\xleftarrow{\sim} \{\text{Sheaves of sets on } X\} \\ \acute{\text{E}}\text{t}(\mathcal{F}) &\longleftrightarrow \mathcal{F} \end{aligned}$$

Inside of this, we have the equivalence

$$\begin{aligned} \{\text{Local homeomorphisms over } X\} &\longleftrightarrow \{\text{Sheaves of sets on } X\} \\ \cup & & \cup \\ \{\text{Covering spaces}\} &\longleftrightarrow \{\text{Locally constant sheaves}\} \end{aligned}$$

Remark If \mathcal{F} is a presheaf, $\acute{\text{E}}\text{t}(\mathcal{F}) \rightarrow X$ is still a local homeomorphism, so we can still take its sheaf of sections

$$\mathcal{F}^{\text{sh}} = \mathcal{F}^+ = \text{sh}(\mathcal{F}) := \mathcal{S}_{\acute{\text{E}}\text{t}(\mathcal{F})/X}$$

which we call the *sheafification* of \mathcal{F} . Sheafification is left adjoint to the inclusion functor $i: \text{Sheaves}(X) \rightarrow \text{Presheaves}(X)$,

$$\text{Hom}_{\text{Presheaves}(X)}(\mathcal{F}, i(\mathcal{G})) \cong \text{Hom}_{\text{Sheaves}(X)}(\mathcal{F}^{\text{sh}}, \mathcal{G}).$$

2.2. Functors on sheaves. Given $f: X \rightarrow Y$, what can we do with sheaves? We would like to be able to push them forward and pull them back:

$$\begin{array}{ccc} & f_* & \\ \text{Sh}(X) & \xrightarrow{\quad} & \text{Sh}(Y) \\ & f^* & \end{array}$$

Given a sheaf \mathcal{F} on X , define

$$f_*(\mathcal{F})(U) = \mathcal{F}(f \in (U))$$

where $U \subset Y$ is open. If \mathcal{G} is a sheaf on Y , define

$$(f^*\mathcal{G})^{\text{pre}}(V) = \frac{\text{colim}}{U \subset f(V)} \mathcal{G}(U),$$

where V runs over the open sets containing U , and define

$$f^*\mathcal{G} = \text{sh}(f^*\mathcal{G}^{\text{pre}}).$$

In terms of local homeomorphisms (étalé spaces), the pullback sheaf/inverse image sheaf should be the sections of the pullback

$$\begin{array}{ccc} X \times_Y E & \longrightarrow & E \\ \downarrow & & \downarrow \\ X & \longrightarrow & Y \end{array}$$

Example 13. Let $f: X \rightarrow \text{pt}$, \mathcal{F} a sheaf on X . Then $f_*(\mathcal{F}) = \Gamma(\mathcal{F}) = \mathcal{F}(X)$.

So f_* is a generalization of global sections. Think of f_* as being sections along the fibres (at least when f looks like a fibration).

If A is a set (i.e. a sheaf on a point), then

$$f^*(A) = A_X, \quad \text{the constant sheaf.}$$

Example 14. Let $i : \{x\} \hookrightarrow X$. Then $i^*\mathcal{F} = \mathcal{F}_x$.

So we can think of pullback as a generalization of the stalk, at least when we are looking at inclusion of a subspace.

Definition 9. If A is a set, i_*A is called the *skyscraper sheaf* at x .

2.3. Homological properties of sheaves. From now on we will turn away from sheaves of sets. Today, $\text{Sh}(X)$ means sheaves of *abelian groups* on X . We are interested in the following fact:

“ $\text{Sh}(X)$ is an abelian category.”

Definition 10. A category \mathcal{C} is *abelian* if

- (1) it contains a zero object (initial and terminal),
- (2) it contains all binary products and coproducts,
- (3) it contains all kernels and cokernels,
- (4) every monomorphism is a kernel and every epimorphism is a cokernel.

Example 15. The category of all groups is a non-example – if $H \subset G$ is non-normal then G/H is not a group.

Properties: In an abelian category,

- $\text{Hom}_{\mathcal{C}}(A, B)$ is an abelian group.
- Finite products = finite coproducts.
- The *first isomorphism theorem* holds:

$$\begin{array}{ccccccc} \ker(f) & \hookrightarrow & A & \xrightarrow{f} & B & \twoheadrightarrow & \text{coker}(f) \\ & & \downarrow & & \uparrow & & \\ & & \text{coim}(f) & \xrightarrow{\sim} & \text{im}(f) & & \end{array}$$

Example 16. For a ring R , R -modules form an abelian category.

Definition 11. In an abelian category \mathcal{C} ,

$$A \xrightarrow{f} B \xrightarrow{g} C$$

is called *exact* if $\text{im}(f) = \ker(g)$.

Observe that this implies that $g \circ f = 0$.

Definition 12. A *short exact sequence* (SES) is an exact sequence of the form

$$0 \rightarrow A \rightarrow B \rightarrow C \rightarrow 0.$$

Example 17. $0 \rightarrow A \rightarrow A \oplus C \rightarrow C \rightarrow 0$; such a SES is called *split*.

Proposition 2.1 (Splitting lemma). A SES $0 \rightarrow A \xrightarrow{f} B \xrightarrow{g} C \rightarrow 0$ is split iff either

- (1) there exists some $s : B \rightarrow A$ such that $s \circ f = \text{id}_A$; or,
- (2) there exists some $t : C \rightarrow B$ such that $g \circ t = \text{id}_C$.

Warning! This is a property of *abelian* categories. A t -splitting in the category of all groups would only tell us that B is a *semi-direct* product.

Definition 13. A *complex* in \mathcal{C} is a sequence of objects and morphisms

$$\dots \rightarrow A^{i-1} \xrightarrow{d_{i-1}} A^i \xrightarrow{d_i} A^{i+1} \rightarrow \dots = A^\bullet$$

such that $d_i \circ d_{i-1} = 0$ for any i . We often write $d^2 = 0$. Then the *cohomology* of this complex is

$$H^i(A^\bullet) = \frac{\ker(d_i)}{\operatorname{im}(d_{i-1})}.$$

Definition 14. A *morphism* of complexes $A^\bullet \rightarrow B^\bullet$ is a commutative diagram

$$\begin{array}{ccccccc} \dots & \longrightarrow & A^i & \longrightarrow & A^{i+1} & \longrightarrow & \dots \\ & & \downarrow & & \downarrow & & \\ \dots & \longrightarrow & B^i & \longrightarrow & B^{i+1} & \longrightarrow & \dots \end{array}$$

A morphism $A^\bullet \rightarrow B^\bullet$ is a *quasi-isomorphism* if it induces an isomorphism of cohomology $H^i(A^\bullet) \xrightarrow{\sim} H^i(B^\bullet)$.

If \mathcal{C} and \mathcal{D} are abelian categories and $F : \mathcal{C} \rightarrow \mathcal{D}$ is a functor, we say

- F is *additive* if it preserves finite coproducts.
- F is *left exact* if it is additive and preserves kernels.
- F is *right exact* if it is additive and preserves cokernels.

If $0 \rightarrow A \rightarrow B \rightarrow C \rightarrow 0$ is a SES in \mathcal{C} , then

- If F is left exact, $0 \rightarrow F(A) \rightarrow F(B) \rightarrow F(C)$ is exact.
- If F is right exact, $F(A) \rightarrow F(B) \rightarrow F(C) \rightarrow 0$ is exact.

In abelian groups, we have the functors (for fixed $A \in \text{Ab}$)

$$\begin{array}{ll} \operatorname{Hom}(A, -) : \text{Ab} \rightarrow \text{Ab} & \text{(left exact)} \\ A \otimes_{\mathbb{Z}} (-) : \text{Ab} \rightarrow \text{Ab} & \text{(right exact)} \end{array}$$

Example 18. Let $A = \mathbb{Z}/2$ and take the SES $0 \rightarrow \mathbb{Z} \xrightarrow{\times 2} \mathbb{Z} \rightarrow \mathbb{Z}/2 \rightarrow 0$.

- Apply $\operatorname{Hom}(A, -)$: $0 \rightarrow 0 \rightarrow 0 \rightarrow \mathbb{Z}/2$.
- Apply $A \otimes_{\mathbb{Z}} (-)$: $\mathbb{Z}/2 \xrightarrow{0} \mathbb{Z}/2 \rightarrow \mathbb{Z}/2 \rightarrow 0$.

Claim: $\operatorname{Sh}(X)$ is an abelian category.

Sketch of proof. Consider $\mathcal{F}, \mathcal{G} \in \operatorname{Sh}(X)$, $\phi : \mathcal{F} \rightarrow \mathcal{G}$.

$$\ker(\phi)(U) = \ker(\phi_U : \mathcal{F}(U) \rightarrow \mathcal{G}(U)),$$

so $\ker(\phi) \in \operatorname{Sh}(X)$. We can define

$$\operatorname{coker}(\phi) := \operatorname{sh}(\operatorname{coker}(\phi))^{\operatorname{pre}}$$

where

$$\operatorname{coker}(\phi)^{\operatorname{pre}}(U) = \operatorname{coker}(\phi_U) = \mathcal{G}/\phi_U(\mathcal{F}(U)).$$

□

Example 19 (Cokernel presheaf is not a sheaf.). Let $X = \mathbb{R}$, $\mathcal{F} = \mathbb{Z}_{\mathbb{R}}$, $\mathcal{G} = \mathbb{Z}_x \oplus \mathbb{Z}_y$, $x \neq y$ in \mathbb{R} . How can we define a map $\phi : \mathbb{Z}_{\mathbb{R}} \rightarrow \mathbb{Z}_x \oplus \mathbb{Z}_y$? Such a map is equivalent to a global section $s \in \Gamma(\mathbb{Z}_x \oplus \mathbb{Z}_y) \cong \mathbb{Z} \oplus \mathbb{Z}$. Choose $(1, 1) \in \mathbb{Z} \oplus \mathbb{Z}$. What is the cokernel of this map?

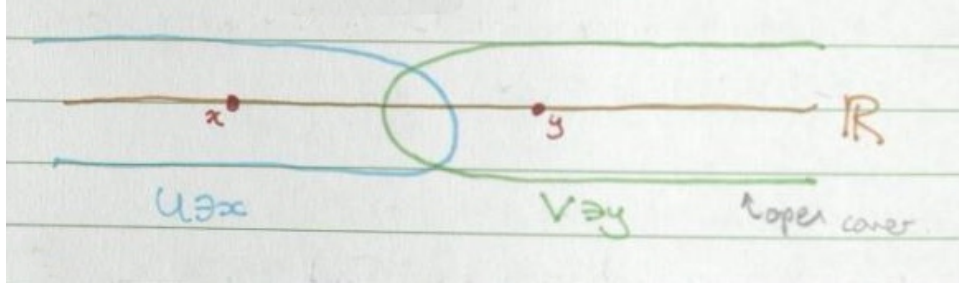


FIGURE 3. Cover of \mathbb{R} by two open sets U and V .

Then

$$\begin{aligned} \phi_U : \mathbb{Z} &\xrightarrow{\sim} (\mathbb{Z}_x \oplus \mathbb{Z}_y)(U) = \mathbb{Z}, \\ \phi_V : \mathbb{Z} &\xrightarrow{\sim} \mathbb{Z}. \end{aligned}$$

So

$$\text{coker}(\phi)^{\text{pre}}(U) = 0 \quad \text{and} \quad \text{coker}(\phi)^{\text{pre}}(V) = 0.$$

But!

$$\text{coker}(\phi)^{\text{pre}}(\mathbb{R}) = \text{coker}(\mathbb{Z} \xrightarrow{(1,1)} \mathbb{Z} \oplus \mathbb{Z}) \cong \mathbb{Z}.$$

Recall that sheafification is global sections of the étalé space $\text{Ét}(\mathcal{F}) = \coprod \mathcal{F}_z$. From the above, $\mathcal{F}_z = 0$ for all $z \in \mathbb{R}$. Thus,

$$\text{coker}(\phi) = 0.$$

Example 20. Let $X = \mathbb{R}_t$, $\mathcal{F} = \mathcal{G} = \mathcal{C}_{\mathbb{R}}^{\infty}$ (complex valued smooth functions). We have a map

$$\frac{d}{dt} : \mathcal{C}_{\mathbb{R}}^{\infty} \rightarrow \mathcal{C}_{\mathbb{R}}^{\infty}, \quad \text{with} \quad \ker\left(\frac{d}{dt}\right) = \mathbb{C}_{\mathbb{R}} \quad (\text{locally constant functions}).$$

What about the cokernel? Let $U \subset \mathbb{R}$ be open, $f \in \mathcal{C}^{\infty}(U)$. Want to construct a function F such that $\frac{d}{dt}F = f$; we can do this (fundamental theorem of calculus), e.g. let $F(t) = \int_{t_0}^t f(x)dx$. So this map of sheaves is surjective.

Example 21. Let $X = S^1 = \mathbb{R}/\mathbb{Z}$, $\frac{d}{dt} : \mathcal{C}_{S^1}^{\infty} \rightarrow \mathcal{C}_{S^1}^{\infty}$. Then $\ker\left(\frac{d}{dt}\right) = \mathbb{C}_{S^1}$ again. Since any open interval $U \subset S^1$ is diffeomorphic to \mathbb{R} , $\frac{d}{dt}|_U : \mathcal{C}_U^{\infty} \rightarrow \mathcal{C}_U^{\infty}$ is surjective. So the cokernel sheaf is $\text{coker}\left(\frac{d}{dt}\right) = 0$.

But: That the constant function $1_{S^1} \in \mathcal{C}_{S^1}^{\infty}$. This is not in the image of $\frac{d}{dt}|_{S^1} : \mathcal{C}^{\infty}(S^1) \rightarrow \mathcal{C}^{\infty}(S^1)$.

Example 22. Phrased differently, we have a SES of sheaves on S^1 ,

$$0 \rightarrow \mathbb{C}_{S^1} \rightarrow \mathcal{C}_{S^1}^{\infty} \xrightarrow{\frac{d}{dt}} \mathcal{C}_{S^1}^{\infty} \rightarrow 0.$$

But if we take global sections Γ ,

$$0 \rightarrow \mathbb{C} \hookrightarrow C^{\infty}(S^1) \xrightarrow{\frac{d}{dt}} C^{\infty}(S^1),$$

i.e. the final map is not surjective. This is a manifestation of the fact the Γ is left exact (but not exact). If we do take the cokernel we have

$$0 \rightarrow \mathbb{C} \hookrightarrow C^{\infty}(S^1) \xrightarrow{\frac{d}{dt}} C^{\infty}(S^1) \rightarrow H_{\text{dR}}^1(S^1) = \mathbb{C}.$$

Proposition 2.2. In general, $\Gamma : \text{Sh}(X) \rightarrow \text{Ab}$ is left exact.

On the other hand, exactness can be checked locally.

Proposition 2.3. A sequence of sheaves $\mathcal{F} \xrightarrow{\phi} \mathcal{G} \xrightarrow{\psi} \mathcal{H}$ is exact if and only if $\mathcal{F}_x \xrightarrow{\phi_x} \mathcal{G}_x \xrightarrow{\psi_x} \mathcal{H}_x$ is exact for all $x \in X$.

If $f : X \rightarrow Y$ is a map of topological spaces, $\mathcal{F} \in \text{Sh}(X)$ and $\mathcal{G} \in \text{Sh}(Y)$, recall we have

$$f_*(\mathcal{F}) \in \text{Sh}(Y) \quad \text{and} \quad f^*(\mathcal{G}) \in \text{Sh}(X).$$

Recall that

$$f^*(\mathcal{G})(U) = \text{sh} \left(U \mapsto \frac{\text{colim}}{V \supset f(U)} \mathcal{G}(V) \right).$$

Proposition 2.4. f^* is left adjoint to f_* .

I.e. $\text{Hom}_{\text{Sh}(X)}(f^*\mathcal{G}, \mathcal{F}) \cong \text{Hom}_{\text{Sh}(Y)}(\mathcal{G}, f_*\mathcal{F})$ is a natural bijection.

Proof. Want to construct natural transformations

$$f^*f_* \xrightarrow{c} \text{id}_{\text{Sh}(X)} \quad \text{and} \quad \text{id}_{\text{Sh}(Y)} \xrightarrow{u} f_*f^*.$$

Why? Given u, c as above,

$$\begin{array}{ccc} \text{Hom}(f^*\mathcal{G}, \mathcal{F}) & \xrightarrow{f_*} & \text{Hom}(f_*f^*\mathcal{G}, f_*\mathcal{F}) \\ & \searrow & \downarrow \\ & & \text{Hom}(\mathcal{G}, f_*\mathcal{F}) \end{array}$$

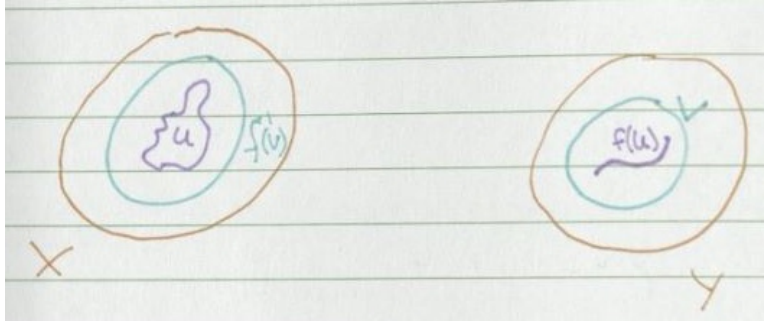


FIGURE 4. Since the map f may not be open, a colimit is required.

Now,

$$(f^*)^{\text{pre}} f_*(\mathcal{F})(U) = \frac{\text{colim}}{V \supset f(U)} \mathcal{F}(f^{-1}(V)),$$

and we have restrictions $\mathcal{F}(f^{-1}(V)) \rightarrow \mathcal{F}(U)$ for each such V , and thus a map from the colimit. This defines a map $(f^*)^{\text{pre}} f_* \rightarrow \text{id}_{\text{Sh}(X)}$; then we use the universal property of sheafification to obtain the counit $f^*f_* \rightarrow \text{id}_{\text{Sh}(X)}$. \square

2.4. Simplicial homology. Simplices:

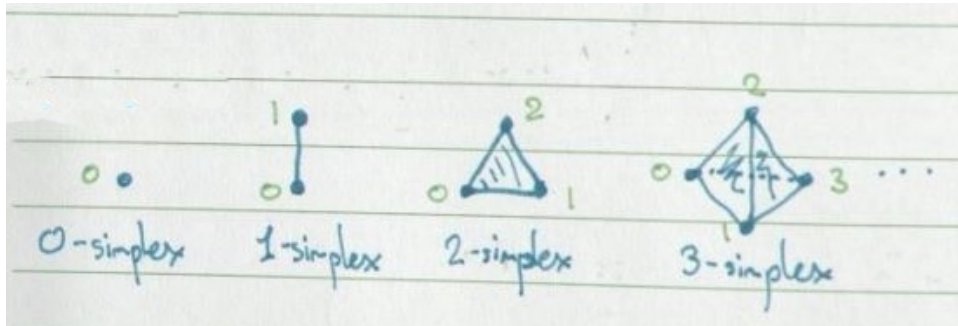


FIGURE 5. Low dimensional simplices.

So,

$$n\text{-simplex} \leftrightarrow (0 \rightarrow 1 \rightarrow \dots \rightarrow n) = [n].$$

The *faces* of an n -simplex are the ordered subsets $S \subset \{0, \dots, n\}$.

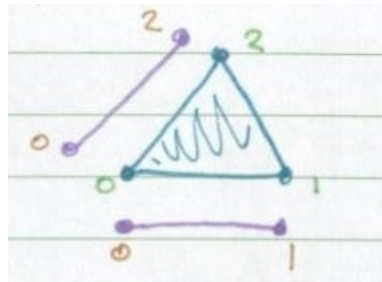


FIGURE 6. Faces of a 2-simplex.

Define the *simplex category* Δ :

Objects: $[0], [1], [2], \dots$

Morphisms: order preserving maps $[n] \rightarrow [m]$.

Definition 15. A *simplicial set* is a functor $X : \Delta^{\text{op}} \rightarrow \text{Set}$ (i.e. a presheaf on Δ).

So we have the category sSet , and there is an embedding

$$\begin{aligned} \Delta &\xrightarrow{\text{Yoneda}} \text{sSet} \\ [n] &\longmapsto \text{Hom}(-, [n]) =: [n] \end{aligned}$$

The fully faithful category given by this is the one with all simplices and all colimits of such (things glued together from simplices).

A simplicial set gives a recipe for building a simplicial topological space.

$$\begin{aligned} \text{sSet} &\xrightarrow{|\cdot|} \text{Top} \\ [n] &\longmapsto \Delta^n \end{aligned}$$

where $|\cdot|$ is *geometric realization* and we extend this definition to all sSet preserving colimits. If $X : \Delta^{\text{op}} \rightarrow \text{Set}$ is a simplicial set we write

$$X([n]) = X_n$$

for the *set of n -simplices*, and if we have a map $f : [n] \rightarrow [m]$ in Δ this induces $X(f) : X_m \rightarrow X_n$ and $f_{\Delta} : \Delta^m \rightarrow \Delta^n$ in Set . So now take concretely

$$|X| = \coprod_n (X_n \times \Delta^n) / \sim$$

where

$$(\sigma, f_{\Delta}(t)) \sim (X(f)(\sigma), t) \quad \text{for } \sigma \in X_n, t \in \Delta^n.$$

Consider the following diagram in Δ :

$$[0] \begin{array}{c} \xrightarrow{d^0} \\ \xleftarrow{s^0} \\ \xrightarrow{d^1} \end{array} [1] \begin{array}{c} \xrightarrow{\quad} \\ \xleftarrow{\quad} \\ \xrightarrow{\quad} \end{array} [2] \begin{array}{c} \xrightarrow{\quad} \\ \xleftarrow{\quad} \\ \xrightarrow{\quad} \end{array} [3] \dots$$

The arrows in this diagram give all possible order preserving maps between adjacent simplices. The maps shown are distinguished maps which we call *coface* (d^i) and *codegeneracy* (s^i) maps. If X is a sSet we have a diagram with *face* and *degeneracy* maps

$$X_0 \begin{matrix} \xleftarrow{\quad} \\ \xrightarrow{\quad} \\ \xleftrightarrow{\quad} \end{matrix} X_1 \begin{matrix} \xleftarrow{\quad} \\ \xrightarrow{\quad} \\ \xleftrightarrow{\quad} \end{matrix} X_2 \cdots$$

A simplex in X_n is called *degenerate* if it is in the image of a degeneracy map. Think:

“Degenerate simplices are secretly lower-dimensional simplices.”

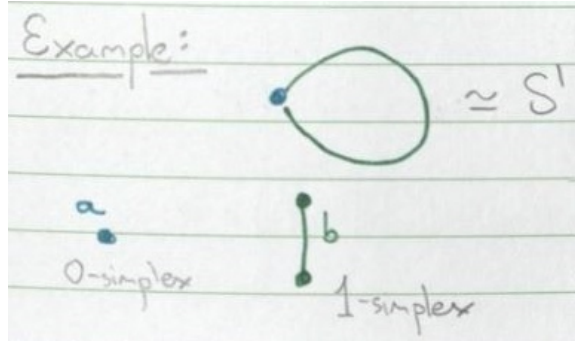


FIGURE 7. Simplicial description of S^1 for example 23.

Example 23. How to prescribe the complex from Figure 7? As a *semi-simplicial set* (use only face maps),

$$X_0 = \{a\} \xleftarrow{\quad} \{b\} = X_1,$$

so that we send both faces to the point a . As a simplicial set we would need to keep track of the degeneracies, e.g. $X_1 = \{b, s_0(a)\}$.

If Y is a topological space, we can produce a simplicial set $S(Y)$ by talking

$$S(Y)_n = \text{Hom}_{\text{Top}}(\Delta^n, Y),$$

the *singular simplicial set*. This is a sSet, since

$$f : [m] \rightarrow [n] \text{ induces } f_{\Delta} : \Delta^m \rightarrow \Delta^n \text{ induces } S(Y)_n \rightarrow S(Y)_m.$$

Theorem 2.5. *If Y is a CW-complex, then $|S(Y)| \simeq Y$ (homotopy equivalence).*

We can also talk about *simplicial abelian groups*,

$$\Delta^{\text{op}} \rightarrow \text{Ab},$$

and more generally *simplicial objects in a category \mathcal{C}* are $\Delta^{\text{op}} \rightarrow \mathcal{C}$.

Example 24. If X is a simplicial set we can define a “free” simplicial abelian group $\mathbb{Z}X$ by

$$(\mathbb{Z}X)_n = \mathbb{Z} \cdot X_n.$$

Given a simplicial abelian group A we can make a chain complex $C(A)_{\bullet}$:

$$C(A)_n = A_n, \quad \delta_n : \begin{matrix} A_n & \rightarrow & A_{n-1} \\ a & \mapsto & \sum_i (-1)^i d_i(a) \end{matrix},$$

and one can prove that $\delta_{n-1}\delta_n = 0$ (left as an exercise).

Remark This construction did **not** use the degeneracy maps – so this makes sense for semi-simplicial sets.

We have a subcomplex (check!) of *degenerate simplices* $D(A) \subset C(A)$.

Proposition 2.6. $D(A)$ is chain homotopic to 0.

In fact,

$$C(A) = D(A) \oplus N(A)$$

where $N(A)$ is the *normalised chain complex* and $N(A) \sim C(A)$ (chain homotopic).

If X is a simplicial set we can define

$$C_\bullet(X; \mathbb{Z}) = C(\mathbb{Z}X),$$

and the singular homology is

$$H_i(X; \mathbb{Z}) = H_i(C(\mathbb{Z}X)).$$

If Y is a topological space then $S(Y)$ produces

$$C_i^{\text{sing}}(Y; \mathbb{Z}) \quad (\text{singular chains on } Y), \quad \text{and} \quad H_i^{\text{sing}}(Y; \mathbb{Z}) \quad (\text{singular homology}).$$

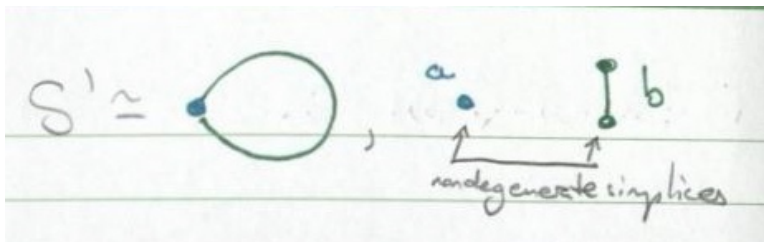


FIGURE 8. Nondegenerate simplices of S^1 .

Example 25. Claim that

$$\begin{array}{l} N(S^1; \mathbb{Z}) = \quad \mathbb{Z}a \xleftarrow{0} \mathbb{Z}b \\ \text{degree:} \quad \quad \quad 0 \quad \quad 1 \end{array}$$

Of course,

$$D(\mathbb{Z}S^1) = \mathbb{Z}a \leftarrow \mathbb{Z}b \oplus \mathbb{Z}s_0(a) \leftarrow \dots$$

plus higher degenerate simplices which make no contribution to homology.

We can also define more generally $H_i(X; A)$ for A an abelian group.

2.4.1. *Homology with coefficients in a local system.* Suppose \mathcal{E} is a local system on $|X|$ (i.e. \mathcal{E} is a locally constant sheaf of abelian groups). Want to define $H_i(X; \mathcal{E})$. Take (provisionally)

$$C_n(X; \mathcal{E}) = \{(x, s) \mid x \in X_n, s \in \Gamma(x^* \mathcal{E})\}.$$

What does this mean? $x \in X_n$, so think of this as $x : \Delta^n \rightarrow |X|$. But we can't add simplices, so we actually want our n -chains to be:

$$C_n(X; \mathcal{E}) = \langle (x, s) \mid x \in X_n, s \in \Gamma(x^* \mathcal{E}) \rangle$$

(i.e. the abelian group generated by the terms in the angle brackets.) Now, the n -simplex is contractible, thus $x^* \mathcal{E}$ is trivializable (so we can take sections):

$$\begin{array}{ccc} x^* \mathcal{E} & & \mathcal{E} \\ s \uparrow \downarrow & & \downarrow \\ \Delta^n & \xrightarrow{x} & |X| \end{array}$$

Now stalkwise, $A = \mathcal{E}_y$ (for some $y \in |X|$), and so on Δ^n , $\Gamma(x^* \mathcal{E}) = A$.

If we took the trivial local system, we would see that we recover our previous notion of singular homology.

We define face maps $d_i : C_n(X; \mathcal{E}) \rightarrow C_{n-1}(X; \mathcal{E})$ as before by restricting sections to faces.

Example 26. See Figure 9.

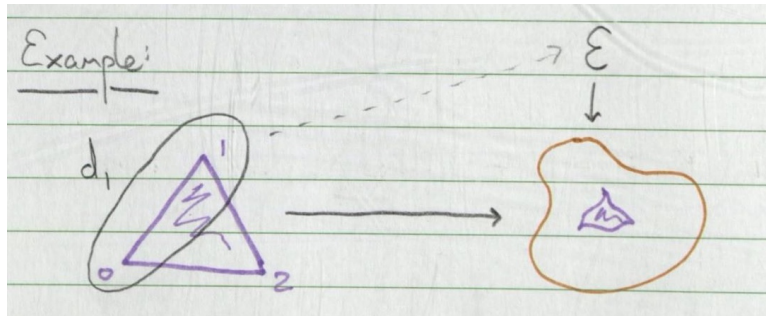


FIGURE 9. Visual representation of the “simplices” in local cohomology.

Then

$$\partial := \sum (-1)^i d_i : C_n(X; \mathcal{E}) \rightarrow C_{n-1}(X; \mathcal{E}).$$

Example 27. $X = S^1$, so $\pi_1(S^1) = \mathbb{Z}$. Then

$$\text{Local system on } S^1 \iff \text{Rep of } \pi_1(S^1) \iff (A, t \in \text{Aut}(A))$$

where A is the stalk of \mathcal{E} at some chosen basepoint.

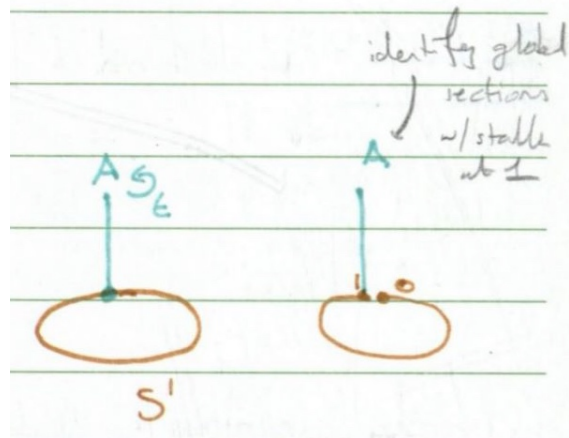


FIGURE 10. A local system on S^1 .

What is our complex?

$$A \xleftarrow{\text{id}-t} A \quad \text{which we can see graphically via:} \quad \begin{array}{ccc} & & \bullet 1 \\ & \text{id} & / \\ 0 \bullet & \leftarrow & \\ & \text{apply monodromy } t & \backslash \\ & & \bullet 0 \end{array}$$

degree: 0 1

Example 28. If $\mathcal{E} = \mathbb{Z}_{S^1}$, then we have $\mathbb{Z} \xleftarrow{0} \mathbb{Z}$.

Example 29. If $A = \mathbb{C}$, $t = \lambda \in \mathbb{C}^\times$, then we have

$$\mathbb{C} \xleftarrow{\text{id}-\lambda} \mathbb{C}.$$

So if $\lambda \neq 1$, $\text{id} - \lambda : \mathbb{C} \cong \mathbb{C}$, so $H_0 = 1, H_1 = 0$, etc...

2.4.2. *Cohomology with coefficients in a local system.* Above, we have defined for a sSet/topological space X and local system \mathcal{E}

$$(\Delta^i \rightarrow X) \in C_i(X; \mathcal{E}) \xrightarrow{H_*} H_i(X; \mathcal{E})$$

We can give this a slightly more down to earth description: an i -simplex with coefficients in \mathcal{E} is an i -simplex with a lift

$$\begin{array}{ccc} & \text{Ét}(\mathcal{E}) & \\ & \nearrow & \downarrow \\ \Delta^i & \longrightarrow & X \end{array}$$

and the differential is induced by the face inclusions $\Delta^{i-1} \hookrightarrow \Delta^i$. We can also define *cohomology with coefficients in a local system*, $H^i(X; \mathcal{E})$, by taking the cochains to be

$$C^i(X; \mathcal{E}) := \left\{ \phi \mid \phi \text{ assigns to each simplex a lift, } \begin{array}{ccc} & \text{Ét}(\mathcal{E}) & \\ & \nearrow \phi(\sigma) & \downarrow \\ \Delta^i & \xrightarrow{\sigma} & X \end{array} \right\},$$

and defining the differential $d : C^i \rightarrow C^{i+1}$ to be the alternating sum of coface maps $d^r : C^i \rightarrow C^{i+1}$, where

$$d^r(\phi)(\sigma^{i+1}) = \phi(d_r(\sigma^{i+1})).$$

3. SHEAF COHOMOLOGY AS A DERIVED FUNCTOR.

3.1. **Idea and motivation. Where are we going?** Our next goal is to prove *Poincaré Duality*: If M is a closed n -manifold, then

$$H_i(M; \mathbb{Z}_M) \cong H^{n-i}(M; \mathcal{O}r_M),$$

where $\mathcal{O}r_M$ is the orientation local system.

Remark If M is orientable, $\mathcal{O}r_M$ is the constant sheaf.

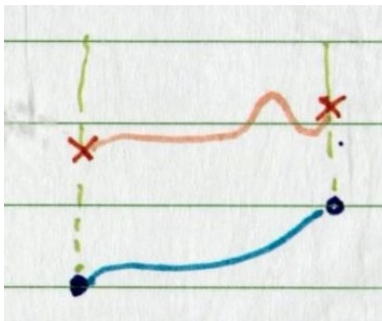
Example 30. If $M = S^1$,

$$\begin{array}{c} H_0, H_1 = \mathbb{Z} \\ \updownarrow \text{Poincaré Duality} \\ H^1, H^0 = \mathbb{Z} \end{array}$$

We will actually recover Poincaré duality as a special case of *Verdier duality*. So, in order to continue, we need to define sheaf cohomology.

Motivating sheaf cohomology. If \mathcal{E} is a local system, what is $H^0(X; \mathcal{E})$? A 0-cochain assigns to each 0-simplex $x \in X$ an element of the stalk at x . I.e. this is a *discontinuous* section of $\text{Ét}(\mathcal{E})$.

What does it mean to be closed? If I have two points and a path between them, the elements of the stalk have to be compatible. I.e. we must have a *continuous* function:

FIGURE 11. H^0 gives continuous sections.

I.e. $H^0(X; \mathcal{L}) = \Gamma(\mathcal{L})$.

In general, given a sheaf \mathcal{F} we want to define functors $H^i(X; \mathcal{F})$ such that $H^0(X; \mathcal{F}) = \Gamma(\mathcal{F})$.

Idea: These functors should measure the *non-exactness* of Γ .

Given a SES of sheaves $0 \rightarrow \mathcal{F}' \rightarrow \mathcal{F} \rightarrow \mathcal{F}'' \rightarrow 0$, taking Γ gives

$$0 \rightarrow \Gamma(\mathcal{F}') \rightarrow \Gamma(\mathcal{F}) \rightarrow \Gamma(\mathcal{F}'') \rightarrow ?$$

In order to measure the failure of exactness, we will define a next term in this sequence called $H^1(\mathcal{F}')$ – it turns out that this will only depend on $H^1(\mathcal{F}')$.

Definition 16. A sheaf \mathcal{F} is called *flabby* (or *flasque*) if for each $V \subseteq U \subseteq X$ of open sets, $\mathcal{F}(U) \rightarrow \mathcal{F}(V)$ is surjective.

Proposition 3.1. Suppose $0 \rightarrow \mathcal{F}' \xrightarrow{f} \mathcal{F} \xrightarrow{g} \mathcal{F}'' \rightarrow 0$ is a SES, and \mathcal{F}' is flabby. Then

$$0 \rightarrow \Gamma(\mathcal{F}') \rightarrow \Gamma(\mathcal{F}) \rightarrow \Gamma(\mathcal{F}'') \rightarrow 0$$

is exact.

Proof. Let $s'' \in \Gamma(\mathcal{F}'') = \mathcal{F}''(X)$. Let's define a set

$$\mathcal{S} := \{(U, s) \mid s \in \mathcal{F}(U) \text{ such that } g(s) = s''|_U\}.$$

We want to show that there is an element of this set with $U = X$. \mathcal{S} has a partial order

$$(U_1, s_1) \leq (U_2, s_2) \text{ if } U_1 \subseteq U_2 \text{ and } s_2|_{U_1} = s_1.$$

Zorn's lemma implies that there is a maximal (U, s) in \mathcal{S} .

Suppose that $x \in X - U$. We can find $V \ni x$ open in X , and $t \in \mathcal{F}(V)$ such that $g(t) = s''|_V$.

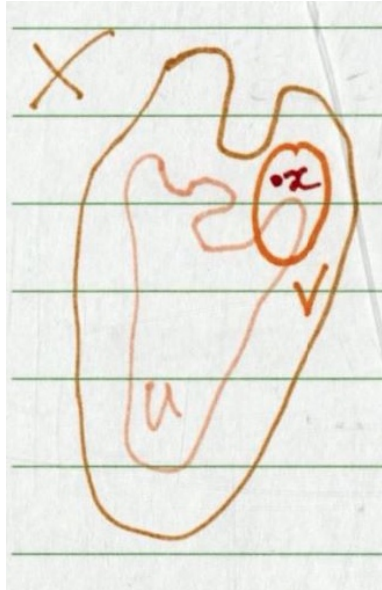


FIGURE 12. Proving that the maximal element is X .

On $U \cap V$, $q := s|_{U \cap V} - t|_{U \cap V} \in \mathcal{F}(U \cap V)$ has the property that $g(q) = 0$. By left exactness, $g(q) = 0$ implies that there exists $w \in \mathcal{F}'(U \cap V)$ such that $f(w) = q$.

Now, since \mathcal{F} is flabby, there exists $r \in \mathcal{F}'(X)$ such that $r|_{U \cap V} = w$. Let $t' = t + f(r)|_V \in \mathcal{F}(V)$. Note that

$$g(t') = s''|_V = g(t)$$

by exactness of $0 \rightarrow \mathcal{F}' \rightarrow \mathcal{F} \rightarrow \mathcal{F}'' \rightarrow 0$, and that $s|_{U \cap V} = t'|_{U \cap V}$. Thus there exists a section $\tilde{s} \in \mathcal{F}(U \cup V)$ such that $g(\tilde{s}) = s''|_{U \cup V}$. But this contradicts maximality of (U, s) . Thus, $U = X$. \square

3.2. Homological Algebra. Idea: If $0 \rightarrow \mathcal{F}' \rightarrow \mathcal{F} \rightarrow \mathcal{F}'' \rightarrow 0$ is a SES, we want a (functorial) LES

$$\begin{array}{ccccccc}
 0 & \longrightarrow & \Gamma(\mathcal{F}') & \longrightarrow & \Gamma(\mathcal{F}) & \longrightarrow & \Gamma(\mathcal{F}'') \\
 & & & & & & \downarrow \\
 & & \hookrightarrow & H^1(\mathcal{F}') & \longrightarrow & H^1(\mathcal{F}) & \longrightarrow & H^1(\mathcal{F}'') \\
 & & & & & & \downarrow \\
 & & \hookrightarrow & H^2(\mathcal{F}') & \longrightarrow & H^2(\mathcal{F}) & \longrightarrow & H^2(\mathcal{F}'') & \longrightarrow & \dots
 \end{array}$$

The collection of functors $\{H^i\}_{i \in \mathbb{Z}_{\geq 0}}$ is called a δ -functor.

There are also naturality conditions. Given a map of SES,

$$\begin{array}{ccc}
 0 & & 0 \\
 \uparrow & & \uparrow \\
 \mathcal{F}_1'' & \longrightarrow & \mathcal{F}_2'' \\
 \uparrow & & \uparrow \\
 \mathcal{F}_1 & \longrightarrow & \mathcal{F}_2 \\
 \uparrow & & \uparrow \\
 \mathcal{F}_1' & \longrightarrow & \mathcal{F}_2' \\
 \uparrow & & \uparrow \\
 0 & & 0
 \end{array}
 \quad \overset{\text{require that}}{\rightsquigarrow}
 \quad
 \begin{array}{ccc}
 H^{i+1}(\mathcal{F}_1') & \longrightarrow & H^{i+1}(\mathcal{F}_2') \\
 \delta \uparrow & \circlearrowleft & \delta \uparrow \\
 H^{i+1}(\mathcal{F}_1'') & \longrightarrow & H^{i+1}(\mathcal{F}_2'')
 \end{array}$$

Where does this come from? If $0 \rightarrow A^\bullet \rightarrow B^\bullet \rightarrow C^\bullet \rightarrow 0$ is a SES of cochain complexes (concentrated in nonnegative degrees), there exists a LES

$$\begin{array}{ccccccc}
 0 \cdots & \longrightarrow & H^i(A) & \longrightarrow & H^i(B) & \longrightarrow & H^i(C) \\
 & & & & & & \uparrow \delta \\
 & & & & & & \longleftarrow \\
 & & & & & & H^{i+1}(A) & \longrightarrow & H^{i+1}(B) & \longrightarrow & H^{i+1}(C) & \longrightarrow \cdots
 \end{array}$$

I.e. $\{H^i\}$ is a δ -functor.

Suppose we have

$$\begin{array}{ccccccccc}
 0 & \longrightarrow & A^i & \xrightarrow{f} & B^i & \xrightarrow{g} & C^i & \longrightarrow & 0 \\
 & & \downarrow d & & \downarrow d & & \downarrow d & & \\
 0 & \longrightarrow & A^{i+1} & \xrightarrow{f} & B^{i+1} & \xrightarrow{g} & C^{i+1} & \longrightarrow & 0
 \end{array}$$

We want to define a map $H^i(C) \xrightarrow{f} H^{i+1}(A)$. Let $c \in H^i(C)$, and choose a representative $\tilde{c} \in C^i$ such that $d\tilde{c} = 0$. There exists $\tilde{b} \in B^i$ such that $g(\tilde{b}) = \tilde{c}$; $g(d\tilde{b}) = 0$, so there exists $\tilde{a} \in A^{i+1}$ such that $f(\tilde{a}) = d\tilde{b}$. But now, $f(d\tilde{a}) = 0$, so $d\tilde{a} = 0$ and thus \tilde{a} represents a class $a \in H^{i+1}(A)$. Thus we define

$$h(c) = a.$$

We can see the argument diagrammatically as follows:

$$\begin{array}{ccccccc}
 & & \tilde{b} & \longmapsto & \tilde{c} & & \\
 0 & \longrightarrow & A^i & \longrightarrow & B^i & \longrightarrow & C^i & \longrightarrow & 0 \\
 & & \downarrow & & \downarrow & & \downarrow & & \\
 0 & \longrightarrow & A^{i+1} & \longrightarrow & B^{i+1} & \longrightarrow & C^{i+1} & \longrightarrow & 0 \\
 & & \tilde{a} & \longmapsto & d\tilde{b} & & & &
 \end{array}$$

and so

$$\begin{array}{ccc}
 0 & \longrightarrow & A^{i+2} & \longrightarrow & B^{i+2} \\
 & & d\tilde{a} & \longmapsto & 0
 \end{array}$$

Computing cohomology. Let's assume that we've already constructed

$$H^i(X; -) : \text{Sh}(X) \rightarrow \text{Ab}$$

as a δ -functor. How would we compute this?

Remark There is a category of cohomological δ -functors, and there is a notion of a *universal* δ -functor: a terminal object in this category. The $H^i(X; -)$ will be universal in this sense.

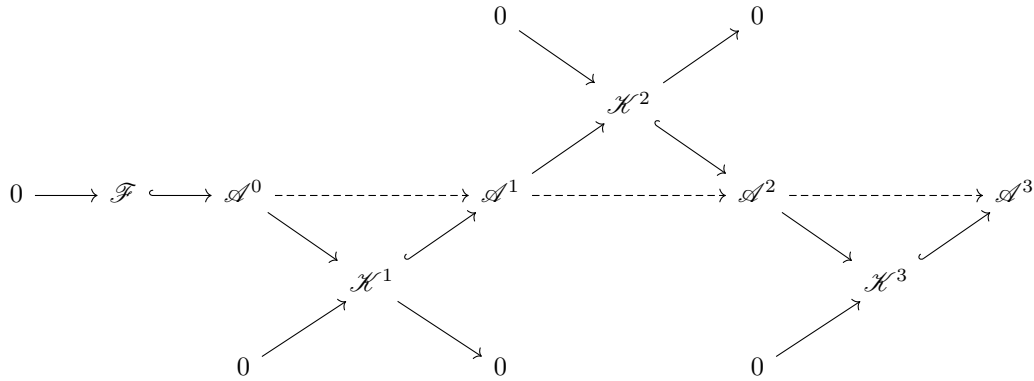
Suppose also that there exists a collection of sheaves $\mathbb{A} := \{\mathcal{A}\}$, such that $H^i(\mathcal{A}) = 0$ for $i > 0$ when $\mathcal{A} \in \mathbb{A}$ (*acyclics*), and for each \mathcal{F} there is some $\mathcal{A} \in \mathbb{A}$ such that $\mathcal{F} \hookrightarrow \mathcal{A}$.

It turns out that flabby sheaves are such an example:

$$\mathcal{F} \hookrightarrow G(\mathcal{F}) := \prod_{x \in X} i_x(\mathcal{F}_x).$$

$G(\mathcal{F})$ is called the *sheaf of discontinuous sections* of \mathcal{F} .

Now, let's compute H^1 . There is a SES $0 \rightarrow \mathcal{F} \rightarrow \mathcal{A}^0 \rightarrow \mathcal{K}^1 \rightarrow 0$ which we can continue into an exact sequence by finding an acyclic \mathcal{A}^1 such that $\mathcal{K}^1 \hookrightarrow \mathcal{A}^1$, splicing in the result, and then repeating the procedure for \mathcal{K}^2 and etc.:



Taking the cohomology LES gives

$$H^0(\mathcal{F}) \rightarrow H^0(\mathcal{A}^0) \rightarrow H^0(\mathcal{K}^1) \rightarrow H^1(\mathcal{F}) \rightarrow H^1(\mathcal{A}^0) = 0,$$

since \mathcal{A}^0 is acyclic. So we can express

$$H^1(\mathcal{F}) = H^0(\mathcal{A}^1) / \text{im}(H^0(\mathcal{A}^0)).$$

Continuing the LES,

$$H^1(\mathcal{A}^0) = 0 \rightarrow H^1(\mathcal{K}^1) \xrightarrow{\sim} H^2(\mathcal{F}) \rightarrow 0.$$

Now as in the above splicing picture, we can play the same game for $\mathcal{K}^1 \hookrightarrow \mathcal{A}^1$:

$$H^2(\mathcal{F}) \cong H^1(\mathcal{K}^1) = H^0(\mathcal{K}^2) / \text{im}(H^0(\mathcal{A}^1)).$$

How can we splice this information together? \mathcal{A}^\bullet is a complex, and we have a *cohomology sheaf* $\mathcal{H}^i(\mathcal{A}^\bullet)$. We also (importantly!) have the

$$H^i(\Gamma(\mathcal{A}^\bullet)) = H^i(\mathcal{F}).$$

Why? Exactness gives that

$$\ker(\mathcal{A}^1 \rightarrow \mathcal{A}^2) = \mathcal{K}^1,$$

so

$$H^1(\mathcal{F}) = \ker(H^0(\mathcal{A}^1) \rightarrow H^0(\mathcal{A}^2)) / \text{im}(H^0(\mathcal{A}^0) \rightarrow H^0(\mathcal{A}^1)).$$

Summary: If for all $\mathcal{F} \in \text{Sh}(X)$ there exists \mathcal{A}^\bullet such that $\mathcal{F} \hookrightarrow \mathcal{A}^\bullet$ and $H^i(\mathcal{A}^\bullet) = 0$ for all $i > 0$, then we can compute $H^i(\mathcal{F})$ as $H^i(\Gamma(\mathcal{A}^\bullet))$. We call such an \mathcal{A}^\bullet an *acyclic resolution*.

Definition 17. A δ -functor which has the above property (i.e. existence of acyclic resolutions) is called *effacable*.

Theorem 3.2. *An effacable δ -functor is universal.*

3.2.1. *Injective resolutions.* Let \mathcal{C} be an abelian category. An object $I \in \mathcal{C}$ is *injective* if $\text{Hom}(-, I)$ is exact. I.e.

$$\begin{array}{ccccc} 0 & \longrightarrow & A & \longrightarrow & B \\ & & \downarrow & \swarrow \exists & \\ & & I & & \end{array}$$

Remark If $0 \rightarrow I \rightarrow B \rightarrow C \rightarrow 0$ is a SES it is split, since

$$\begin{array}{ccccccc} 0 & \longrightarrow & I & \longrightarrow & B & \longrightarrow & C \longrightarrow 0 \\ & & \parallel & \swarrow \text{splitting map} & & & \\ & & I & & & & \end{array}$$

Remark If F is an additive functor, it preserves split exact sequences.

Example 31. In Ab , \mathbb{Z} is not injective; e.g.

$$0 \rightarrow \mathbb{Z} \xrightarrow{\times 2} \mathbb{Z} \rightarrow \mathbb{Z}/2\mathbb{Z} \rightarrow 0,$$

but $\mathbb{Z} \not\cong \mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z}$. On the other hand, \mathbb{Q} is injective.

Definition 18. A category \mathcal{C} is said to have *enough injectives* if for all $A \in \mathcal{C}$ there exists I injective such that $A \hookrightarrow I$. Having enough injectives implies the existence of *injective resolutions* $A \rightarrow I^\bullet$.

Suppose $F : \mathcal{C} \rightarrow \mathcal{D}$ is left exact, and \mathcal{C} has enough injectives. Then we can define a (universal) δ -functor $R^i F$ as follows:

$$R^i F(A) := H^i(F(I^\bullet)),$$

where $A \rightarrow I^\bullet$ is an injective resolution.

Why is this well defined, and why is it a δ -functor? This boils down to the *comparison lemma*

$$\begin{array}{ccc} A & \longrightarrow & B \\ \downarrow & & \downarrow \\ I^\bullet & \dashrightarrow \exists & J^\bullet \end{array}$$

and the *Horseshoe lemma*

$$\begin{array}{ccccccc} 0 & \longrightarrow & A & \longrightarrow & B & \longrightarrow & C \longrightarrow 0 \\ & & \downarrow & & \downarrow & & \downarrow \\ 0 & \longrightarrow & I^\bullet & \dashrightarrow & J^\bullet := I^\bullet \oplus K^\bullet & \dashrightarrow & K^\bullet \longrightarrow 0 \end{array}$$

In particular:

$$H^i(X; -) = R^i \Gamma(X; -).$$

Remark The LES sequence of the δ -functor is exactly the cohomology LES of

$$0 \rightarrow F(I^\bullet) \rightarrow F(J^\bullet) \rightarrow F(K^\bullet) \rightarrow 0.$$

We can compute cohomology using injective resolutions.

3.3. **Why does $\text{Sh}(X)$ have enough injectives?** Ab has enough injectives, since \mathbb{Q}/\mathbb{Z} is injective and

$$A \xrightarrow{\text{embeds}} \text{Hom}(A, \mathbb{Q}/\mathbb{Z}) \xrightarrow{\text{embeds}} \prod \mathbb{Q}/\mathbb{Z}.$$

Then for $\mathcal{F} \in \text{Sh}(X)$, we can construct injectives $I(-)$ using the above procedure (see [W]) to obtain

$$\mathcal{F} \hookrightarrow G(\mathcal{F}) = \prod_{x \in X} (i_x)_*(\mathcal{F}_x) = \prod_{x \in X} (i_x)_* I(\mathcal{F}_x).$$

3.4. **Computing sheaf cohomology.** Recall that we can compute cohomology using acyclic resolutions.

Proposition 3.3. *Flabby sheaves are acyclic.*

Proof. If \mathcal{F} is flabby, take an injective resolution $0 \rightarrow \mathcal{F} \rightarrow I^\bullet$. Now, injective sheaves are flabby (exercise), and in the SES

$$0 \rightarrow \mathcal{F} \rightarrow I^\bullet \rightarrow \mathcal{K} \rightarrow 0$$

\mathcal{K} is also flabby (exercise). So the LES of a δ -functor gives

$$\begin{array}{ccccccc} 0 & \longrightarrow & H^0(\mathcal{F}) & \longrightarrow & H^0(I) & \twoheadrightarrow & H^0(\mathcal{K}) \\ & & & & & & \downarrow 0 \\ & & \hookrightarrow & H^1(\mathcal{F}) & \longrightarrow & 0 & \longrightarrow & 0 \\ & & & & & & \downarrow \\ & & \hookrightarrow & H^2(\mathcal{F}) & \longrightarrow & 0 & \longrightarrow & \dots \end{array}$$

□

We have $\mathcal{F} \hookrightarrow G(\mathcal{F})$, so we have from this the *Godement resolution* $\mathcal{F} \hookrightarrow G^\bullet(\mathcal{F})$, and so

$$H^i(X; \mathcal{F}) = H^i(\Gamma(G^\bullet(\mathcal{F}))).$$

Computing cohomology with the Godement resolution is, however, bloody stupid. Thankfully we have already seen that all we need are acyclic resolutions.

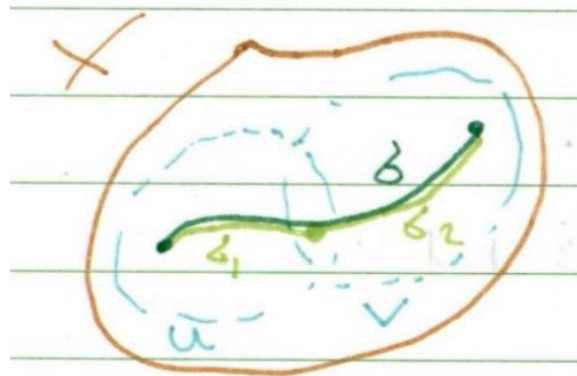


FIGURE 13. Sum of two singular chains.

3.4.1. *Singular cohomology.* Let $\mathcal{C}_X^{\text{sing,pre}}$ be the presheaf of singular cochains on X with coefficients in \mathbb{Z} . This is **not** a sheaf!

Let $\sigma \in C_i(X)$ be as pictured in Figure 13, and let $\varphi \in C^i(X)$ be defined by $\varphi(\sigma) = 1$ and $\varphi(\tilde{\sigma}) = 0$ if $\tilde{\sigma} \neq \lambda\sigma$. Then in particular, $\varphi|_U \equiv 0$.

So $\mathcal{C}_X^{\text{sing,pre}}$ is not a sheaf. But for sort of a silly reason: if we define σ_1 and σ_2 as in Figure 13 then $\varphi(\sigma_i) = 0$, but $\varphi(\sigma_1 + \sigma_2) = \varphi(\sigma) = 1$. We really should have that $\sigma_1 + \sigma_2$ and σ represent the same object.

So, define $\mathcal{C}_X^{\text{sing}} := \text{sh}(\mathcal{C}_X^{\text{sing,pre}})$.

Claims:

- (1) There is a quasi-isomorphism $\mathcal{C}_X^{\text{sing}}(X)^\bullet \simeq \mathcal{C}_X^{\text{sing,pre}}(X)^\bullet = C^{\text{sing}}(X)^\bullet$ (this uses “the lemma of small chains”).
- (2) $\mathcal{C}_X^{\text{sing}}$ is flabby.
- (3) If X is locally contractible, then

$$\mathbb{Z}_X \rightarrow \mathcal{C}_X^{\text{sing}}$$

is a resolution. For this, exactness on small enough contractible opens is sufficient; then $H^0 = \mathbb{Z}$ and $H^i = 0$ for $i > 0$.

So if X is locally contractible, then for a locally constant sheaf \mathcal{E} ,

$$H^i(X; \mathcal{E}) = H_{\text{sing}}^i(X; \mathcal{E}).$$

3.4.2. *De Rham cohomology.* If M is a smooth manifold, then we have the *sheaf of smooth i -forms on M* , \mathcal{A}_M^i . Using the de Rham differential we get a complex

$$\mathcal{A}_M^\bullet := \mathcal{C}_M^\infty = \mathcal{A}_M^0 \xrightarrow{d} \mathcal{A}_M^1 \xrightarrow{d} \mathcal{A}_M^2 \xrightarrow{d} \dots$$

Then the Poincaré lemma says that $\mathbb{C}_M \rightarrow \mathcal{A}_M^\bullet$ is a resolution. I.e.,

$$0 \rightarrow \mathbb{C} \rightarrow A^0(\mathbb{R}^n) \rightarrow A^1(\mathbb{R}^n) \rightarrow \dots \rightarrow A^n(\mathbb{R}^n) \rightarrow 0$$

is exact (“any closed form on \mathbb{R}^n is exact”).

Remark Really this is just an application of the fundamental theorem of calculus.

Now: the \mathcal{A}_M^i are not flabby, but they are *fine* (and *soft*).

Exercise 3.1. Prove that the \mathcal{A}_M^i are acyclic (hint: partitions of unity). Thus it will follow that

$$H^i(M; \mathbb{C}_M) \cong H^i(\mathcal{A}_M^\bullet(M)) = H_{\text{dR}}^i(M; \mathbb{C}).$$

3.4.3. *Dolbeault resolution.* If X is a complex manifold, we have sheaves \mathcal{O}_X of holomorphic functions and Ω_X^i of holomorphic i -forms. We have that

$$\mathbb{C}_X \rightarrow \Omega_X^0 \xrightarrow{d} \dots \rightarrow \Omega_X^n$$

is a resolution. But we can’t compute cohomology with this: the Ω_X^i are not acyclic!

What we can do is the following. Begin by embedding $\Omega_X^0 \hookrightarrow \mathcal{A}_X^0$ (smooth functions). Then we have a resolution

$$\Omega_X^0 \rightarrow \mathcal{A}_X^0 \xrightarrow{\bar{\partial}} \mathcal{A}^{0,1} \xrightarrow{\bar{\partial}} \mathcal{A}^{0,2} \rightarrow \dots \rightarrow \mathcal{A}^{0,n},$$

and this is an acyclic resolution. In fact, we can form a double complex:

$$\begin{array}{ccccccc} & & & & & & \mathcal{A}^{0,n} \\ & & & & & & \uparrow \bar{\partial} \\ & & & & & & \vdots \\ & & & & & & \uparrow \bar{\partial} \\ & & & & & & \vdots \\ & & & & & & \uparrow \bar{\partial} \\ & & & & & & \mathcal{A}^{0,1} \xrightarrow{\partial} \mathcal{A}^{1,1} \\ & & & & & & \uparrow \bar{\partial} \\ & & & & & & \mathcal{A}_X^0 \xrightarrow{\partial} \mathcal{A}^{1,0} \longrightarrow \dots \\ & & & & & & \uparrow \\ \Omega_X^0 & \longrightarrow & \Omega_X^1 & \longrightarrow & \dots & \longrightarrow & \Omega_X^n \end{array}$$

Then we have that in fact

$$H^p(\Omega_X^q) = H_{\text{Dol}}^{q,p}(X) =: H^p(\Gamma(\mathcal{A}^{q,\bullet}), \bar{\partial}).$$

4. MORE DERIVED FUNCTORS.

If $f : X \rightarrow Y$ we have the functor

$$f_* : \text{Sh}(X) \rightarrow \text{Sh}(Y);$$

observe that $f_* = \Gamma$ if $f : X \rightarrow \text{pt.}$ f_* is a left exact functor between abelian categories, so we can define the right derived functors of f_*

$$R^i f_*(\mathcal{F}) = \mathcal{H}^i(f_*(\mathcal{I}^\bullet))$$

where \mathcal{I} is an injective/flabby/acyclic resolution of \mathcal{F} , and so $f_*(\mathcal{I})$ is a complex of sheaves on Y . Thus $R^i f_*(\mathcal{F}) \in \text{Sh}(Y)$.

Example 32. If $f : X \rightarrow Y$ is a fibration (or fibre bundle, or submersion), then for the constant sheaf $R^i f_*(\mathbb{Z}_X) \in \text{Sh}(Y)$, and on stalks

$$R^i f_*(\mathbb{Z}_X)_y = H^i(f^{-1}(y); \mathbb{Z}).$$

Warning! Take $i : \mathbb{C}^\times \hookrightarrow \mathbb{Z}$ and pushforward the constant sheaf (or sheaf of singular cochains). Then since locally around $0 \in \mathbb{C}$ we have punctured open balls ($\cong \mathbb{C}^\times$) our stalk at zero picks up

$$R^1 i_*(\mathbb{Z}_{\mathbb{C}^\times})_0 \cong H^1(\mathbb{C}^\times; \mathbb{Z}) = \mathbb{Z}.$$

Now, if $X \xrightarrow{f} Y \xrightarrow{g} Z$ it is easy to show that $(g \circ f)_* = g_* f_*$. What about $R^i g_* \circ R^j f_*$?

Example 33. Using $Z = \text{pt}$ we might wish to try and compute cohomology on a fibration by understanding how the cohomology of the fibres varies and taking the sheaf cohomology of that. This is computed using the *Leray spectral sequence*, which is a potential topic for another day.

For the moment we take a different tack. We have

$$R^i f_*(\mathcal{F}) = \mathcal{H}^i(f_*(\mathcal{I}^0) \rightarrow f_*(\mathcal{I}^1) \rightarrow \dots),$$

so we define the *total derived functor* to be

$$Rf_*(\mathcal{F}) = f_*(\mathcal{I}^0) \rightarrow f_*(\mathcal{I}^1) \rightarrow \dots$$

We will worry about the dependence upon a choice of \mathcal{I} in a second. Observe that

$$Rg_* \circ Rf_* = R(g \circ f)_* = g_* f_*(\mathcal{I}^\bullet).$$

This makes sense, as the pushforward of an injective resolution is still an injective resolution.

Remark The equation $Rg_* \circ Rf_* = R(g \circ f)_*$ secretly encodes the Leray-Serre spectral sequence.

Remark If \mathcal{F}^\bullet is a *complex* of sheaves (bounded below) we can find an injective resolution

$$\mathcal{F}^\bullet \xrightarrow{\text{quasi-isomorphism}} \mathcal{I}^\bullet,$$

and $Rf_*(\mathcal{F}^\bullet) = f_*(\mathcal{I}^\bullet)$.

What is going on here? We would like to say that we have a functor

$$Rf_* : \{\text{Complexes of sheaves on } X.\} \rightarrow \{\text{Complexes of sheaves on } Y.\},$$

but this doesn't make sense – there are sheaves which are quasi-isomorphic but **not** isomorphic. We can fix this by taking (roughly)

$$Rf_* : D^+(\text{Sh}(X)) \rightarrow D^+(\text{Sh}(Y)),$$

where $D^+(\text{Sh}(X))$ is the *derived category*,

$$D^+(\text{Sh}(X)) = \{\text{bounded below complexes of sheaves on } X\}[\text{quasi-isomorphisms}]^{-1},$$

a category whose objects are complexes, whose morphisms are morphisms of complexes, but where all quasi-isomorphisms have been inverted.

Warning! This is not rigorous definition – there are problems we will tackle later.

Remark If \mathcal{F} and \mathcal{G} are objects in $D^+(\mathrm{Sh}(X))$ and $\mathcal{H}^i(\mathcal{F}) \cong \mathcal{H}^i(\mathcal{G})$ for all i , it is not necessarily true that $\mathcal{F} \simeq \mathcal{G}$ (quasi-isomorphism).

Example 34. Consider the Hopf fibration $S^1 \hookrightarrow S^3 \xrightarrow{f} S^2$. We want to consider $Rf_*(\mathbb{Z}_{S^3}) \in D^+\mathrm{Sh}(S^2)$. Let's look at the cohomology objects $R^i f_*(\mathbb{Z}_{S^3}) \in \mathrm{Sh}(S^2)$. f is a fibration, so for $U \subset S^2$ a small disk,

$$\Gamma(U; R^i f_*(\mathbb{Z}_{S^3})) = H^i(\underbrace{f^{-1}(U)}_{S^1 \times U}; \mathbb{Z}) \cong H^i(S^1; \mathbb{Z}).$$

So the $R^i f_*(\mathbb{Z}_{S^3})$ are locally constant, and since S^2 is simply connected, locally constant sheaves are constant. Hence,

$$\begin{aligned} R^0 f_*(\mathbb{Z}_{S^3}) &= \mathbb{Z}_{S^2} && \text{(measuring } H^0 \text{ of fibres)} \\ R^1 f_*(\mathbb{Z}_{S^3}) &= \mathbb{Z}_{S^2} && \text{(measuring } H^1 \text{ of fibres)} \end{aligned}$$

What is the total derived functor $Rf_*(\mathbb{Z}_{S^3})$? There is always an obvious guess:

$$\mathbb{Z}_{S^2} \oplus \mathbb{Z}_{S^2}[-1].$$

Consider

$$S^3 \xrightarrow{f} S^2 \xrightarrow{p} \mathrm{pt},$$

which gives

$$\underbrace{Rp_*}_{R\Gamma(S^2; -)} Rf_* = R(p \circ f)_* = R\Gamma(S^3; -).$$

Now if this were the total derived functor, we would have

$$Rp_*(\mathbb{Z}_{S^2} \oplus \mathbb{Z}_{S^2}[-1]) = \underbrace{Rp_*(\mathbb{Z}_{S^2})}_{C^*(S^2; \mathbb{Z})} \oplus \underbrace{Rp_*(\mathbb{Z}_{S^2})[-1]}_{C^*(S^2; \mathbb{Z})[-1]},$$

and upon taking cohomology of this complex, we get

$$H^*(Rp_*(\mathbb{Z}_{S^2} \oplus \mathbb{Z}_{S^2}[-1])) = \mathbb{Z} \oplus \mathbb{Z}[-1] \oplus \mathbb{Z}[-2] \oplus \mathbb{Z}[-3].$$

But $H^*(S^3) = \mathbb{Z} \oplus \mathbb{Z}[-3]$, and so

$$Rf_*(\mathbb{Z}_{S^3}) \not\cong \mathbb{Z}_{S^2} \oplus \mathbb{Z}_{S^2}[-1].$$

Remark A spectral sequence calculation relates $H^*(S^3)$ and $H^*(Rp_*(\mathbb{Z}_{S^2} \oplus \mathbb{Z}_{S^2}[-1]))$. The calculation makes transparent how the degree 1 and 2 \mathbb{Z} terms are killed off.

4.1. Compactly supported sections. Define the *compactly supported sections* functor by

$$\begin{aligned} \Gamma_c(X; -) &: \mathrm{Sh}(X) \rightarrow \mathrm{Ab} \\ \Gamma_c(X; \mathcal{F}) &= \{s \in \Gamma(X; \mathcal{F}) \mid \mathrm{supp}(s) \subseteq K \subseteq X \text{ for some compact } K\} \end{aligned}$$

where

$$\mathrm{supp}(s) := \{x \in X \mid s_x \in \mathcal{F}_x \text{ is nonzero}\}.$$

Exercise 4.1. Show that $\mathrm{supp}(s)$ is closed.

Γ_c is left exact, so we can consider its right derived functors which we call the *compactly supported cohomology* of \mathcal{F} :

$$R^i \Gamma_c(X; \mathcal{F}) = H_c^i(X; \mathcal{F}).$$

Example 35. If X is compact, then $\Gamma_c(X; -) = \Gamma(X; -)$.

Example 36. If $X = \mathbb{R}^n$, $\Gamma_c(X; \mathbb{Z}_{\mathbb{R}^n}) = 0$.

Given $f : X \rightarrow Y$ we can define

$$f_! : \text{Sh}(X) \rightarrow \text{Sh}(Y)$$

by

$$f_!(\mathcal{F})(V) = \left\{ s \in \mathcal{F}(f^{-1}(V)) \mid \begin{array}{l} \text{supp}(s) \subseteq f^{-1}(V), \text{ and} \\ \text{supp}(s) \xrightarrow{f|_{\text{supp}(s)}} V \text{ is proper} \end{array} \right\}.$$

(Recall that a map is *proper* if the preimage of a compact set is compact.)

We should assume some ‘niceness’ properties – e.g. Hausdorff, etc. We would need to change our notion of properness to work with, e.g. the Zariski topology for a variety.

Example 37. If Y is a point, $f_! = \Gamma_c$

Observe that

- a) If $i : Z \hookrightarrow X$ is a closed embedding, then i is proper.
- b) If $j : U \hookrightarrow X$ is an open embedding, then j is **not** proper.

Example 38.

$$\begin{array}{ccc} \mathbb{C}^\times & \xleftarrow{\text{open emb.}} & \mathbb{C} \\ & & \uparrow \text{closed emb.} \\ D^\times & \xleftarrow{\text{open emb.}} & \overline{D} \end{array}$$

4.2. **Summary of induced functors so far.** A map $f : X \rightarrow Y$ induces:

$$\begin{array}{ccc} f_* : \text{Sh}(X) & \xleftarrow{\hspace{2cm}} & \text{Sh}(Y) : f^* \\ \uparrow \text{right adjoint} & & \uparrow \text{left adjoint (and exact)} \\ \\ Rf_* : D^+\text{Sh}(X) & \xleftarrow{\hspace{2cm}} & D^+\text{Sh}(Y) : f^* \\ \uparrow \text{right adjoint} & & \uparrow \text{left adjoint (no need to derive)} \\ \\ f_! : \text{Sh}(X) & \longrightarrow & \text{Sh}(Y) \\ \downarrow & & \\ Rf_! : D^+\text{Sh}(X) & \longrightarrow & D^+(\text{Sh}(Y)) \end{array}$$

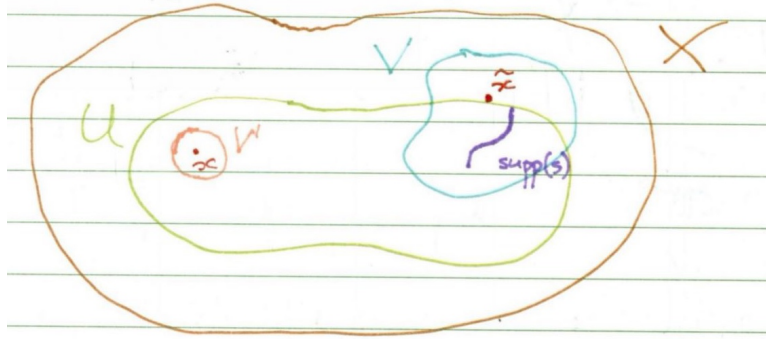
We call $f_!$ the *pushforward/direct image with proper supports*.

Example 39. If $Y = \text{pt}$, then

- $Rf_* = R\Gamma(X; -)$.
- $R^i f_* = H^i(X; -)$.
- $R^i f_! = H_c^i(X; -)$.

4.3. **Computing derived functors.** Let $j : U \hookrightarrow X$ be an open embedding, and let $\mathcal{G} \in \text{Sh}(U)$. Then

$$j_!(\mathcal{G})(V) = \{s \in \Gamma(U \cap V; \mathcal{G}) \mid \text{supp}(s) \hookrightarrow V \text{ is proper}\}.$$

FIGURE 14. Defining and computing $!$ -pushforward.

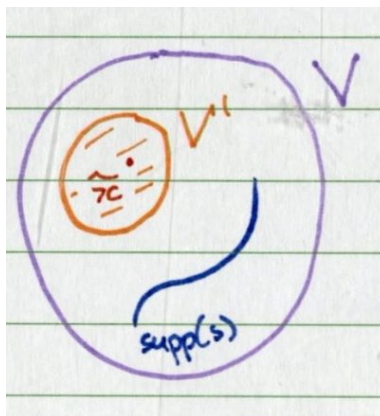
Observe that $\text{supp}(s) \hookrightarrow V$ is proper iff $\text{supp}(s)$ is closed in V .

Let's try and compute the stalk of this sheaf. For $x \in U$ we can always find $V' \subset U$ containing x ; thus the condition $\text{supp}(s) \hookrightarrow V'$ is proper is vacuous (since $s \in \Gamma(U \cap V'; \mathcal{G}) = \Gamma(V'; \mathcal{G})$). Thus the stalk at x is just \mathcal{G}_x , the stalk of \mathcal{G} at x .

Now consider $\tilde{x} \in U$, $X \ni \tilde{x}$.

$$\Gamma(V; j_! \mathcal{G}) = \{s \in \mathcal{G}(V \cap U) \mid \text{supp}(s) \hookrightarrow V \text{ is closed}\}.$$

Given such an s we can take $\tilde{x} \in V' \subseteq V$ such that $V' \cap \text{supp}(s) = \emptyset$ (this probably requires our space to be Hausdorff).

FIGURE 15. Separating V' and $\text{supp}(s)$.

Then

$$s \mapsto 0 \in (j_! \mathcal{G})_{\tilde{x}}.$$

We summarize:

$$(j_! \mathcal{G})_x = \begin{cases} \mathcal{G}_x & \text{if } x \in U, \\ 0 & \text{if } x \notin U. \end{cases}$$

We call this *extension of \mathcal{G} by 0*.

Now, it is clear that $j^* j_! \mathcal{G} \simeq \mathcal{G}$. What about $j_! j^* \mathcal{F}$? There is a map $j_! j^* \mathcal{F} \rightarrow \mathcal{F}$ given on open sets V by taking a section on $\mathcal{F}(U \cap V)$ and extending by 0 to all of V .

Proposition 4.1. $j_!$ is left adjoint to j^* .

The counit of the adjunction is $j_! j^* \mathcal{F} \rightarrow \mathcal{F}$, and the unit of the adjunction is $\mathcal{G} \rightarrow j^* j_! \mathcal{G}$. I.e. we have

$$\mathrm{Hom}(j_! \mathcal{G}, \mathcal{F}) \simeq \mathrm{Hom}(\mathcal{G}, j^* \mathcal{F}).$$

To move between the unit/counit and Hom description of the adjunction, take e.g.

$$\begin{array}{ccc} \mathrm{Hom}(j_! \mathcal{G}, j_! \mathcal{G}) & \xleftarrow{\sim} & \mathrm{Hom}(\mathcal{G}, j^* j_! \mathcal{G}) \\ \text{unit} & \longmapsto & \text{id} \end{array}$$

Remark The functor $j_!$ is exact (since it is exact on stalks by our earlier calculation).

Remark This adjunction and exactness is *only* for open embeddings!

4.4. **Functoriality.** Consider

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ & \searrow & \downarrow p \\ & & \text{pt} \end{array}$$

We want to compute $H^*(X; f^* \mathcal{G})$. We have

$$\begin{array}{ccc} R\Gamma(X; f^* \mathcal{G}) & \xlongequal{\quad} & R p_* \circ R f_*(f^* \mathcal{G}) \xleftarrow{\text{use adj.}} R p_*(\mathcal{G}) \\ & \swarrow \text{---} & \parallel \\ & & R\Gamma(Y; \mathcal{G}) \end{array}$$

So for example, if $\mathcal{G} = \mathbb{Z}_Y$, then we have a map

$$H^*(Y; \mathbb{Z}) \rightarrow H^*(X; \mathbb{Z}).$$

What about for compactly supported cohomology? We can try and do the same trick. **Assume f is proper.** Then $R f_* \simeq R f_!$, so we can run the same argument as above to get maps

$$H_c^*(X; \mathcal{G}) \rightarrow H_c^*(X; f^* \mathcal{G}),$$

which are given by

$$\begin{array}{ccc} R\Gamma_c(X; f^* \mathcal{G}) & \xlongequal{\quad} & R p_! \circ R f_!(f^* \mathcal{G}) \xleftarrow{f \text{ proper}} R p_! \circ R f_*(f^* \mathcal{G}) \xleftarrow{\quad} R p_*(\mathcal{G}) \\ & \swarrow \text{---} & \parallel \\ & & R\Gamma(Y; \mathcal{G}) \end{array}$$

Example 40. Consider the open embedding

$$\begin{array}{ccc} \mathbb{C}^\times & \xrightarrow{j} & \mathbb{C} \\ \parallel & & \parallel \\ \mathbb{R}^2 - \{0\} & & \mathbb{R}^2 \end{array}$$

We understand $j_!(\mathbb{Z}_{\mathbb{C}^\times})$ – it is constant away from 0, and has no sections on sets containing 0. Now we claim

$$j_* \mathbb{Z}_{\mathbb{C}^\times} = \mathbb{Z}_{\mathbb{C}}.$$

Letting U be a small ball around 0. Then this follows from

$$(j_* \mathbb{Z}_{\mathbb{C}^\times})(U) = \mathbb{Z}_{\mathbb{C}^\times}(U \cap \mathbb{C}^\times) \cong \mathbb{Z}.$$

j_* is not exact, so let's compute its derived functor:

$$R j_* (\mathbb{Z}_{\mathbb{C}^\times}) = j_*(\mathcal{C}_{\mathbb{C}^\times}^{\bullet, \text{sing}})(U) = C^{\bullet, \text{sing}}(U \cap \mathbb{C}^\times).$$

$U \cap \mathbb{C}^\times \simeq S^1$, so taking cohomology gives \mathbb{Z} in degrees 0 and 1. Now, we have the cohomology sheaves

$$R^0 j_* (\mathbb{Z}_{\mathbb{C}^\times}) = \mathbb{Z}_{\mathbb{C}}, \quad R^1 j_* (\mathbb{Z}_{\mathbb{C}^\times}) = \mathbb{Z}_0,$$

where we observe that we have a skyscraper sheaf at 0 since there is no first cohomology on contractible sets not containing 0.

4.5. Open-closed decomposition. Now, consider $j : U \hookrightarrow X \leftarrow Z : i$ where $Z = X - U$.

Exercise 4.2. The sequence

$$0 \rightarrow j_! j^* \mathcal{F} \rightarrow \mathcal{F} \rightarrow i_* i^* \mathcal{F} \rightarrow 0$$

is exact. (Hint: It is easy to check exactness on stalks.)

Think: “The sheaf \mathcal{F} is built up from its restriction to open and closed complementary subsets.”

Apply $R\Gamma_c(X; -)$ to the above SES:

$$\begin{array}{ccccc} R\Gamma_c(X; j_! j^* \mathcal{F}) & \longrightarrow & R\Gamma_c(X; \mathcal{F}) & \longrightarrow & R\Gamma_c(X; i_* i^* \mathcal{F}) \\ \parallel & & & & \parallel \\ R(p_U)_!(j^* \mathcal{F}) & \xlongequal{\quad} & R(p_X)_! j_! j^* \mathcal{F} & & R(p_X)_! i_* i^* \mathcal{F} \\ & & & & \parallel \\ & & & & R(p_X)_! i_! i^* \mathcal{F} \xlongequal{\quad} R(p_Z)_!(i^* \mathcal{F}) \end{array}$$

where

$$\begin{array}{ccc} U & \xrightarrow{j} & X \\ & \searrow p_U & \downarrow p_X \\ & & \text{pt} \end{array} \qquad \begin{array}{ccc} X & \xleftarrow{i} & Z \\ p_X \downarrow & \swarrow p_Z & \\ \text{pt} & & \end{array}$$

Then we obtain a LES

$$H_c^*(U; j^* \mathcal{F}) \rightarrow H_c^*(X; \mathcal{F}) \rightarrow H_c^*(Z; i^* \mathcal{F}),$$

which we call the *LES in compactly supported (CS) cohomology*.

Example 41. $j : \mathbb{R}^n \hookrightarrow S^n \leftarrow \text{pt} : i$, with $\mathcal{F} = \mathbb{Z}_{S^n}$. Since pt and S^n are compact (and we assume $n \geq 1$), we find that the LES in CS cohomology for \mathbb{Z}_{S^n} is:

$$\begin{array}{ccccc} 0 & & 0 & & 0 \\ H_c^n(\mathbb{R}^n; \mathbb{Z}) & \xrightarrow{\sim} & H^n(S^n; \mathbb{Z}) \cong \mathbb{Z} & & 0 \\ 0 & & 0 & & 0 \\ \vdots & & \vdots & & \vdots \\ 0 & & 0 & & 0 \\ H_c^0(\mathbb{R}^n; \mathbb{Z}) & \longrightarrow & H^0(S^n; \mathbb{Z}) \cong \mathbb{Z} & \xrightarrow{\sim} & H^0(\text{pt}; \mathbb{Z}) \cong \mathbb{Z} \end{array}$$

So

$$H_c^*(\mathbb{R}^n; \mathbb{Z}) = \begin{cases} \mathbb{Z}, & \text{if } * = n, \\ 0 & \text{else.} \end{cases}$$

In particular, observe that H_c^* is not a homotopy invariant – it can distinguish between \mathbb{R}^n of different dimensions.

Notation: If $j : U \rightarrow X$, write \mathcal{F}_U for $j_! j^* \mathcal{F}$.

If $X = U_1 \cup U_2$ with both U_i open, we have a SES of sheaves

$$0 \rightarrow \mathcal{F}_{U_1 \cap U_2} \xrightarrow{(+,+)} \mathcal{F}_{U_1} \oplus \mathcal{F}_{U_2} \xrightarrow{(+,-)} 0.$$

This gives rise to another LES, the *Mayer-Vietoris sequence in CS cohomology*.

Next, given $j : U \hookrightarrow X \leftarrow Z : j$, consider the exact sequence

$$0 \rightarrow \Gamma_Z \mathcal{F} \rightarrow \mathcal{F} \rightarrow j_* j^* \mathcal{F} =: \Gamma_U \mathcal{F},$$

where

$$(\Gamma_Z \mathcal{F})(V) = \{s \in \mathcal{F}(V) \mid \text{supp}(s) \subseteq Z\}.$$

Γ_Z is always left exact, but is not exact in general. So we can derive

$$R\Gamma_Z : D^+ \text{Sh}(X) \rightarrow D^+ \text{Sh}(X).$$

There is another functor

$$R\Gamma_Z(X, -) : D^+ \text{Sh}(X) \rightarrow D^+(\text{Ab}),$$

which we call the *local cohomology*.

5. VERDIER DUALITY.

Start with a map of topological spaces $f : X \rightarrow Y$. So far we have seen the following solid arrows:

$$\begin{array}{ccc}
 & f^* & \\
 & \curvearrowright & \\
 D^+ \text{Sh}(X) & \xrightarrow{Rf_*} & D^+ \text{Sh}(Y) \\
 & \xleftarrow{Rf_!} & \\
 & \curvearrowleft & \\
 & f_! &
 \end{array}$$

Natural question: Does the dashed adjoint exist?

Example 42. If $U \hookrightarrow X$ is an *open* embedding, we have seen that $j_! \dashv j^* \dashv Rj_*$, (\dashv means “is left adjoint to”). So in this case $j^! = j^*$.

Example 43. If $i : Z \hookrightarrow X$ is a *closed* embedding,

$$i^* \dashv i_* \simeq i_! \dashv i^* \Gamma_Z,$$

where $i_* \simeq i_!$ since i is proper, i^* is exact, and Γ_Z is left exact. Thus we can right derive to get

$$i^! = i^* R\Gamma_Z.$$

Remark We have seen that previously the functors f^* , $Rf_!$, etc on $D^+(\mathcal{A})$ are induced from functors on \mathcal{A} by (right) deriving. In general, $f^!$ is *only* defined in the derived category – it is not derived from the original categories.

For now, let us simplify by considering sheaves of rational vector spaces, $D^+ \text{Sh}_{\mathbb{Q}}(-)$. (This is a simplification since all \mathbb{Q} vector spaces are injective.)

In general: We want $Rf_! \dashv f^!$.

Remark If f is proper, $Rf_* \simeq Rf_!$.

5.1. Dualizing complex. Consider $p : X \rightarrow \text{pt}$. What is the “dualizing complex” $p^!(\mathbb{Q}) = \omega_X^\bullet$?

We haven’t constructed it yet, but let us deduce some of its properties. Unless otherwise stated, $\text{Hom}_X = \text{Hom}_{D^+(\text{Sh}(Z))}$. We will have

$$R\text{Hom}_X(\mathcal{F}, \omega_X^\bullet) = R\text{Hom}_X(\mathcal{F}, p^! \mathbb{Q}) \simeq R\text{Hom}_{\mathbb{Q}}(Rp_!(\mathcal{F}), \mathbb{Q}) = R\Gamma_c(X; \mathcal{F})^\vee,$$

where we are thinking of \mathbb{Q} as a complex concentrated in degree 0, and $-\vee$ denotes the dual complex of vector spaces.

Remark $R\mathrm{Hom}(A^\bullet, B^\bullet)$ means the *cochain complex* $\mathrm{Hom}^\bullet(A^\bullet, I^\bullet)$ where I^\bullet is an injective resolution of B^\bullet . I.e.

$$\mathrm{Hom}^n(A^\bullet, I^\bullet) = \bigoplus_i \mathrm{Hom}(A^i, I^{n+i}), \text{ which we can visualize as}$$

$$\begin{array}{ccc} \vdots & & \vdots \\ \uparrow & & \uparrow \\ A^2 & \xrightarrow{\text{orange}} & B^2 \\ \uparrow & & \uparrow \\ A^1 & \xrightarrow{\text{orange}} & B^1 \\ \uparrow & \nearrow \text{blue} & \uparrow \\ A^0 & \xrightarrow{\text{orange}} & B^0 \\ \uparrow & & \uparrow \\ A^{-1} & \xrightarrow{\text{orange}} & B^{-1} \\ \uparrow & & \uparrow \\ \vdots & & \vdots \end{array}$$

In the above, orange arrows are degree 0 homs, blue arrows are degree 2 homs, and the black arrows denote the differential we can put on this graded vector space such that

$$H^0(\mathrm{Hom}^\bullet(A^\bullet, I^\bullet)) = \mathrm{Hom}(A^\bullet, I^\bullet).$$

Remark The $R\mathrm{Hom}$ adjunction should follow from the Hom adjunction by the universal property of R .

Example 44. Let $\mathcal{F} = \mathbb{Q}_X = p^*\mathbb{Q}$ where $p: X \rightarrow \mathrm{pt}$. Then

$$R\mathrm{Hom}_X(\mathbb{Q}_X; \omega_X^\bullet) = R\mathrm{Hom}_{\mathbb{Q}}(\mathbb{Q}, R\Gamma(X; \omega_X^\bullet)) = R\Gamma(X; \omega_X^\bullet)$$

by the p^* adjunction, and

$$R\mathrm{Hom}_X(\mathbb{Q}_X; \omega_X^\bullet) = R\Gamma_c(X; \mathbb{Q})^\vee = C_c^*(X; \mathbb{Q})^\vee$$

by the (desired) $p^!$ adjunction. Be aware that C_c^* is a cochain complex that is not necessarily bounded below.

Remark If A^\bullet is a cochain complex of vector spaces, i.e.

$$\cdots \rightarrow A^i \rightarrow A^{i+1} \rightarrow A^{i+2} \rightarrow \cdots,$$

when we dualize we can either consider this as a chain complex, or we can relabel,

$$((A^\bullet)^\vee)^i = (A^{-i})^\vee,$$

so that $(A^\bullet)^\vee$ is a cochain complex. In this class, unless explicitly stated, all complexes are cochain complex.

Remark For X finite dimensional, $R\Gamma(X; \omega_X^\bullet)$ is bounded above. Thus, in general, if X is infinite dimensional the $!$ -pushforward does not exist (since we used this to get $C_c^*(X; \mathbb{Q})^\vee = R\Gamma(X; \omega_X^\bullet)$).

We define *Borel-Moore chains on X* to be

$$C_*^{\mathrm{BM}}(X; \mathbb{Q}) := C_c^*(X; \mathbb{Q})^\vee.$$

Example 45. Let $\mathcal{F} = \mathbb{Q}_U = j_!\mathbb{Q}_U$ for $j: U \hookrightarrow X$ an open subset. Then

$$R\Gamma(U; \omega_U^\bullet) = R\mathrm{Hom}(\mathbb{Q}_U; \omega_X^\bullet) = C_c^*(U; \mathbb{Q})^\vee,$$

where $\omega_U^\bullet = \omega_X^\bullet|_U$.

We have an assignment

$$\left(\begin{array}{c} \text{Open set } U \\ \text{in } X \end{array} \right) \mapsto \left(\begin{array}{c} \text{Cochain complex} \\ C_c^*(U; \mathbb{Q})^\vee \end{array} \right).$$

Think of this as a presheaf in cochain complexes:

$$\begin{array}{ccc} U \hookrightarrow V & \rightsquigarrow & C_c^*(U; \mathbb{Q}) \hookrightarrow C_c^*(V; \mathbb{Q}) \\ & & \downarrow \\ & & C_c^*(U; \mathbb{Q})^\vee \leftarrow C_c^*(V; \mathbb{Q})^\vee \end{array}$$

If we were working fully homotopically, we could take this as a definition.

But, as written we have a problem – an object in the derived category is an *equivalence class* of complexes. To make sense of this, we would need a homotopical version of a sheaf (an ∞ -stack).

5.1.1. *What is ω_X^\bullet ?* Let \mathcal{S}^\bullet be the Godement resolution of \mathbb{Q}_X ,

$$\mathcal{S}^0 = \prod_{x \in X} \mathbb{Q}_X.$$

Definition 19 (Tentative). $\omega_X^i(U) = \Gamma_c(U; \mathcal{S}^{-i})^\vee$ (so the dualizing sheaf is concentrated in negative degrees – it is a not necessarily bounded below complex).

We now have the meaning/interpretation

$$R\mathrm{Hom}_X(\mathbb{Q}_X, \omega_X^\bullet) \cong R\Gamma(\omega_X^\bullet) = \Gamma_c(X; \mathcal{S}^{-\bullet})^\vee \cong R\Gamma_c(X; \mathbb{Q})^\vee$$

where the final isomorphism is because \mathcal{S} resolves the constant sheaf.

We need the following assumption: X is *finite dimensional*.

$$\dim(X) := \max\{n \mid \exists \mathcal{F} \in \mathrm{Sh}(X), H_c^n(X; \mathcal{F}) = 0\}.$$

Fact: If $X = \mathbb{R}^n$, $\dim X = n$.

Another fact: Define $\mathcal{H}^\bullet \in D^+\mathrm{Sh}(X)$ by

$$\mathcal{H}^i := \begin{cases} \mathcal{S}^\bullet & \text{if } i < n, \\ \mathrm{im}(\mathcal{S}^{n-1} \rightarrow \mathcal{S}^n) & \text{if } i = n, \\ 0 & \text{if } i > n. \end{cases}$$

If $\dim(X) = n$, then \mathcal{H}^\bullet is a *soft* resolution of \mathbb{Q}_X .

Recall: \mathcal{F} is soft if for every $Z \subseteq X$ closed, $\Gamma(X; \mathcal{F}) \rightarrow \Gamma(Z; \mathcal{F})$ is surjective. Soft sheaves are acyclic for Γ_c .

Upshot: If X is finite dimensional, we can find a *finite* soft resolution of \mathbb{Q}_X .

Definition 20. $\omega_X^i \in \mathrm{Sh}(X)$ is given by

$$\omega_X^i(U) = \Gamma_c(U; \mathcal{H}^{-i})^\vee.$$

With the above definition and the finite dimensionality assumption,

$$\omega_X^\bullet \in D^+(\mathrm{Sh}(X)).$$

Now, let's look at homology complexes.

$$\begin{aligned} \mathrm{pre} \mathcal{H}^i(\omega_X^\bullet)(U) &= H^i(\Gamma_c(U; \mathcal{H}^\bullet)^\vee) \\ &= H^i(C_c^*(U; \mathbb{Q})^\vee) \\ &= H_c^{-i}(U; \mathbb{Q})^\vee \end{aligned}$$

where the final equality uses the rationality assumption (i.e. that we are dealing with vector spaces). In particular, on stalks we have

$$\mathcal{H}^i(\omega_X^\bullet)_x = \mathrm{colim}_{U \ni x} H_c^{-i}(U; \mathbb{Q})^\vee = H_c^{-i}(U; \mathbb{Q})$$

where the final equality holds for small enough U and nice enough X .

Main point: If $X = M^n$ is a topological n -manifold, then

$$\mathcal{H}^{-n}(\omega_X^\bullet) \text{ is a locally constant sheaf.}$$

Why? For charts $U \cong \mathbb{R}^n$,

$$\mathcal{H}^{-n}(\omega_X^\bullet)(U) = H^n(U; \mathbb{Q})^\vee = \mathbb{Q}.$$

Definition 21 (Orientation). $\mathcal{H}^{-n}(\omega_X^\bullet) = \mathcal{O}r_X$, is called the *orientation sheaf* of X . We say that X is *orientable* if $\mathcal{O}r_X \cong \mathbb{Q}_X$.

So: If $X = M^n$ is a compact, oriented manifold, we claim that

$$H^i(X; \mathbb{Q}) \cong H_{n-i}(X; \mathbb{Q}),$$

and in particular

$$b^i(X) = b_{n-i}(X) \quad (\text{equality of Betti numbers}).$$

Summary of properties (so far):

- (1) $\mathcal{H}^{-i}(\omega_X^\bullet)$ is the sheafification of

$$U \mapsto H_c^i(U; \mathbb{Q})^\vee = H_i^{\text{BM}}(U; \mathbb{Q}) := H^{-i}(U; \omega_U^\bullet).$$

The constant sheaf represents cochains; we can think of the dualizing complex ω_X^\bullet as representing Borel-Moore chains, i.e. “locally finite” (e.g. singular) chains.

- (2) $R\text{Hom}(\mathcal{F}^\bullet, \omega_X^\bullet) \simeq R\Gamma_c(X; \mathcal{F})^\vee$.

Example 46.

$$H_c^i(\mathbb{R}^n; \mathbb{Q}) = \begin{cases} \mathbb{Q}, & i = n \\ 0 & \text{otherwise} \end{cases} = H_i^{\text{BM}}(\mathbb{R}^n; \mathbb{Q}).$$

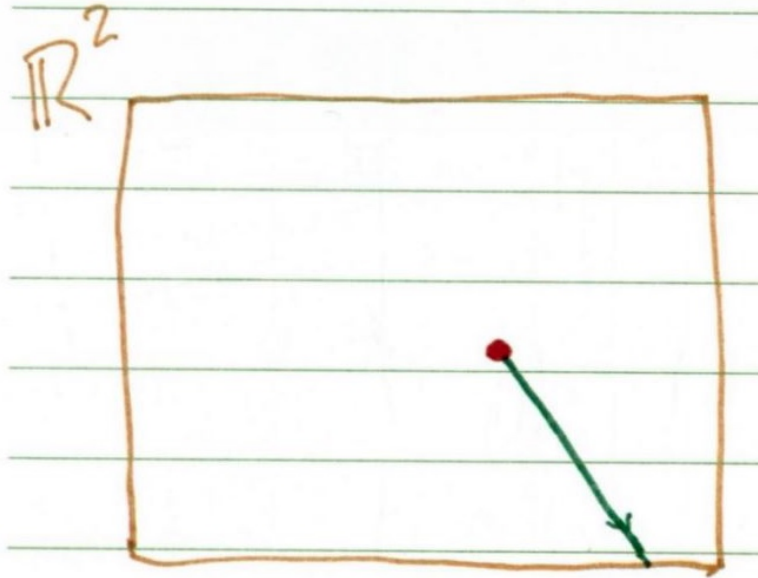


FIGURE 16. A Borel-Moore 1-cycle in \mathbb{R}^2 .

For instance:

- $H_2^{\text{BM}}(\mathbb{R}^2; \mathbb{Q}) \cong \mathbb{Q}$, generated by all of \mathbb{R}^2 , a *locally* finite sum of 2-simplices.
- $H_0^{\text{BM}}(\mathbb{R}^2; \mathbb{Q}) = 0$, since any point is the boundary of a ray headed out to ∞ (as per Figure 16).

If X is a topological n -manifold, then

$$\mathcal{H}^{-i}(\omega_X^\bullet) = 0 \quad \text{if } i \neq n,$$

and

$$\mathcal{H}^{-n}(\omega_X^\bullet) \text{ is locally constant.}$$

Define the *orientation sheaf* to be

$$\mathcal{O}r_X := \mathcal{H}^{-n}(\omega_X^\bullet).$$

We say that X is *orientable* if $\mathcal{O}r_X \simeq \mathbb{Q}_X$.

5.2. Poincaré Duality. If X is orientable,

$$H_i^{\text{BM}}(X; \mathbb{Q}) := H^{-i}(X; \omega_X^\bullet) \cong H^{-i}(X; \mathbb{Q}_X[n]) \cong H^{n-i}(X; \mathbb{Q}).$$

The isomorphism $H_i^{\text{BM}}(X; \mathbb{Q}) \cong H^{n-i}(X; \mathbb{Q})$ is called the *Poincaré Duality isomorphism* (PD). If X is compact this recovers the (potentially) more familiar statement of Poincaré Duality, since then $H_*^{\text{BM}} = H_*$.

Remark $H_i^{\text{BM}}(U; \mathbb{Q}) = H^{-i}(U; \omega_U^\bullet) = H^{-i}(\omega_X^\bullet(U))$.

5.2.1. *Why is PD true?* There are two types of “sheaves” (up to homotopy),

$$\begin{aligned} U &\mapsto C^*(U; \mathbb{Q}) \sim \mathbb{Q}_X \\ U &\mapsto C_c^*(U; \mathbb{Q})^\vee = C_*^{\text{BM}}(U; \mathbb{Q}) \sim \omega_X^\bullet. \end{aligned}$$

A priori, these are two different (pre)sheaves. But if they agree on a basis of open sets, they must agree everywhere.

So on a manifold we can check these agree (up to a shift) locally on X , via the computation on \mathbb{R}^n .

Example 47. $\mathbb{R}P^2$ and the Möbius strip are non-orientable. $\pi_1(\mathbb{R}P^2) = \mathbb{Z}/2\mathbb{Z}$, and $\mathcal{O}r_{\mathbb{R}P^2}$ is the local system corresponding to the non-trivial representation of $\mathbb{Z}/2\mathbb{Z}$.

5.3. Borel-Moore homology.

Example 48. Consider the singular space shown in Figure 17.

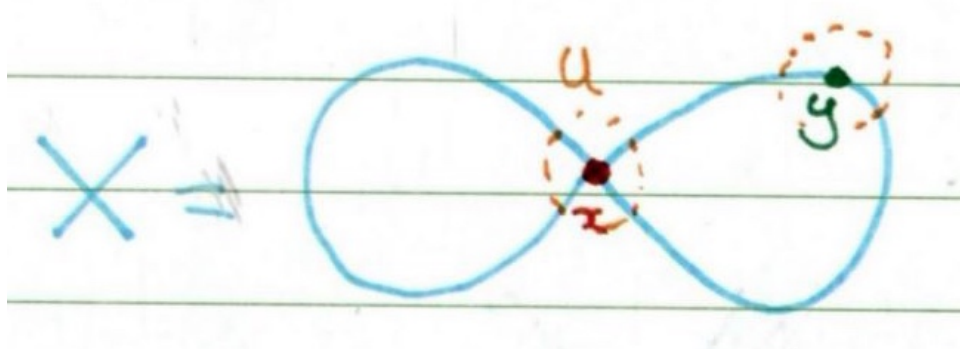


FIGURE 17. The ‘figure 8’ singular space.

Away from the singular point, we have

$$\mathcal{H}^{-i}(\omega_X^\bullet)_y = \begin{cases} \mathbb{Q}, & i = 1, \\ 0, & i \neq 1. \end{cases}$$

Locally around the singular point x , the space looks like the set U of Figure 18.

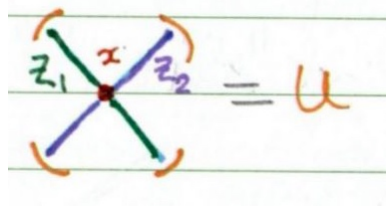


FIGURE 18. Local model around the singular point of the figure 8.

So,

$$\mathcal{H}^{-i}(\omega_X^\bullet)_x = H_i^{\text{BM}}(U; \mathbb{Q}).$$

How can we compute this Borel-Moore homology? In general there is a Mayer-Vietoris sheaf SES,

$$0 \rightarrow \mathcal{F}_{Z_1 \cup Z_2} \rightarrow \mathcal{F}_{Z_1} \oplus \mathcal{F}_{Z_2} \rightarrow \mathcal{F}_{Z_1 \cap Z_2} \rightarrow 0.$$

So we have a SES of sheaves

$$0 \rightarrow \mathbb{Q}_{Z_1 \cup Z_2} \rightarrow \mathbb{Q}_{Z_1} \oplus \mathbb{Q}_{Z_2} \rightarrow \mathbb{Q}_{Z_1 \cap Z_2} \rightarrow 0.$$

Apply the functor $R\Gamma_c$:

$$\begin{array}{c} \rightarrow H_c^1(Z_1 \cup Z_2) \longrightarrow H_c^1(Z_1) \oplus H_c^1(Z_2) \longrightarrow 0 \\ \\ \\ \end{array}$$

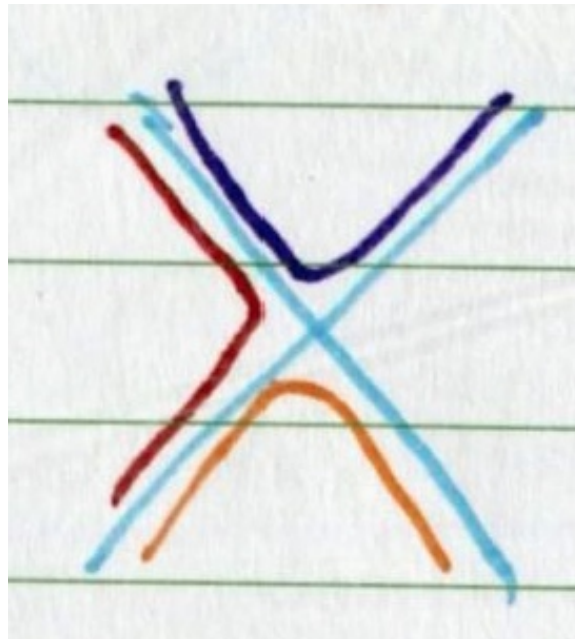
Since $Z_i \cong \mathbb{R}$ and $Z_1 \cap Z_2 = \text{pt}$, we have $H_c^1(Z_i) \cong \mathbb{Q}$, $H_c^0(Z_1 \cap Z_2) \cong \mathbb{Q}$, and $H_c^0(Z_i) = 0$. Hence we get a SES

$$0 \rightarrow \mathbb{Q} \rightarrow H_c^1(Z_1 \cup Z_2) \rightarrow \mathbb{Q}^2 \rightarrow 0,$$

and so

$$H_c^1(U) \cong \mathbb{Q}^3.$$

We can see this H_1^{BM} as generated by the three 'V' shaped cycles in Figure 19.

FIGURE 19. Borel-Moore generating 1-cycles for U .

So we can now see in Figure 20 that $\mathcal{H}^i(\omega_X^\bullet)$ is somehow measuring singularities in our space.

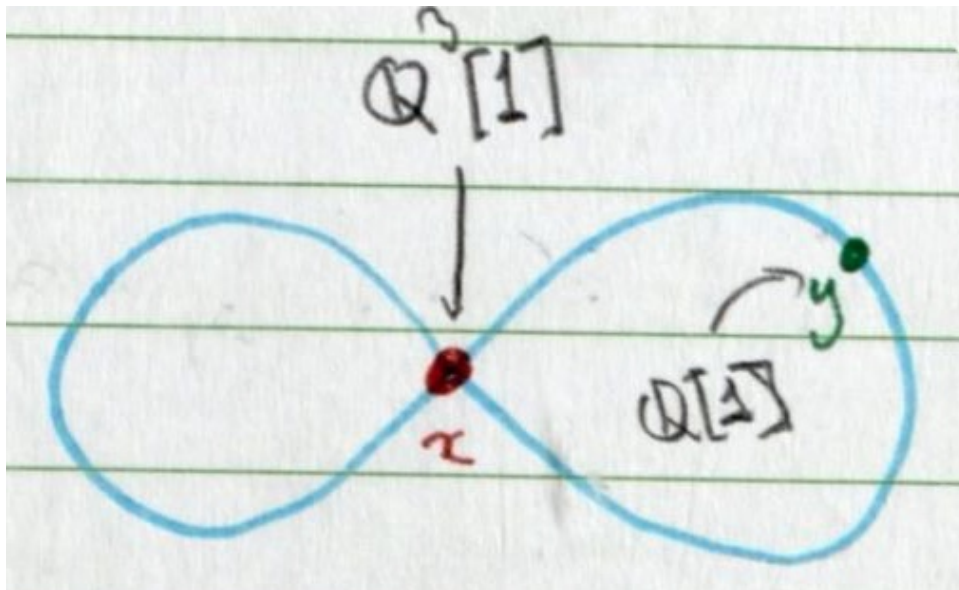


FIGURE 20. Stalks of the cohomology sheaf of ω_X^\bullet .

Exercise 5.1. Think about the restriction maps for this example.

Example 49. Think of the cone with open ends, as in Figure 21.

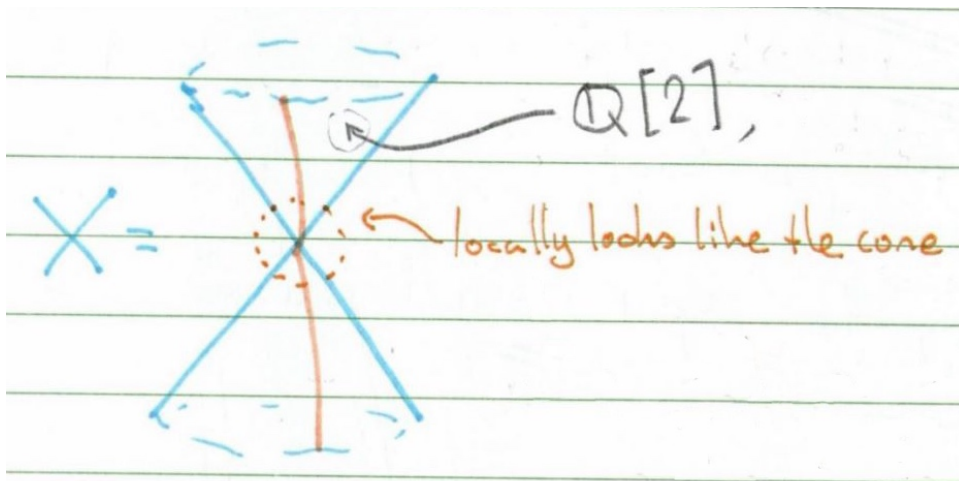


FIGURE 21. Borel-Moore homology of the cone with open ends.

Away from the singular point, the stalk of $\mathcal{H}^*(\omega_X^\bullet)$ is $\mathbb{Q}[2]$, since there the cone is locally a 2-manifold. Around the singular point, we have that locally the manifold looks again like all of X – so here we need to calculate $H_*^{\text{BM}}(X; \mathbb{Q})$. We have

$$H_*^{\text{BM}}(X; \mathbb{Q}) = \begin{cases} \mathbb{Q}^2, & * = 2 \text{ (generated by the upper and lower cones),} \\ \mathbb{Q}, & * = 1 \text{ (generated by the line in Figure 21).} \end{cases}$$

This is a rough geometric argument – we could also decompose and use a LES argument as we did in the previous example.

More generally, if $f : X \rightarrow Y$, we want to define

$$f^! : D^+ \text{Sh}(Y) \rightarrow D^+ \text{Sh}(X).$$

If $\mathcal{K} \in \text{Sh}(X)$ is a soft sheaf, and $\mathcal{F} \in \text{Sh}(Y)$ is injective,

$$f_{\mathcal{K}}^!(\mathcal{F}) = \text{Hom}(f_!(\mathcal{K}), \mathcal{F}).$$

Then define

$$f^!(\mathcal{F}) = (f_{\mathcal{K}^n}^!(\mathcal{F}) \rightarrow f_{\mathcal{K}^{n-1}}^!(\mathcal{F}) \rightarrow \cdots \rightarrow f_{\mathcal{K}^0}^!(\mathcal{F})),$$

where the first term is in degree $-n$, the final term is in degree 0, and $\mathbb{Q}_X \rightarrow \mathcal{K}$ is the finite (length n) soft resolution as given before. By definition,

$$\omega_X^\bullet = f^!(\mathbb{Q}) \quad \text{when } Y = \text{pt}.$$

Proposition 5.1. $R\text{Hom}(Rf_!(\mathcal{G}), \mathcal{F}) \simeq R\text{Hom}(\mathcal{G}, f^!(\mathcal{F}))$.

Proof. See [KS]. □

Warning! There is a condition on defining $f^!$: X and Y must both be finite dimensional.

Definition 22. $\omega_{X/Y} := f^!(\mathbb{Q}_Y)$.

5.3.1. *Topological submersions.* We saw (Poincaré Duality) that something nice happened with ω_X for X a manifold. What is a similarly nice situation here?

Definition 23. $f : X \rightarrow Y$ is a *topological submersion of relative dimension d* if for all $x \in X$ there exists open $U \subset X$ with $x \in U$, such that

$$\begin{array}{ccc} U & \xrightarrow{\cong} & f(U) \times \mathbb{R}^d \\ & \searrow & \swarrow \\ & f(U) & \end{array}$$

and $f(U)$ is open in Y .

Remark This is strictly stronger than just having manifolds for fibres.

Example 50. $\mathbb{R} \xrightarrow{x^2} \mathbb{R}$ is **not** a topological submersion (it fails at 0).

Proposition 5.2. If f is a topological submersion of relative dimension d , then

$$\begin{aligned} \mathcal{H}^{-d}(\omega_{X/Y}) &=: \mathcal{O}r_{X/Y} \text{ is a local system,} \\ \mathcal{H}^{-i}(\omega_{X/Y}) &= 0 \text{ for } i \neq d. \end{aligned}$$

We say that X/Y is *orientable* iff $\mathcal{O}r_{X/Y} \simeq \mathbb{Q}_X$. In that case,

$$f^!(-) \simeq f^*(-)[d].$$

In general: for any f ,

$$f^!(-) \simeq f^*(-) \otimes \omega_{X/Y}.$$

6. THE 6-FUNCTOR FORMALISM.

We have functors Rf_* , $Rf_!$, f^* , $f^!$, $- \otimes_{\mathbb{Q}} -$, $R\mathcal{H}om(-, -)$. These give rise to 4 kinds of (co)homology.

- (1) $\underbrace{H^*(X; \mathbb{Q})}_{H^*(X)} = Rp_*p^*(\mathbb{Q})$ (ordinary cohomology)
- (2) $H_c^*(X) = Rp_!p^*(\mathbb{Q})$ (compactly supported cohomology)

$$(3) H_{-*}^{\text{BM}}(X) = Rp_* \underbrace{p^!}_{\omega_X}(\mathbb{Q}) \text{ (Borel-Moore homology)}$$

$$(4) H_{-*}(X) = Rp_! p^!(\mathbb{Q}) \text{ (ordinary homology)}$$

BM homology and ordinary homology use *Verdier duality*. One way of thinking about this – Verdier duality gives a way to build a *cosheaf* from a sheaf, and we take *homology* of a cosheaf.

Unless explicitly stated we assume X is locally compact and finite dimensional.

6.1. Functoriality from adjunctions. $f : X \rightarrow Y$ gives a unit map

$$\begin{aligned} 1_{D^+(Y)} &\longrightarrow Rf_* f^*, \\ \mathbb{Q}_Y &\longmapsto Rf_*(\mathbb{Q}(X)) \end{aligned}$$

which gives a map

$$R\Gamma(\mathbb{Q}_Y) = H^*(Y) \rightarrow H^*(X) = \underbrace{R(p_Y)_* Rf_*(\mathbb{Q}_X)}_{R(p_X)_*}$$

where

$$\begin{array}{ccc} X & & Y \\ & \searrow p_X & \swarrow p_Y \\ & \text{pt} & \end{array}$$

Similarly, there is a counit map

$$\begin{aligned} Rf_! f^! &\longrightarrow 1_{D^+(Y)} \\ Rf_! \underbrace{f^!}_{\omega_X}(\omega_Y) &\longmapsto \omega_Y \end{aligned}$$

Applying $R(p_Y)_!$ gives

$$H_{-*}(X) = R(p_Y)_!(Rf_!(\omega_X)) \rightarrow R(p_Y)_!(\omega_Y) = H_{-*}(Y).$$

I.e.:

- H^* is contravariant.
- H_* is covariant.
- H_c^* :
 - For an open embedding $j : U \hookrightarrow X$, $j^! \simeq j^*$, i.e. j^* is right adjoint to $j_!$, and so H_c^* is covariant.
 - For a proper map $f : X \rightarrow Y$, $f_! = f_*$, and so H_c^* is contravariant.
- H_*^{BM} is essentially opposite to H_c^* .

If $f : X \rightarrow Y$ is a topological submersion of relative dimension d , and

$$\mathcal{O}r_{X/Y} (= \mathcal{H}^{-d}(\omega_{X/Y})) \simeq \mathbb{Q}_X,$$

then

$$f^!(-) \simeq f^*(-)[d] \quad \text{and so} \quad f^![-d] \simeq f^*.$$

Thus,

$$1_{D^+(Y)} \rightarrow Rf_* f^* \simeq Rf_* f^![-d].$$

Apply to ω_Y :

$$\omega_Y \rightarrow Rf_* \underbrace{f^!}_{\omega_X}(\omega_Y)[-d] = Rf_*(\omega_X)[-d],$$

so applying $R(p_Y)_*$, we have

$$R(p_Y)_*(\omega_Y) \rightarrow \underbrace{R(p_Y)_* Rf_*(\omega_X)[-d]}_{R(p_X)_*}$$

and so taking cohomology gives

$$H_{-*}^{\text{BM}}(Y) \rightarrow H_{-(*)+d}^{\text{BM}}(X).$$

Example 51. If $Y = \text{pt}$ (i.e. X is an orientable manifold),

$$\begin{aligned} \mathbb{Q} = H_0^{\text{BM}}(\text{pt}) &\longrightarrow H_d^{\text{BM}}(X) && \text{(we are using } \textit{homological} \text{ grading here)} \\ 1 &\longmapsto [X] && \text{(the fundamental class)} \end{aligned}$$

So we should think of this map as relating to some *relative* fundamental class.

Note that for an open-closed decomposition $j : U \hookrightarrow X \leftarrow Z = X - U : i$, U open, we have an exact sequence of functors

$$0 \rightarrow j_!j^* \rightarrow 1_{\text{Sh}(X)} \rightarrow i_!i^* \rightarrow 0$$

on the level of abelian categories; so exact sequences of sheaves for any $\mathcal{F} \in \text{Sh}(X)$

$$0 \rightarrow \underbrace{j_!j^*}_{j_!j^!}(\mathcal{F}) \xrightarrow{\text{counit}} \mathcal{F} \xrightarrow{\text{unit}} \underbrace{i_!i^*}_{i_*i^*}(\mathcal{F}) \rightarrow 0.$$

Now apply $R(p_X)_!(-)$ to get a SES of complexes, thus a LES in compactly supported cohomology.

Example 52. If $\mathcal{F} = \mathbb{Q}_X$ we have

$$\begin{array}{c} \hookrightarrow H_c^{*+1}(U) \longrightarrow \dots \\ \longleftarrow \phantom{H_c^{*+1}(U)} \\ H_c^*(U) \longrightarrow H_c^*(X) \longrightarrow H_c^*(Z) \end{array}$$

This gives rise to a *distinguished triangle* in $D(X)$,

$$Rj_!j^* \rightarrow 1_{D(X)} \rightarrow Ri_!i^* \xrightarrow{+1} \dots$$

Note that if we take $R(p_X)_*$ we have a different interpretation,

$$\underbrace{H^*(X, Z)}_{\text{relative cohomology}} \longrightarrow H^*(X) \longrightarrow H^*(Z).$$

So:

- H^* of the decomposition deals with relative cohomology.
- $H_c^*(X)$ is built up out of $H_c^*(U)$ and $H_c^*(Z)$.

We also have another distinguished triangle,

$$Ri_*i^!(\mathcal{F}) \rightarrow \mathcal{F} \rightarrow Rj_*j^!(\mathcal{F}) \xrightarrow{+1} \dots$$

which gives rise to a LES in Borel-Moore homology

$$H_*^{\text{BM}}(Z) \rightarrow H_*^{\text{BM}}(X) \rightarrow H_*^{\text{BM}}(U).$$

Definition 24. The *Euler characteristic* of X is

$$\chi(X) = \sum (-1)^i \dim(H_c^i(X)).$$

Note that using H_c^* means that by the H_c^* LES,

$$\chi(X) = \chi(U) + \chi(Z),$$

i.e. additivity of the Euler characteristic under the open-closed decomposition $U \hookrightarrow X \leftarrow Z$.

Proposition 6.1. *If $i : Z \hookrightarrow X$ is a closed submanifold of codimension d , and the normal bundle $N_{Z/X}$ is orientable, then*

$$i^!(\mathbb{Q}_X) \simeq \mathbb{Q}_Z[-d].$$

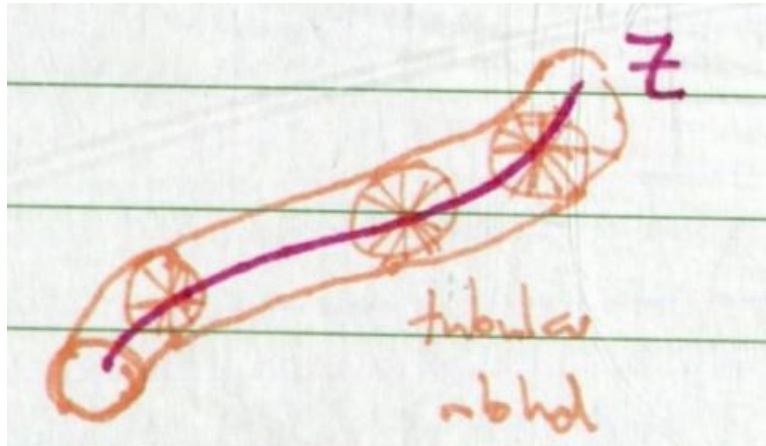
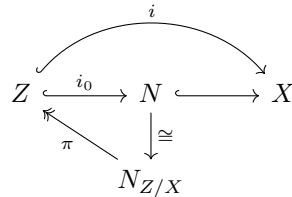


FIGURE 22. Tubular neighbourhood N of Z in X .

Proof. Let N be a tubular neighbourhood of Z in X as in Figure 22. Then



π is a topological submersion which is orientable. So $i^!(\mathbb{Q}_X) = i_0^!(\mathbb{Q}_N)$, and we have reduced to working on a vector bundle.

$$i_0^!(\mathbb{Q}_N) = i_0^!(\pi_*\mathbb{Q}_Z) = i_0^!\pi^!\mathbb{Q}_Z[-d] = \mathbb{Q}_Z[-d]$$

since $i_0^!\pi^! = \text{id}$, as i_0 is a section of π . Thus,

$$i^!(\mathbb{Q}_X) = \mathbb{Q}_Z[-d].$$

□

This leads to the following:

$$\begin{array}{ccc}
 i_!i^!\mathbb{Q}_X & \longrightarrow & \mathbb{Q}_X \\
 \parallel & & \\
 i_*\mathbb{Q}_Z[-d] & \longrightarrow & \mathbb{Q}_X
 \end{array}$$

Now apply Rp_* to this to get a *Gysin map* (or *wrong way map*)

$$H^{*-d}(Z) \rightarrow H^*(X).$$

But we have the distinguished triangle given by

$$i_!i^!\mathbb{Q}_X \rightarrow \mathbb{Q}_X \rightarrow j_*j^*\mathbb{Q}_X,$$

which gives rise to a Gysin LES

$$H^{*-d}(Z) \rightarrow H^*(X) \rightarrow H^*(U) \xrightarrow{+1} \dots$$

6.2. Base change. Suppose we have the cartesian square of a fibre product

$$\begin{array}{ccc}
 X \times_Z Y & \xrightarrow{\tilde{f}} & Y \\
 \downarrow \tilde{g} & & \downarrow g \\
 X & \xrightarrow{f} & Z
 \end{array}$$

Then:

- (1) $g^* f_! \simeq \tilde{f}_! \tilde{g}^* : \text{Sh}(X) \rightarrow \text{Sh}(Y)$ on the level of abelian categories; there is thus also the derived version $g^* Rf_! \simeq R\tilde{f}_! \tilde{g}^*$.
- (2) $g^! Rf_* \simeq Rf_* \tilde{g}^!$.

Example 53. $Y = \text{pt} \xrightarrow{x} X$ gives

$$Rf_!(\mathcal{F})_x = R\Gamma_c(f^{-1}(x); \mathcal{F}).$$

Note:

- If f is proper, $f_* = f_!$.
- If f is an open embedding, $f^! = f^*$.
- If f is a topological submersion, $f^! \simeq f^*[d]$.

So in these (and other) cases we get interesting base change results.

7. NEARBY AND VANISHING CYCLES.

Want to study the topology of singular varieties, e.g.,

$$X_0 = f^{-1}(0), \text{ where } f : X \rightarrow \mathbb{C} \text{ is a proper holomorphic map.}$$

Here X is a (smooth) complex manifold. Think of X as a parametrized collection of varieties (the fibres), all compact since f is proper. Some fibres, such as X_0 , may be singular – see Figure 23 for an example.

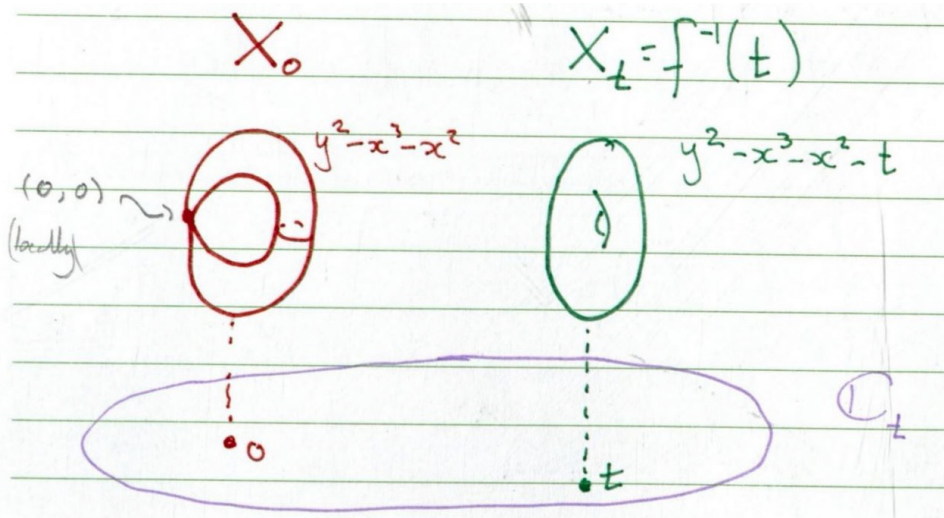


FIGURE 23. Family over \mathbb{C} with singular fibre at 0.

Assume $0 \in \mathbb{C}$ is an (isolated) singular value, i.e. X_0 is singular. Then $f|_{f^{-1}(\Delta^*)}$ is a submersion, where $\Delta \subset \mathbb{C}$ is a small disk and $\Delta^* = \Delta - \{0\}$.

Example 54. $f(x, y) = y^2 - x^3 - x^2$ has partial derivatives

$$\frac{\partial f}{\partial x} = 3x^2 - 2x, \quad \frac{\partial f}{\partial y} = 2y,$$

so df is onto *except* for at $(x, y) = (0, 0)$; this is the pinch point.

For f proper, Ehresmann's theorem implies that $f|_{f^{-1}(\Delta^*)}$ is a locally trivial fibre bundle, i.e. for all $t \in \Delta^*$, there exists a neighbourhood U of t such that there is a diffeomorphism

$$\begin{array}{ccc} f^{-1}(U) & \xrightarrow{\cong} & X_t \times U \\ & \searrow & \swarrow \\ & U & \end{array}$$

Let's think about $\mathcal{H}^i := R^i f_*(\mathbb{Q}_X)$. Recall that the stalk

$$\mathcal{H}_t^i = H^i(X_t) \quad (\text{this equality uses } \textit{proper} \text{ base change}).$$

$\mathcal{H}^i|_{\Delta^*}$ is a locally constant sheaf, so there is an automorphism

$$T : \mathcal{H}_{t_1}^i \xrightarrow{\cong} \mathcal{H}_{t_1}^i,$$

where $t_1 \in \Delta^*$ is a choice of basepoint. T comes from a geometric monodromy (from Ehresmann's theorem)

$$X_{t_1} \xrightarrow{\cong} X_{t_1}.$$

Choosing a path from t to 0 and flowing along it, we also obtain a *specialisation map*

$$r_t : X_t \rightarrow X_0.$$

This induces

$$H^*(X_0) \rightarrow H^*(X_t)$$

via the restriction map

$$\mathcal{H}_0^i = \mathcal{H}^i(U) \rightarrow \mathcal{H}^i(V) = \mathcal{H}_t^i$$

where U, V are as in Figure 24.

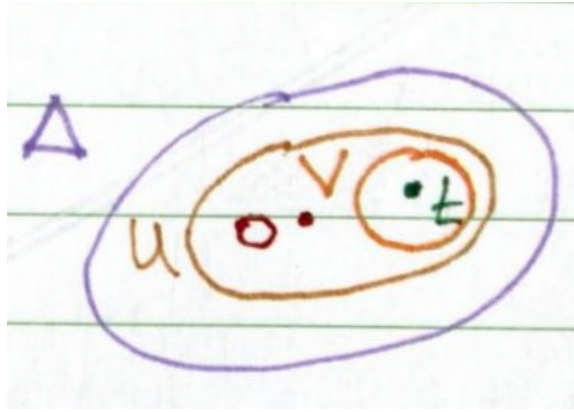


FIGURE 24. Restriction to an open away from the singular point.

Write $r \equiv r_t$ and define

$$\psi_f := Rr_*(\mathbb{Q}_{X_t}),$$

which, up to a shift, is the same as

$$\psi_f^! := Rr_*(\omega_{X_t}).$$

So we have a complex of sheaves $\psi_f \in D^+(X_0)$, and

$$H^*(X_0; \psi_f) = H^*(X_t).$$

Similarly,

$$H^*(X_0; \psi_f^!) = H_*^{\text{BM}}(X_t).$$

We can also look at stalks. Consider the zoomed in picture around the singular fibre (Figure 25).

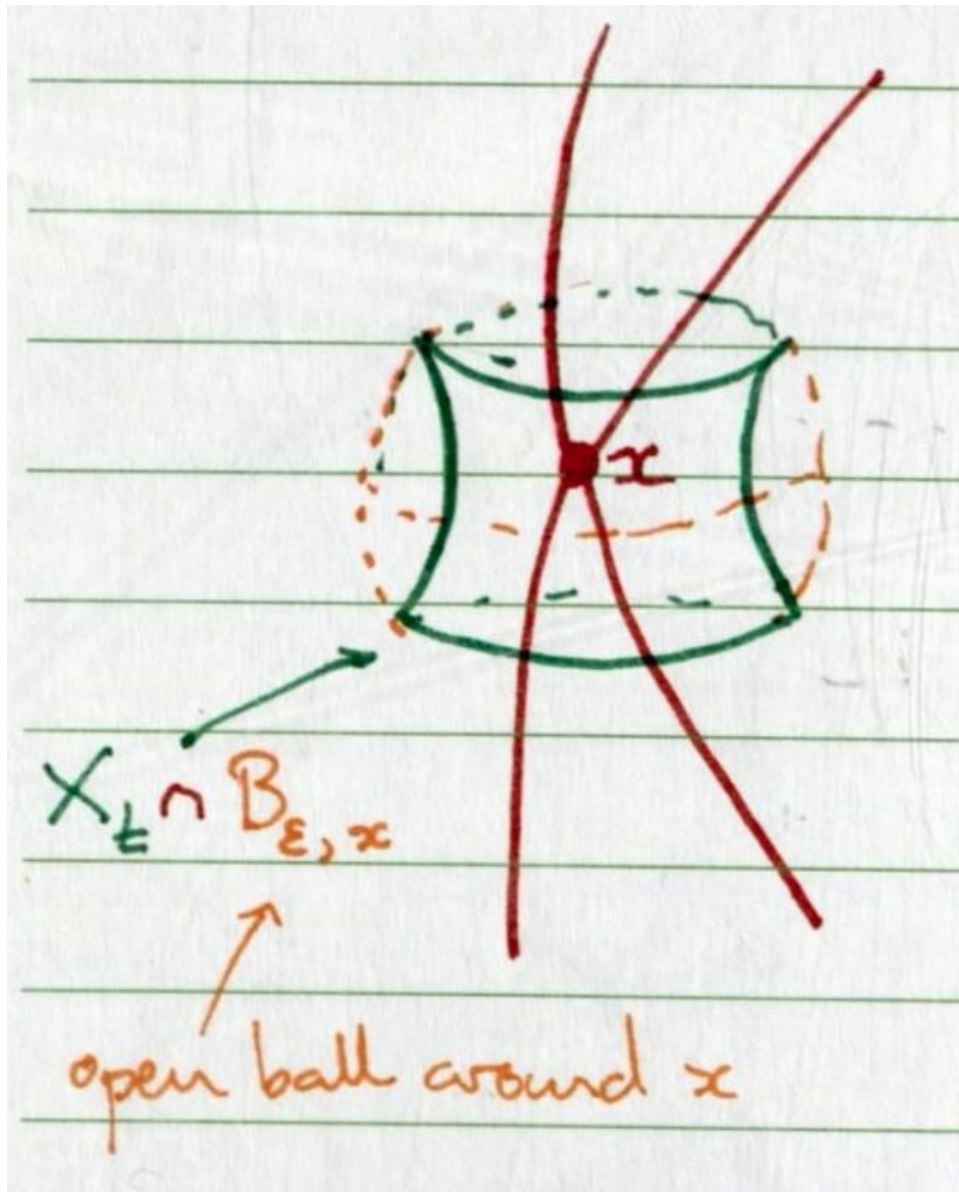


FIGURE 25. Milnor fibre around a singular point.

Then

$$(\psi_f)_x = H^*(\text{Mil}_{f,x}),$$

where the *Milnor fibre* is

$$\text{Mil}_{f,x} = B_{x,\epsilon} \cap X_t$$

where $\epsilon > |t| > 0$ are small enough, and $B_{x,\epsilon}$ is a ball of radius ϵ around x .

Why? Unpacking definitions, using that r is proper, and using base change,

$$(\psi_f)_x = H^*(r^{-1}(x));$$

then finally observe that $r^{-1}(x)$ is the Milnor fibre up to homotopy (compact core of Milnor fibre).

So ψ_f is a sheaf on X_0 that tells us about the cohomology of nearby fibres.

If $x \in X_0$ is nonsingular, $r^{-1}(x)$ is a single point, so that

$$(\psi_f)_x \cong H^*(r^{-1}(x)) \cong \mathbb{Q}.$$

I.e. the Milnor fibre $\text{Mil}_{f,x}$ is contractible if x is nonsingular.

The monodromy map gives us a map of sheaves

$$T : \psi_f \rightarrow \psi_f.$$

If we take

$$X \cap B_{x,\epsilon} \rightarrow \Delta_\epsilon := f(X \cap B_{x,\epsilon}),$$

then over Δ_ϵ^* we have a fibre bundle with generic fibre $\text{Mil}_{f,x}$. We call this the *Milnor fibration*. See [M] for an original reference.

Facts: If $x \in X_0$ is an *isolated* singularity (no matter how terrible),

$$\text{Mil}_{f,x} \simeq \bigvee_{\mu(x)} S^n,$$

the wedge of $\mu(x)$ n -spheres where $n = \dim_{\mathbb{C}}(X_0)$. We call $\mu(x)$ the *Milnor number*.

Define ϕ_f as follows: there is a unit map

$$\mathbb{Q}_{X_0} \rightarrow \psi_f = R(r_t)_*(r_t^* \mathbb{Q}_{X_0})$$

and this corresponds to the specialisation map

$$H^*(X_0) \xrightarrow{\text{sp}} H^*(X_t).$$

Define $\phi_f = \text{cone}(\text{sp})$. I.e. we have an exact triangle in $D^+(X_0)$

$$\mathbb{Q}_{X_0} \rightarrow \psi_f \rightarrow \phi_f \xrightarrow{+1} \dots$$

So there is a LES in cohomology

$$H^*(X_0) \rightarrow H^*(X_t) \rightarrow H^*(X_0; \phi_f),$$

as well as a local version

$$H^*(X_0 \cap B_{\epsilon,x}) \rightarrow H^*(\text{Mil}_{f,x}) \rightarrow H^*(\phi_{f,x}).$$

Alternatively, we could use $\psi^!$ to get

$$\begin{array}{ccccc}
 \phi_f^! & \xrightarrow{\hspace{10em}} & \psi_f^! & \xrightarrow{\hspace{10em}} & \omega_{X_0} \\
 \uparrow & & \uparrow & & \uparrow \\
 \text{cone shifted by 1} & & \text{Borel-Moore chains on nearby fibre} & & \text{Borel-Moore chains on singular fibre}
 \end{array}$$

so $(\phi_f^!)_x$ are the cycles in $\text{Mil}_{f,x}$ which go to 0 under specialisation. We call this the *vanishing cycles sheaf*.

Example 55. If X has isolated singularities, $\phi_f^!$ must be a sum of skyscraper sheaves supported at the singular points,

$$\phi_f^! = \bigoplus_{x \in X_0} \mathbb{Q}_x^{\mu(x)}[+n],$$

where this is implicitly 0 for nonsingular x .

Example 56. Want to compute the Milnor fibration for our example $y^2 - x^3 - x^2$ at $0 \in \mathbb{C}^2$ (i.e. studying the collapse of the cylinders to a cone near 0). The Hessian is non-degenerate, so the Morse lemma (holomorphic version) tells us we can change coordinates to

$$f(u, v) = uv : \mathbb{C}^2 \rightarrow \mathbb{C}.$$

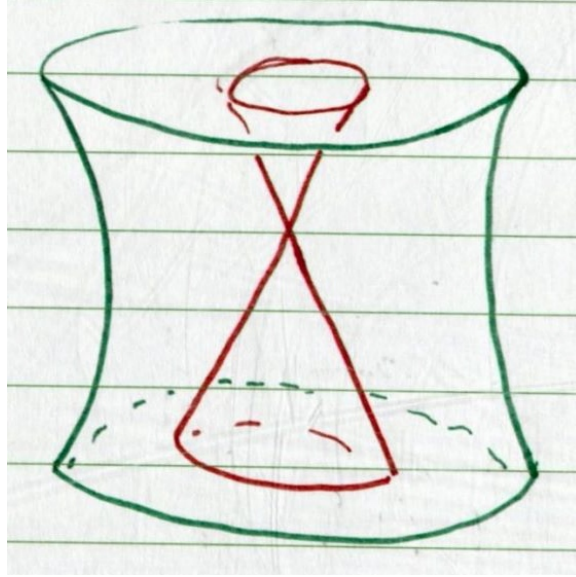


FIGURE 26. Picture of $f^{-1}(z)$ ($f(u, v) = uv$) around the singular point 0.

We want to compute the monodromy for $X_t \cong \mathbb{C}^\times$ for $t \neq 0$ – we make this identification via the map

$$z \mapsto \left(z, \frac{t}{z} \right).$$

We also have $X_0 = \mathbb{C} \amalg_0 \mathbb{C}$. Then flowing along a lift of $\frac{\partial}{\partial \theta}$ downstairs,

$$T_\theta : X_1 \rightarrow X_{e^{i\theta}}, \quad T_\theta(u, v) = \left(e^{\frac{i\theta}{2}} u, e^{\frac{i\theta}{2}} v \right)$$

is the parallel transport map. In particular,

$$\begin{aligned} T_{2\pi} : X_1 &\rightarrow X_1 \\ T_{2\pi}(u, v) &= (-u, -v) \end{aligned}$$

is the antipodal map. So the *local* monodromy is the identity, since on an odd-dimensional sphere the antipodal map is a rotation,

$$T : H^*(X_1^l) \xrightarrow{\text{id}} H^*(X_1^l).$$

What about the global monodromy? See Figure 27.

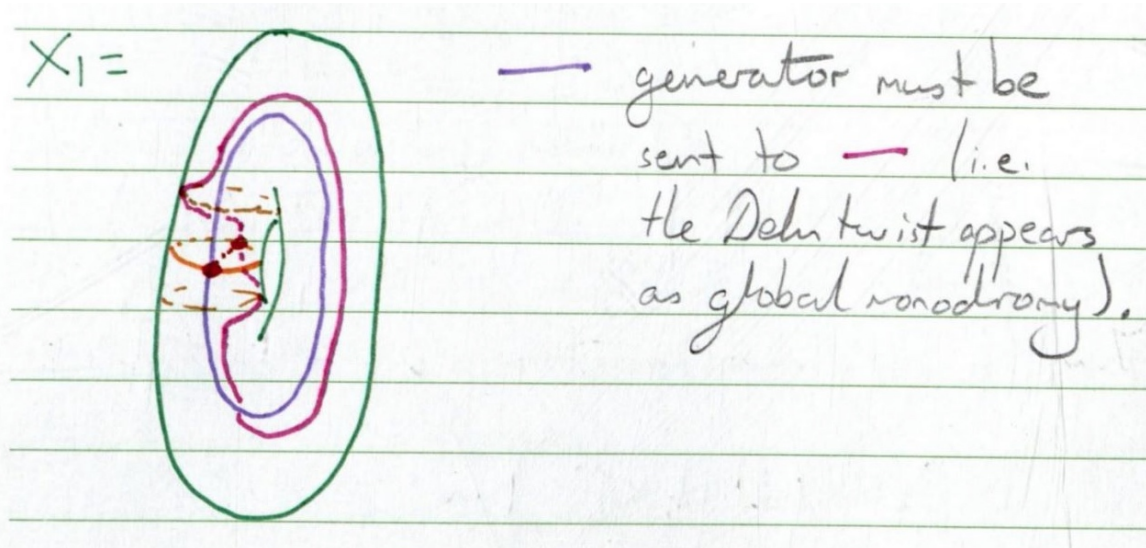


FIGURE 27. Global monodromy for X_1 .

8. A PREVIEW OF THE RIEMANN-HILBERT CORRESPONDENCE.

8.1. C^∞ **Riemann-Hilbert.** Let X be a C^∞ -manifold of dimension n . Consider the sheaf of rings \mathcal{C}_X^∞ on X . Then there is a correspondence

$$\begin{array}{ccc} \left\{ \begin{array}{c} \mathcal{C}_X^\infty\text{-vector bundles} \\ \text{on } X \end{array} \right\} & \longleftrightarrow & \left\{ \begin{array}{c} \text{Locally free sheaves} \\ \text{of } \mathcal{C}_X^\infty\text{-modules} \end{array} \right\} \\ (V \rightarrow X) & \longmapsto & \Gamma(-, V) \\ (V \mathcal{M} \rightarrow X) & \longleftarrow & \mathcal{M} \end{array}$$

We define the bottom map as follows. Given a locally free \mathcal{C}_X^∞ -module \mathcal{M} , the trivializations

$$\phi_i^\mathcal{M} : \mathcal{M}|_{U_i} \xrightarrow{\sim} (\mathcal{C}_{U_i}^\infty)^{\oplus r}$$

give rise to transition functions

$$c_{ij}^\mathcal{M} = \phi_i \circ \phi_j^{-1}|_{U_i \cap U_j} \in C^\infty(U_i \cap U_j, GL_n).$$

These can then be glued together to give a vector bundle

$$V\mathcal{M} = \frac{\coprod_i U_i \times \mathbb{C}^r}{\sim}$$

There is another correspondence

$$\begin{array}{ccc} \left\{ \begin{array}{c} \text{Locally constant} \\ \text{sheaves of} \\ \mathbb{C}\text{-vector spaces} \end{array} \right\} & \longleftrightarrow & \left\{ \begin{array}{c} \text{Vector bundles with} \\ \text{flat connection} \end{array} \right\} \\ \mathcal{F} & \longmapsto & (\mathcal{C}_X^\infty \otimes_{\mathbb{C}_X} \mathcal{F} = \mathcal{M}, d^\mathcal{M}(f \otimes s) = df \otimes s) \\ \ker(d^\mathcal{M}) & \longleftarrow & (\mathcal{M}, d^\mathcal{M}) \end{array}$$

Remark

- The data of the $c_{ij}^\mathcal{M}$ determines a class in $H^1(X; \mathcal{C}^\infty(-, GL_n))$.
- In the above, s is a local section of \mathcal{F} and f is a local section of \mathcal{C}_X^∞ .

- The data of a vector bundle with flat connection is equivalent to a class in $\check{H}^1(X, \underline{GL}_n)$ (locally constant transition functions).

Given a flat vector bundle $(\mathcal{M}, d^{\mathcal{M}})$, define

$$dR(\mathcal{M})^\bullet = \mathcal{M} \xrightarrow{d^{\mathcal{M}}} \mathcal{M} \otimes_{\mathcal{C}_X^\infty} \mathcal{A}_X^1 \xrightarrow{d^{\mathcal{M}}} \mathcal{M} \otimes_{\mathcal{C}_X^\infty} \mathcal{A}_X^2 \xrightarrow{d^{\mathcal{M}}} \cdots \xrightarrow{d^{\mathcal{M}}} \mathcal{M} \otimes_{\mathcal{C}_X^\infty} \mathcal{A}_X^n,$$

where \mathcal{A}_X^i are the smooth i -forms on X , and we extend $d^{\mathcal{M}}$ via the Leibniz rule.

Proposition 8.1. $0 \rightarrow \ker(d^{\mathcal{M}}) \rightarrow dR(\mathcal{M})^\bullet$ gives a quasi-isomorphism.

Proof. Can check exactness locally, and then this is immediately implied by the Poincaré lemma. □

Corollary 8.2. $H^*(X; \ker(d^{\mathcal{M}})) = H^*(\Gamma(dR(\mathcal{M})^\bullet)) = H_{dR}^*(\mathcal{M}, d^{\mathcal{M}})$.

Proof. Use that the sheaves $\mathcal{M} \otimes_{\mathcal{C}_X^\infty} \mathcal{A}_X^m$ are fine (thus soft, thus acyclic). □

8.2. Complex geometry. Now suppose X is a complex manifold, $\dim_{\mathbb{C}} X = n$. Write

- \mathcal{O}_X for the sheaf of holomorphic functions, and
- Ω_X^m for the sheaf of holomorphic m -forms.

We get a correspondence

$$\begin{array}{ccc} \left\{ \begin{array}{l} \text{Locally constant sheaves} \\ \text{of } \mathbb{C}\text{-vector spaces} \\ \text{(locally free } \mathbb{C}_X\text{-modules)} \end{array} \right\} & \longleftrightarrow & \left\{ \begin{array}{l} \text{Holomorphic vector bundles} \\ \text{with flat connection} \\ d^{\mathcal{M}} : \mathcal{M} \rightarrow \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^1 \end{array} \right\} \\ \mathcal{F} & \longmapsto & (\mathcal{O}_X \otimes_{\mathbb{C}_X} \mathcal{F} = \mathcal{M}, d^{\mathcal{M}}(f \otimes s) = \bar{\partial}f \otimes s) \\ \ker(d^{\mathcal{M}}) & \longleftarrow & (\mathcal{M}, d^{\mathcal{M}}) \end{array}$$

Remark \mathcal{O}_X -modules are not acyclic for $\Gamma(X; -)$.

Example 57. If $X \hookrightarrow \mathbb{C}\mathbb{P}^N$ is projective, then X is an algebraic variety, and

$$\text{Coherent } \mathcal{O}_X\text{-modules} \xrightarrow{\sim} \text{Coherent } \mathcal{O}_X^{\text{alg}}\text{-modules}$$

Example 58. If X is Stein, $X \hookrightarrow \mathbb{C}^N$, then coherent \mathcal{O}_X -modules are acyclic.

Definition 25. An \mathcal{O}_X -module \mathcal{M} is called *coherent* if

- (1) it is finitely generated as an \mathcal{O}_X -module, (i.e. for each $x \in X$ there exists a neighbourhood $U \ni x$ and $\mathcal{O}_U^{\oplus r} \rightarrow \mathcal{M}|_U$); and,
- (2) for each $U \subseteq X$ open and any

$$\phi : (\mathcal{O}_X|_U)^{\oplus r} \rightarrow \mathcal{M}|_U,$$

we have that $\ker(\phi)$ is finitely generated.

Theorem 8.3 (Oka). \mathcal{O}_X is coherent as a module over \mathcal{O}_X .

Exercise 8.1. Compare to the smooth case: \mathcal{C}_X^∞ is **not** coherent as a \mathcal{C}_X^∞ -module.

Hint: Consider multiplication by the function

$$f(x) = \begin{cases} e^{-\frac{1}{x^2}}, & x > 0, \\ 0, & x \leq 0. \end{cases}$$

Remark Coherent \mathcal{O}_X -modules are the smallest subcategory of sheaves which

- (1) contains vector bundles, and
- (2) is closed under finite \oplus , kernels and cokernels.

Note that f^* does not preserve \mathcal{O} -modules.

Example 59. Flat connections on $X = \mathbb{C}^\times$ (i.e. locally constant sheaves). Every holomorphic vector bundle on \mathbb{C}^\times is trivial, so

$$\left\{ \begin{array}{c} \text{holomorphic flat connections} \\ \text{on } \mathbb{C}^\times \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{c} \text{square matrices of holomorphic 1-forms} \\ A(z)dz \end{array} \right\}$$

$$d^A(s) = ds - Asdz \longleftarrow A(z)$$

where d^A is a connection on $\mathcal{O}_X^{\oplus r}$. We know that

$$\{\text{flat connections on } \mathbb{C}^\times\} \simeq \{\text{Reps of } \pi_1(\mathbb{C}^\times) \cong \mathbb{Z}\} \simeq \{\text{vector space with an automorphism}\}.$$

So how do we determine the monodromy automorphism? Take A to be 1×1 in what follows – in general the ideas below require us to consider the *path-ordered exponential*.

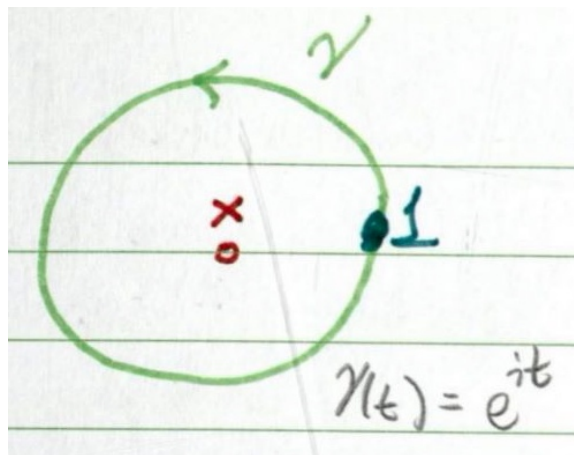


FIGURE 28. Choice of path in \mathbb{C}^\times for parallel transport.

Given a connection matrix A , let $s_0 \in \mathbb{C}^r$ be a section at 1. We want to find $s(t)$ such that $d^A(s) = 0$, i.e.

$$s'(t) = A(\gamma(t))\gamma'(t)s(t), \quad \text{and} \quad s(0) = s_0.$$

To solve this, write

$$\frac{s'}{s} = A(\gamma(t))\gamma'(t),$$

and observe¹ that the solution is given by

$$s(t) = \exp\left(\int_0^t A(\gamma(t))\gamma'(t)dt\right) \cdot s_0.$$

Hence the monodromy automorphism is

$$s(2\pi) = \exp\left(\oint_\gamma A dz\right) \cdot s_0.$$

¹One can motivate this solution by observing that the LHS is a log-derivative, so we expect naively to see

$$\log\left(\frac{s(t)}{s_0}\right) = \int_0^t A(\gamma(t))\gamma'(t)dt.$$

Theorem 8.4 (Cauchy). *The monodromy matrix is*

$$M(z) = \exp(\operatorname{Res}_0(A) \cdot 2\pi i).$$

I.e. we only need to look at connections of the form

$$B(z) = \frac{\operatorname{Res}_0(A(z))}{z}.$$

Exercise 8.2. It follows that every flat connection on \mathbb{C}^\times is equivalent to one of the form $d\frac{B}{z}$, B constant, i.e.

$$d\frac{B}{z} = d + \frac{B}{z}.$$

So, find an invertible matrix $G(z)$ such that

$$\frac{B}{z} = \pm G^{-1}AG \pm G^{-1}dG,$$

where working out the correct signs is part of the exercise.

9. CONSTRUCTIBLE SHEAVES.

We now wish to understand a more general class of sheaves.

Definition 26. A *partition* \mathcal{P} of a topological space X is a collection of disjoint, locally closed subsets of X , X_i , such that

$$\bigcup_i X_i = X.$$

Definition 27. A sheaf $\mathcal{F} \in \operatorname{Sh}(X; \mathbb{C})$ is called *constructible* (w.r.t. \mathcal{P}) if $\mathcal{F}|_{X_i}$ is a locally constant sheaf of finite rank.

Example 60. Let $f : X \rightarrow \Delta$ be a proper holomorphic map such that $f|_{f^{-1}(\Delta^*)}$ is a submersion. Then $\mathcal{H}^i = R^i f_*(\mathbb{C}_X)$ is a constructible sheaf on $\Delta = \Delta^* \cup \{0\}$.

Definition 28. A complex $\mathcal{F} \in D^+ \operatorname{Sh}(X; \mathbb{C})$ is called a *constructible complex* if $\mathcal{H}^i(\mathcal{F})$ is constructible for each i .

Example 61. Let $f : S^3 \rightarrow S^2$ be the Hopf fibration. $Rf_*(\mathbb{C}_{S^3})$ is a constructible complex of sheaves w.r.t. the trivial partition,

$$R^i f_*(\mathbb{C}_{S^3}) = \begin{cases} \mathbb{C}, & i = 0, 1, \\ 0, & \text{else.} \end{cases}$$

Recall that

$$Rf_*(\mathbb{C}_{S^3}) \not\cong \mathbb{C}_{S^2} \oplus \mathbb{C}_{S^2}[-1].$$

So,

$$D_{c,\emptyset}^+(S^2) \not\cong D^+(\operatorname{Sh}_{c,\emptyset}(S^2)),$$

where $D_{c,\emptyset}^+$ means the bounded derived category of constructible complexes with respect to the empty partition, and $\operatorname{Sh}_{c,\emptyset}$ means local systems.

Example 62. $X = \Delta = \Delta^* \cup \{0\}$. Let a partition be given by $\mathcal{P} = \{\Delta^*, \{0\}\}$, and choose nonzero $t \in \Delta$. What kind of data describes a constructible sheaf?

Let $\mathcal{F} \in \operatorname{Sh}_{c,\mathcal{P}}(\Delta)$, and let

$$V_0 = \mathcal{F}_0, \quad V_t = \mathcal{F}_t.$$

We can consider small open sets to determine \mathcal{F}_0 and \mathcal{F}_t ,

$$V_0 = \Gamma(U; \mathcal{F}) = \mathcal{F}(U)$$

$$V_t = \Gamma(V; \mathcal{F}) = \mathcal{F}(V)$$

where U and V are as shown in Figure 29.

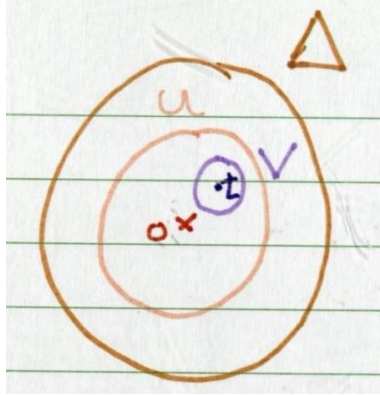


FIGURE 29. Obtaining a quiver from specialization maps.

So we get a quiver

$$\begin{array}{c}
 V_0 \\
 \text{(restriction map)} \alpha \downarrow \\
 V_t \\
 \uparrow \\
 \beta \text{ (monodromy)}
 \end{array}$$

with the relation

$$\beta\alpha = \alpha \quad (\text{sections in } V_t \text{ that extend to } V_0 \text{ must have trivial monodromy}).$$

Fact: This data (representation of a quiver with given relation) is *equivalent* to the data of a constructible sheaf.

10. PRELIMINARIES ON \mathcal{D} -MODULES.

Let X be a complex manifold. An \mathcal{O}_X -module is a sheaf of modules for the sheaf of rings \mathcal{O}_X .

Definition 29. A \mathcal{D} -module on X is an \mathcal{O}_X module \mathcal{M} together with **flat** connections

$$\begin{aligned}
 d^{\mathcal{M}} : \mathcal{M} &\rightarrow \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^1 \\
 d^{\mathcal{M}}(f \cdot m) &= df \otimes m + f \otimes d^{\mathcal{M}}(m), \quad f \in \mathcal{O}_X, m \in \mathcal{M}.
 \end{aligned}$$

Let \mathcal{T}_X be the sheaf of holomorphic vector fields. For each vector field $\xi \in \mathcal{T}_X$,

$$d_{\xi}^{\mathcal{M}} : \mathcal{M} \rightarrow \mathcal{M},$$

and flatness means

$$d_{\xi}^{\mathcal{M}} d_{\nu}^{\mathcal{M}} - d_{\nu}^{\mathcal{M}} d_{\xi}^{\mathcal{M}} = d_{[\xi, \nu]}^{\mathcal{M}} \quad \forall \xi, \nu \in \mathcal{T}_X.$$

Example 63. If x_1, \dots, x_n are local coordinates on X , then

$$\partial_i := \frac{\partial}{\partial x_i} \in \mathcal{T}_X, \quad [\partial_i, \partial_j] = 0,$$

and we have commuting operators

$$d_{\partial_i}^{\mathcal{M}} : \mathcal{M} \rightarrow \mathcal{M}.$$

For now on we write $\xi(m)$ or ξm instead of $d_{\xi}^{\mathcal{M}}(m)$.

Let \mathcal{D}_X denote the subsheaf of rings of $\mathcal{E}nd_{\mathbb{C}_X}(\mathcal{O}_X)$ generated by

- multiplication by $g \in \mathcal{O}_X$;
- \mathcal{I}_X acting by derivations.

\mathcal{D}_X is called the *ring of differential operators*.

In local coordinates, $P \in \mathcal{D}_X$ looks like

$$P = \sum_{\alpha} f_{\alpha}(x) \partial_{x_1}^{\alpha_1} \cdots \partial_{x_n}^{\alpha_n}.$$

Fact: A \mathcal{D} -module \mathcal{M} is the same thing as a \mathcal{D}_X -module.

Definition 30. A *stratification* of X is a partition whose strata are manifolds (+ other conditions not listed here).

Theorem 10.1. *There is an equivalence*

$$\left\{ \begin{array}{l} \text{Bounded constructible complexes for} \\ \text{some analytic stratification of } X \end{array} \right\} \xleftarrow[\sim]{\text{Riemann-Hilbert correspondence}} D^b \left\{ \begin{array}{l} \text{regular holonomic} \\ \mathcal{D}_X\text{-modules} \end{array} \right\}$$

$$dR(\mathcal{M}) \longleftarrow \mathcal{M}$$

Sitting inside of these categories we have

$$\begin{array}{ccc} D_c(X; \mathbb{C}) & \longleftrightarrow & D^b(\mathcal{D}_X\text{-mod}^{rh}) \\ \uparrow & & \uparrow \\ \text{Perv}(X; \mathbb{C}) & \xrightarrow{\sim} & \mathcal{D}_X\text{-mod}^{rh} \end{array}$$

where the bottom left category is the category of perverse sheaves.

We would like to understand this correspondence.

10.1. Differential equations. A (linear) differential operator on X is

$$Pu = 0 \quad \text{where } P \in \mathcal{D}_X.$$

Given $P \in \mathcal{D}_X$, define

$$\mathcal{M}_P = \mathcal{D}_X / \mathcal{D}_X \cdot P, \quad \text{a left } \mathcal{D}_X\text{-module.}$$

Warning! \mathcal{D}_X is non-commutative, so there is a distinction between right and left modules.

\mathcal{M}_P represents the following functor,

$$\mathcal{S} \mapsto \{u \in \mathcal{S} \mid Pu = 0\};$$

\mathcal{S} is thought of as a space of functions in which we might look for solutions. Or, more specifically, \mathcal{S} is some space of functions on X which is a \mathcal{D}_X -module.

Example 64. $\mathcal{O}_X, \mathcal{S}_X$ the space of Schwarz functions, Sobolev spaces, etc.

Then

$$\text{Hom}_{\mathcal{D}_X}(\mathcal{M}_P, \mathcal{S}) = \{u \in \mathcal{S} \mid Pu = 0\}.$$

Example 65. $X = \mathbb{C}$, coordinate z .

- (1) $P = \partial_z$ gives the left \mathcal{D} -module

$$\mathcal{M}_P = \mathcal{D}_X / \mathcal{D}_X \cdot \partial_z = \mathcal{O}_X.$$

- (2) For $P = z$, what is the \mathcal{D} -module $\mathcal{M}_P = \mathcal{D}_X/\mathcal{D}_X \cdot z$? Note that the \mathcal{D} -modules \mathcal{M}_P are cyclic; i.e. generated as a \mathcal{D}_X -module by one section u , the image of 1 in the quotient. So we can think of the module as

$$\mathcal{M}_P = \mathcal{D}_X \cdot u.$$

For instance, for the prior example, $\mathcal{M}_{\partial_z} = \mathcal{D}_X \cdot 1_X$, $\partial_z(1_X) = 0$. What about for this example? We have

$$\mathcal{M}_z = \mathcal{D}_X \cdot u, \quad z \cdot u = 0.$$

We call this

$$u = \delta(z), \quad \text{the } \delta\text{-function.}$$

For us, $\delta(z)$ is just the name for the generator of \mathcal{M}_z , which satisfies $z \cdot \delta(z) = 0$. You can make sense of this with distributions if you want, but we won't have to in this course.

Then \mathcal{M}_z will be generated by

$$\partial_z \delta(z) = \delta'(z), \dots, \partial_z^n \delta(z) = \delta^{(n)}(z), \dots$$

So

$$\mathcal{M}_z = \mathbb{C}\langle \delta, \delta', \dots \rangle \cong \mathbb{C}[\partial_z],$$

i.e. the \mathcal{D} -module of *constant coefficient differential operators*.

- (3) $\mathcal{D}_X \cdot z^\lambda$ with $\lambda \in \mathbb{C}$. We won't worry (yet) about troubles with solutions being multivalued. The object z^λ solves a differential equation,

$$\begin{aligned} \partial_z(z^\lambda) &= \lambda z^{\lambda-1} \\ z\partial_z(z^\lambda) &= \lambda z^\lambda \\ \Rightarrow (z\partial_z - \lambda)z^\lambda &= 0. \end{aligned}$$

If $\lambda \notin \mathbb{Z}$, then

$$\mathcal{D}_X \cdot z^\lambda = \mathcal{D}_X/\mathcal{D}_X(z\partial_z - \lambda).$$

On \mathbb{C}^\times this gives a flat connection

$$d^{\mathcal{M}} = d + \frac{\lambda}{z} dz$$

with monodromy $e^{2\pi i \lambda}$. Why?

$$\partial_z(f(z)z^\lambda) = \frac{\partial f}{\partial z} z^\lambda + \frac{\lambda}{z} dz(z^\lambda).$$

One can compute that the stalk at 0 is

$$(\mathcal{D}_X z^\lambda)_0 = 0.$$

10.2. The ring \mathcal{D}_X . We now wish to study the ring structure on \mathcal{D}_X ; recall from above that this is the sheaf \mathcal{D}_X on a complex manifold X ,

$$\mathcal{D}_X \subset \mathcal{E}nd_{\mathbb{C}_X}(\mathcal{O}_X).$$

which is generated by $\mathcal{O}_X \subset \mathcal{E}nd_{\mathbb{C}_X}(\mathcal{O}_X)$ acting by multiplication, and $\mathcal{T}_X = \text{Der}(\mathcal{O}_X, \mathcal{O}_X) \subset \mathcal{E}nd_{\mathbb{C}_X}(\mathcal{O}_X)$.

Note: If $\theta \in \mathcal{T}_X$, $f \in \mathcal{O}_X$, let $[\theta, f] = \theta f - f\theta$. Then

$$[\theta, f](g) = \theta(fg) - f\theta(g) = \theta(f)g + f\theta(g) - f\theta(g) = \theta(f)g.$$

So

$$[\theta, f] = \theta(f) \in \mathcal{O}_X \subset \mathcal{D}_X.$$

Definition 31. We say $P \in \mathcal{D}_X$ has *order* $\leq m$ if P can be written as a sum of

$$\theta_1 \cdots \theta_l, \quad \theta_i \in \mathcal{T}_X, \quad l \leq m.$$

Define

$$\mathcal{D}_X(m) = \{\text{differential operators of order } \leq m\}.$$

Proposition 10.2. $[\mathcal{D}_X(m), \mathcal{D}_X(0)] \subset \mathcal{D}_X(m-1)$. Observe that $\mathcal{D}_X(0) = \mathcal{O}_X$.

Definition 32 (Alternative definition due to Grothendieck). Given a commutative \mathbb{C} -algebra A , define a \mathbb{C} -algebra $\mathcal{D}_A \subseteq \text{End}_{\mathbb{C}}(A)$ as follows:

- $\mathcal{D}_A(0) := A \subseteq \text{End}_{\mathbb{C}}(A)$
- $\mathcal{D}_A(m) := \{P \in \text{End}_{\mathbb{C}}(A) \mid [P, f] \in \mathcal{D}_A(m-1) \forall f \in A = \mathcal{D}_A(0)\}$

Remark This definition makes sense for a sheaf of commutative \mathbb{C}_X -algebras \mathcal{A} .

Example 66. If $\mathcal{A} = \mathcal{O}_X$ then $\mathcal{D}_{\mathcal{O}_X} = \mathcal{D}_X$. This is not hard, but not trivial. E.g. for $m = 1$ we suppose $P : \mathcal{O}_X \rightarrow \mathcal{O}_X$ has the property $[P, f] \in \mathcal{O}_X$. Then we claim that $P - P(1)$ is a derivation.

Exercise 10.1. Prove the claim of the example.

Example 67. If A is the coordinate ring of a smooth affine algebraic variety $\text{Spec}(A)$, we call \mathcal{D}_A the ring of algebraic differential operators.

More generally:

- If X^{alg} is a smooth variety over \mathbb{C} , then $\mathcal{D}_{X^{\text{alg}}}$ is a sheaf of rings in the Zariski topology.
- If X^{alg} is smooth, then $\mathcal{D}_{X^{\text{alg}}}$ is generated by $\mathcal{O}_{X^{\text{alg}}}$ and $\mathcal{I}_{X^{\text{alg}}}$.
- **But** if X is singular this is no longer true in general.

Example 68. Let $A = \mathbb{C}[x_1, \dots, x_n]$. Then

$$\mathcal{D}_{\mathbb{C}[x_1, \dots, x_n]} =: W_n, \quad \text{the Weyl algebra.}$$

This is a ring generated by symbols

$$x_1, \dots, x_n, \partial_1, \dots, \partial_n,$$

subject to the relations

$$[x_i, x_j] = 0, \quad [\partial_i, \partial_j] = 0, \quad [\partial_i, x_j] = \delta_{ij}.$$

Example 69. Let

$$A = \mathcal{O}_n := (\mathcal{O}_{\mathbb{C}^n})_0 =: \mathbb{C}\{\{x_1, \dots, x_n\}\},$$

(think of as power series with positive radius of convergence). Define $\mathcal{D}_n := \mathcal{D}_{\mathcal{O}_n}$, and note that at a point $x \in X$ a complex manifold,

$$(\mathcal{D}_X)_x \cong \mathcal{D}_n \quad \text{after picking coordinates around } x.$$

Remark There is a PBW type theorem for \mathcal{D}_n ,

$$\mathcal{D}_n = \bigoplus_{\alpha} \mathcal{O}_n \cdot \underbrace{\partial_1^{\alpha_1} \dots \partial_n^{\alpha_n}}_{\partial^{\alpha}, \alpha = (\alpha_1, \dots, \alpha_n)},$$

where $\partial_i = \frac{\partial}{\partial x_i}$. I.e. any $P \in \mathcal{D}_n$ has a *unique* expression of the form

$$P = \sum f_{\alpha}(x) \partial^{\alpha}.$$

The *order* of P as a differential operator is the weight

$$|\alpha| = \alpha_1 + \dots + \alpha_n.$$

Proposition 10.3. (1) \mathcal{D}_n is a filtered ring,

$$\mathcal{D}_n(0) \subseteq \mathcal{D}_n(1) \subseteq \mathcal{D}_n(2) \subseteq \dots, \quad \text{and} \quad \mathcal{D}_n(m)\mathcal{D}_n(k) \subseteq \mathcal{D}_n(m+k).$$

Note that this is **not** graded, as the bracket can reduce the degree, e.g. $[\partial_x, x] = 1$.

(2) The associated graded ring of \mathcal{D}_n is

$$\text{Gr}(\mathcal{D}_n) := \bigoplus_{m=0}^{\infty} \mathcal{D}_n(m) / \mathcal{D}_n(m-1).$$

The symbol maps are the quotients

$$\sigma_m : \mathcal{D}_n(m) \rightarrow \mathcal{D}_n(m) / \mathcal{D}_n(m-1) =: \text{Gr}(\mathcal{D}_n)(m).$$

This is graded,

$$\text{Gr}(\mathcal{D}_n)(m) \cdot \text{Gr}(\mathcal{D}_n)(k) \subseteq \text{Gr}(\mathcal{D}_n)(m+k).$$

Note that $\sigma_1(x\partial_x) = \sigma_1(\partial_x x)$, for instance. Then we have that

$$\text{Gr}(\mathcal{D}_n) = \mathcal{O}_n[\xi_1, \dots, \xi_n],$$

where $\xi_i = \sigma_1(\partial_i)$. Observe that this is a commutative ring, which is holomorphic in \mathbb{C}^n and polynomial in the dual space $(\mathbb{C}^n)^*$.

(3) Define $\mathcal{D}_n^{\text{op}}$ to have the same underlying vector space as \mathcal{D}_n , but with multiplication rule

$$P \cdot^{\text{op}} Q := QP, \quad P, Q \in \mathcal{D}_n^{\text{op}}.$$

Then we have $\mathcal{D}_n \cong \mathcal{D}_n^{\text{op}}$ via the map

$$\begin{aligned} f \in \mathcal{O}_n &\xrightarrow{a} f \in \mathcal{O}_n \\ \partial_i &\xrightarrow{a} -\partial_i \end{aligned}$$

so that

$$\sum_{\alpha} f_{\alpha}(x) \partial^{\alpha} \mapsto \sum_{\alpha} (-1)^{|\alpha|} \partial^{\alpha} f_{\alpha}(x).$$

\mathcal{D}_X is also a filtered sheaf of rings,

$$\begin{array}{ccccc} \text{Gr}(\mathcal{D}_X) & \xlongequal{\quad} & \text{Sym}_{\mathcal{O}_X}(\mathcal{T}_X) & \xleftarrow{\quad} & \pi_* \mathcal{O}_{T^*X} \\ \uparrow \wr & & \uparrow & & \uparrow \wr \\ \text{sheaf of rings} & & \text{holomorphic functions on } T^*X & & \text{holomorphic functions on } T^*X \\ & & \text{which are polynomial in the fibres} & & \end{array}$$

where $\pi : T^*X \rightarrow X$.

To look up (if interested): There is also a ring \mathcal{E}_X of *micro differential operators*.

Proof. We prove the second claim of the proposition. Why is the associated graded commutative?

$$P \in \mathcal{D}_n(m), Q \in \mathcal{D}_n(k) \quad \text{implies} \quad [P, Q] \in \mathcal{D}_n(m+k-1).$$

Thus,

$$\sigma_m(P)\sigma_k(Q) - \sigma_k(Q)\sigma_m(P) = \sigma_{m+k}([P, Q]) = 0.$$

Then the PBW theorem implies that

$$\mathcal{D}_n(m)/\mathcal{D}_n(m-1) \cong \bigoplus_{|\alpha|=m} \mathcal{O}_n \cdot \xi_1^{\alpha_1} \cdots \xi_n^{\alpha_n}.$$

□

With respect to the third part of the proposition: first recall that left A^{op} -modules are the same thing as right A -modules. In general (e.g. X a complex manifold), we have that \mathcal{O}_X is a left \mathcal{D}_X -module. We also have a holomorphic line bundle (locally trivial sheaf of \mathcal{O}_X -modules of rank 1), Ω_X^n .

Claim: Ω_X^n is naturally a right \mathcal{D}_X -module.

Motivation: Given $\eta \in \Omega_X^n$, $f \in \mathcal{O}_X$, and ignoring for the moment the fact that we are working with holomorphic top forms, consider the desired module structure

$$\int (\eta \cdot \theta) f = \int \eta(\theta(f)), \quad \theta \in \mathcal{T}_X.$$

I.e. we want to define $(\eta \cdot \theta)$ such that

$$(\eta \cdot \theta)(f) - \eta(\theta(f)) \text{ is exact.}$$

Definition 33. $\eta \cdot \theta = -\mathcal{L}_{\theta}(\eta)$, the Lie derivative on top forms.

Then

$$-\mathcal{L}_\theta(\eta) = -d\iota_\theta(\eta) - \iota_\theta(d\eta) = -d\iota_\theta(\eta)$$

since η is a top form.

Claim: This defines a right \mathcal{D} -module structure on Ω_X^n .

Proposition 10.4. *There is an equivalence of categories*

$$\begin{aligned} \mathcal{D}_X\text{-mod} &\longrightarrow \mathcal{D}_X^{\text{op}}\text{-mod} \\ \mathcal{M} &\longmapsto \Omega_X^n \otimes_{\mathcal{O}_X} \mathcal{M} \end{aligned}$$

11. ALGEBRAIC GEOMETRY.

Let X be a complex manifold, \mathcal{O}_X the sheaf of holomorphic functions on X .

Definition 34. A closed subset $Z \subseteq X$ is called *analytic* if Z is locally of the form

$$V(f_1, \dots, f_r) = \{x \mid f_1(x) = \dots = f_r(x) = 0\},$$

where $f_1, \dots, f_r \in \mathcal{O}_X$.

Given an analytic subset $Z \subseteq X$ we define a sheaf of ideals

$$\mathcal{I}_Z = \{f \in \mathcal{O}_X \mid f|_Z = 0\} \subseteq \mathcal{O}_X.$$

Note that \mathcal{I}_Z is coherent, since locally $\mathcal{I}_Z = (f_1, \dots, f_r)$ (by definition).

Note also that \mathcal{I}_Z is radical, i.e. if $f^N \in \mathcal{I}_Z$ then $f \in \mathcal{I}_Z$. I.e.

$$\mathcal{I}_Z = \sqrt{\mathcal{I}_Z} = \{f \mid f^N \in \mathcal{I}_Z \text{ for some } N > 0\}.$$

Theorem 11.1 (Analytic Nullstellensatz).

$$\begin{aligned} \left\{ \begin{array}{l} \text{coherent sheaves of} \\ \text{radical ideals} \\ \mathcal{I} = \sqrt{\mathcal{I}} \end{array} \right\} &\xrightarrow{\sim} \left\{ \begin{array}{l} \text{closed analytic subsets} \\ Z \subseteq X \end{array} \right\} \\ \mathcal{I} &\longmapsto V(\mathcal{I}) \\ \mathcal{I}_Z &\longleftarrow Z \end{aligned}$$

In fact, for any coherent ideal sheaf \mathcal{I} ,

$$\mathcal{I}_{V(\mathcal{I})} = \sqrt{\mathcal{I}}.$$

The ring of germs of holomorphic functions at $x \in X$ is $\mathcal{O}_{X,x}$ – it is a noetherian local ring, with maximal ideal the functions vanishing at x . Prime ideals in $\mathcal{O}_{X,x}$ correspond to germs of irreducible analytic subsets of X near x .

Given an \mathcal{O}_X -module \mathcal{F} , define

$$\text{supp}^\circ(\mathcal{F}) := \{x \in X \mid \mathcal{F}_x \neq 0\}.$$

and let $\text{supp}(\mathcal{F})$ be its closure. There is a sheaf of ideal $\text{Ann}(\mathcal{F}) \subseteq \mathcal{O}_X$,

$$\text{Ann}(\mathcal{F}) := \{f \in \mathcal{O}_X \mid f \cdot s = 0 \quad \forall s \in \mathcal{F}\}.$$

Proposition 11.2. *If \mathcal{F} is of finite type (locally finitely generated over \mathcal{O}_X), then*

$$\text{supp}(\mathcal{F}) = V(\text{Ann}(\mathcal{F})).$$

In particular, it is an analytic subset.

Proof. Suppose $\mathcal{F}_x = 0$, i.e. $x \notin \text{supp}(\mathcal{F})$. Choose local generators s_1, \dots, s_r near x . Note that

$$\mathcal{F}_x = 0 \quad \text{implies} \quad (s_1)_x = \dots = (s_r)_x = 0.$$

So there exists some $U \ni x$ such that $\mathcal{F}|_U = 0$. So,

$$\text{Ann}(\mathcal{F})|_U = \mathcal{O}_U, \quad \text{and so } V(\text{Ann}(\mathcal{F})|_U) = \emptyset.$$

In particular, $x \notin V(\text{Ann}(\mathcal{F}))$. Conversely, if $\mathcal{F}_x \neq 0$, take $0 \neq s_x \in \mathcal{F}_x$, $f \in \text{Ann}(\mathcal{F})$. Then $f_x \cdot s_x = 0$ implies $f(x) = 0$ (since if $f(x) \neq 0$ then f is invertible on a neighbourhood of x , and f_x would be invertible, implying that $s_x = 0$ – a contradiction). \square

Example 70. Let $X = \Delta = \{|x| < 1\}$. Let $\mathcal{F} = \mathcal{O}_X/(x^k)$. Then $\text{Ann}(\mathcal{F}) = (x^k)$, $\sqrt{\text{Ann}(\mathcal{F})} = (x)$, and $\text{supp}(\mathcal{F}) = V(x) = \{0\} \subset \Delta$.

Example 71. As above, but let

$$\mathcal{F}' = \bigoplus_{i=1}^k \mathcal{O}_X/(x).$$

Both examples are skyscraper sheaves supported at zero with k -dimensional stalks, but they are **not** the same sheaf.

Given an analytic set $i : Z \subseteq X$ we get a sheaf of rings

$$i^{-1}(\mathcal{O}_X/\mathcal{I}_Z),$$

where i^{-1} denotes the functor we previously had called i^* (from here on out we adopt this change in notation). Z is called a *complex analytic variety*, and decomposes as

$$Z = Z^{\text{reg}} \cup Z^{\text{sing}},$$

where the nonsingular points Z^{reg} form a complex manifold. Z is said to be *irreducible* if whenever we express Z as a union of analytic subsets

$$Z = Z_1 \cup Z_2,$$

we either have $Z = Z_1$ or $Z = Z_2$.

Fact: $Z = \cup_i Z_i$ where the Z_i are irreducible and the union is locally finite.

11.1. Cycle of a coherent sheaf. Suppose $\mathcal{F} \in \text{Coh}(X)$, the category of coherent sheaves, and Z is an irreducible component of $\text{supp}(\mathcal{F})$. We define the *multiplicity of \mathcal{F} along Z* , $m(\mathcal{F}; Z) \in \mathbb{Z}_{>0}$ as follows.

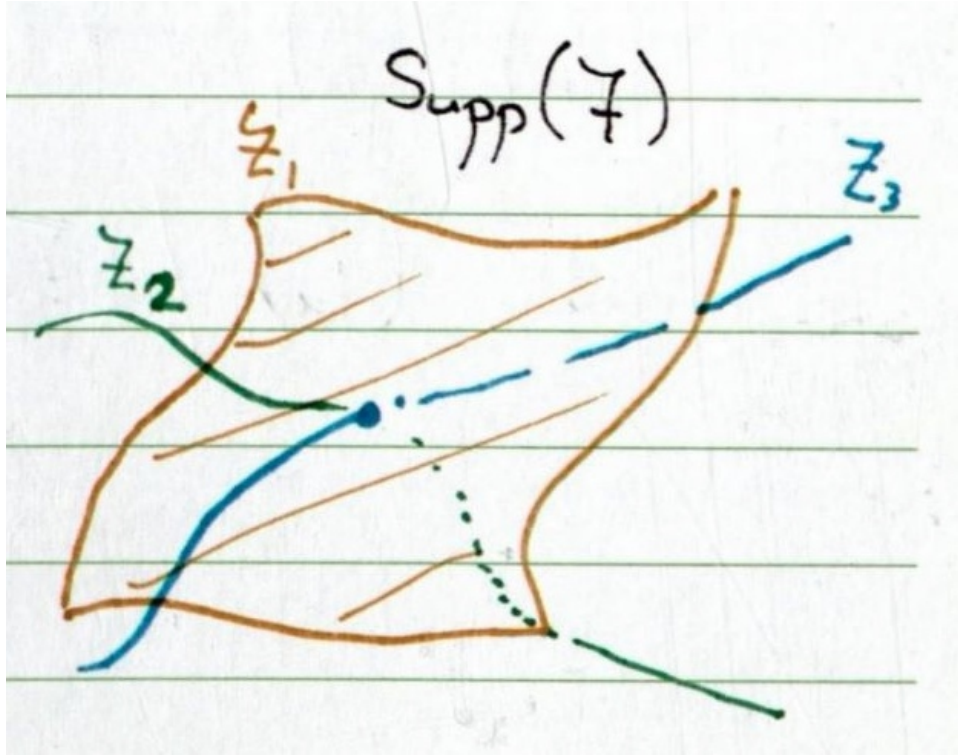


FIGURE 30. Decomposition of the support into irreducible components.

Pick $x \in Z^{\text{reg}}$ (i.e. a smooth point). Then \mathcal{F}_x is an $\mathcal{O}_{X,x}$ -module, and $\mathfrak{p} = \mathcal{I}_{Z,x}$ is a prime ideal in $\mathcal{O}_{X,x}$ (prime because x is regular in Z). Localize at $\mathcal{I}_{Z,x}$. Then $\mathcal{F}_{x,\mathfrak{p}}$ is an $\mathcal{O}_{X,x,\mathfrak{p}}$ -module (i.e. invert everything in $\mathcal{O}_{X,x} - \mathfrak{p}$). Recall that $\text{length}_A(M)$ is the length of the longest chain of submodules

$$M_0 \subsetneq M_1 \subsetneq \cdots \subsetneq M_n = M.$$

Then we define

$$m(\mathcal{F}; Z) = \text{length}_{\mathcal{O}_{X,x,\mathfrak{p}}}(\mathcal{F}_{x,\mathfrak{p}}).$$

(Claim that this is independent of the choice of x .)

More explicitly: \mathcal{F}_x has a filtration

$$0 = (\mathcal{F}_x)_0 \subseteq (\mathcal{F}_x)_1 \subseteq \cdots \subseteq (\mathcal{F}_x)_k = \mathcal{F}_x,$$

such that

$$(\mathcal{F}_x)_i / (\mathcal{F}_x)_{i-1} \cong \mathcal{O}_X / \mathfrak{p}_i$$

for some prime ideals $\mathfrak{p}_i \subseteq \mathcal{O}_{X,x}$. Then

$$m(\mathcal{F}; Z) = \text{number of times } \mathfrak{p} \text{ appears as a } \mathfrak{p}_i.$$

In the algebraic setting, we can take ξ_Z the generic point of Z . Then localize at ξ_Z , to obtain \mathcal{F}_{ξ_Z} as an \mathcal{O}_{X,ξ_Z} -module. Then the multiplicity is the length of this module.

Definition 35. The *cycle* of \mathcal{F} is

$$\text{Cyc}(\mathcal{F}) = \sum_{Z \subset \text{supp}(\mathcal{F})} m(\mathcal{F}; Z) \cdot [Z]$$

where the sum is locally finite, and is taken over the irreducible components of $\text{supp}(\mathcal{F})$. We can also define

$$\text{Cyc}_d(\mathcal{F}) = \sum_{\dim(Z)=d} m(\mathcal{F}; Z) \cdot [Z].$$

Finally, we define

$$m_d(\mathcal{F})_x := \sum_{Z \ni x, \dim(Z)=d} m(\mathcal{F}; Z).$$

Example 72. $X = \Delta$, $\mathcal{F} = \mathcal{O}_X/(x^k)$, $\text{Ann}(\mathcal{F}) = (x^k)$. So $\text{supp}(\mathcal{F}) = \{0\}$, but

$$\text{Cyc}(\mathcal{F}) = k \cdot [0] = \underbrace{[0] + \cdots + [0]}_{k \text{ times}}.$$

I.e. $m(\mathcal{F}, \{0\}) = k$. A chain of length k is

$$0 \rightarrow \mathcal{O}_X/(x) \xrightarrow{\cdot x} \mathcal{O}_X/(x^2) \xrightarrow{\cdot x} \cdots \xrightarrow{\cdot x} \mathcal{O}_X/(x^k).$$

We have the same result for $\mathcal{F}' = \bigoplus_{i=1}^k \mathcal{O}_X/(x)$, i.e.

$$\text{Cyc}(\mathcal{F}') = k \cdot [0].$$

So the cycle does **not** distinguish between these two different sheaves.

12. D -MODULES: SINGULAR SUPPORT AND FILTRATIONS.

Recall that \mathcal{D}_X is a sheaf of rings on X , and we have a filtration

$$F_0\mathcal{D}_X \subseteq F_1\mathcal{D}_X \subseteq \cdots;$$

previously we called $F_i\mathcal{D}_X = \mathcal{D}_X(i)$, the differential operators of order $\leq i$. Recall that

$$\text{Gr}^F(\mathcal{D}_X) = \text{Sym}_{\mathcal{O}_X}^{\bullet}(\mathcal{T}_X) \subseteq (\pi_X)_*\mathcal{O}_{T^*X}.$$

If \mathcal{M} is a coherent \mathcal{D}_X -module, we want to define a subset, the *singular support*,

$$SS(\mathcal{M}) \subseteq T^*X,$$

a closed analytic conic subset (i.e. it is stable under the \mathbb{C}^\times action on T^*X given by $t \cdot (x, \xi) = (x, t\xi)$). We will also define the associated cycle of $SS(\mathcal{M})$ in T^*X , which we call $CC(\mathcal{M})$ (the *characteristic cycle*).

Assume we have a filtration $F_i\mathcal{M}$ ($F_k(\mathcal{D}_X) \cdot F_l(\mathcal{M}) \subseteq F_{k+l}(\mathcal{M})$) such that

$$\text{Gr}^F(\mathcal{M}) \text{ is coherent as a } \text{Gr}^F(\mathcal{D}_X)\text{-module.}$$

Locally we can pick generators u_1, \dots, u_r of \mathcal{M} and define

$$F_k\mathcal{M} := \sum_{i=1}^r F_k(\mathcal{D}_X) \cdot u_i.$$

$\text{Gr}(\mathcal{M})$ is a coherent $\text{Sym}_{\mathcal{O}_X}(\mathcal{T}_X)$ -module, and we extend scalars

$$\text{Gr}(\mathcal{M})^\sim := \mathcal{O}_{T^*X} \otimes_{\pi_X^{-1}\text{Sym}(\mathcal{T}_X)} \pi_X^{-1}\text{Gr}(\mathcal{M}) \in \text{Coh}(T^*X).$$

Then

$$\begin{aligned} SS(\mathcal{M}) &= \text{supp}(\text{Gr}(\mathcal{M})^\sim), \\ CC(\mathcal{M}) &= \text{Cyc}(\text{Gr}(\mathcal{M})^\sim). \end{aligned}$$

Recall: A (left) \mathcal{D}_X -module is equivalent to the data of an \mathcal{O}_X -module with a flat connection.

Let \mathcal{M} be a \mathcal{D}_X -module. Say that \mathcal{M} is *filtered* when

$$\cdots \subseteq F_i\mathcal{M} \subseteq F_{i+1}\mathcal{M} \subseteq \cdots$$

such that

- (1) $F_i\mathcal{M} = 0$ for $i \ll 0$,
- (2) $\bigcup_i F_i\mathcal{M} = \mathcal{M}$, and
- (3) $F_i\mathcal{D}_X \cdot F_j\mathcal{M} \subseteq F_{i+j}\mathcal{M}$.

A filtration is called *good* if additionally

$$\mathrm{Gr}^F(\mathcal{M}) := \bigoplus_i (F_i \mathcal{M} / F_{i-1} \mathcal{M})$$

is a coherent $\mathrm{Gr}^F(\mathcal{D}_X)$ -module.

Remark The good condition implies that \mathcal{M} is coherent as a \mathcal{D}_X -module.

Remark If \mathcal{M} is coherent (as a \mathcal{D}_X -module) then locally it is generated by some sections, s_1, \dots, s_r . I.e. there exists U such that

$$\mathcal{M}|_U = \mathcal{D}_U \cdot s_1 + \dots + \mathcal{D}_U \cdot s_r.$$

Define

$$F_i \mathcal{M}|_U := F_i \mathcal{D}_U \cdot s_1 + \dots + F_i \mathcal{D}_U \cdot s_r.$$

Claim: $(\mathcal{M}|_U, F)$ is a good filtration. I.e. good filtrations exist locally for a coherent \mathcal{D}_X -module.

Given (\mathcal{M}, F) a good filtered \mathcal{D}_X -module,

$$\mathrm{Gr}^F(\mathcal{M}) \text{ is a coherent } \mathrm{Sym}_{\mathcal{O}_X}^\bullet(\mathcal{T}_X) = \mathrm{Gr}(\mathcal{D}_X)\text{-module.}$$

Aside: If V is a finite dimensional vector space over \mathbb{C} , the ring of polynomial functions on V is

$$\mathrm{Sym}_{\mathbb{C}}^\bullet(V^*) = \mathbb{C} \oplus V^* \oplus \mathrm{Sym}^2(V^*) \oplus \dots$$

I.e. if e_1, \dots, e_r is a basis for V with dual basis $\epsilon_1, \dots, \epsilon_r$,

$$\mathrm{Sym}^\bullet(V^*) = \mathbb{C}[\epsilon_1, \dots, \epsilon_r].$$

If M is a $\mathrm{Sym}^\bullet(V^*)$ -module, then for $\mathrm{Ann}(M) \subseteq \mathrm{Sym}^\bullet(V^*)$

$$V(\mathrm{Ann}(M)) = \mathrm{supp}(M) \subseteq V.$$

V is also a \mathbb{C} -manifold, so we have \mathcal{O}_V . We can think of $\mathrm{Sym}^\bullet(V^*)$ as a constant sheaf of rings. Then we have

$$\mathcal{O}_V \otimes_{\mathrm{Sym}^\bullet(V^*)} M =: M^\sim,$$

which is a coherent sheaf. $\mathrm{supp}(M) = V(\mathrm{Ann}(M^\sim))$, i.e. we have the same notion of support.

If $M = \bigoplus_i M_i$ is a graded module over $\mathrm{Sym}^\bullet(V^*) = \bigoplus_i \mathrm{Sym}^i(V^*)$ (a graded ring), then $\mathrm{Ann}(M)$ is a homogeneous ideal. Then $\mathrm{supp}(M)$ is *conic*, i.e. it is preserved by the \mathbb{C}^\times action on V . *End aside.*

Now, to make sense of $\mathrm{Sym}_{\mathcal{O}_X}^\bullet(\mathcal{T}_X)$, think of

$$V = T_x^* X, \quad V^* = T_x X \quad \text{for each point } x \in X.$$

So if (\mathcal{M}, F) is a good coherent \mathcal{D}_X -module, we have that

$$\mathrm{Gr}^F(\mathcal{M}) \text{ is a coherent } \mathrm{Sym}_{\mathcal{O}_X}^\bullet(\mathcal{T}_X)\text{-module,}$$

and so we get

$$\mathrm{Gr}(\mathcal{M})^\sim = \mathcal{O}_{T^*X} \otimes_{\pi_X^{-1} \mathrm{Sym}(\mathcal{T}_X)} \pi_X^{-1}(\mathrm{Gr}^F(\mathcal{M})),$$

which is a coherent \mathcal{O}_{T^*X} -module, where $\pi_X : T^*X \rightarrow X$ is projection.

Definition 36. The *singular support* is

$$SS(\mathcal{M}, F) = \mathrm{supp}(\mathrm{Gr}^F(\mathcal{M})^\sim) = V(\mathrm{Ann}(\mathrm{Gr}^F(\mathcal{M})^\sim)) \subseteq T^*X.$$

$SS(\mathcal{M})$ is a conic subset of T^*X .

Proposition 12.1. $SS(\mathcal{M}, F)$ is independent of the choice of good filtration F .

We omit the proof.

Corollary 12.2. If \mathcal{M} is a coherent \mathcal{D}_X -module, $SS(\mathcal{M}) \subseteq T^*X$ is well-defined.

Definition 37. The *characteristic ideal* of \mathcal{M} is

$$J_{\mathcal{M}} := \sqrt{\text{Ann}(\text{Gr}(\mathcal{M})^\sim)} \subseteq \text{Sym}^\bullet(\mathcal{T}_X).$$

The *characteristic cycle* is

$$CC(\mathcal{M}) = \text{Cyc}(\text{Gr}(\mathcal{M})^\sim).$$

Example 73. Let $\mathcal{M} = \mathcal{D}_X$ and F be the order filtration.

$$\text{Gr}^F(\mathcal{D}_X) = \text{Sym}^\bullet(\mathcal{T}_X)$$

and

$$\text{Gr}^F(\mathcal{D}_X)^\sim = \mathcal{O}_{T^*X},$$

so we have

$$SS(\mathcal{D}_X) = \text{supp}(\mathcal{O}_{T^*X}) = T^*X.$$

Remark Think of \mathcal{D}_X as a noncommutative deformation of $\text{Sym}^\bullet(\mathcal{T}_X) \subseteq \mathcal{O}_{T^*X}$, i.e. that \mathcal{D}_X is a *quantization* of T^*X .

Think of \mathcal{D}_X -modules as “living on T^*X ”. The first approximation to this idea is

$$\mathcal{M} \mapsto SS(\mathcal{M}) \subseteq T^*X.$$

Example 74. Given $P \in \mathcal{D}_X$, let $\mathcal{M}_P = \mathcal{D}_X / \mathcal{D}_X \cdot P$. (I.e. this roughly corresponds to solving the equation $Pu = 0$.) So P could be, for example, $x^2 \partial_x^2 + \dots$. Then the *principal symbol* of P is

$$\sigma(P) = \text{image of } P \text{ in } \text{Gr}_m(\mathcal{D}_X) \text{ where } m \text{ is maximal.}$$

Implicitly we are considering the ∂_* as coordinates on the cotangent bundle. For instance, $P = x^2 \partial_x^2 + x \partial_x$ has

$$\sigma(P) = x^2 \xi^2,$$

where (x, ξ) are coordinates on T^*X (here $\xi = \sigma(\partial_x)$).

Proposition 12.3. $SS(\mathcal{M}) = V(\sigma(P)) \subseteq T^*X$.

Proof. We have a SES

$$0 \rightarrow \mathcal{D}_X \xrightarrow{P} \mathcal{D}_X \xrightarrow{q} \mathcal{M}_P \rightarrow 0.$$

q induces a good filtration on \mathcal{M}_P by taking the image of the filtration on \mathcal{D}_X . Then

$$\text{Gr}(\mathcal{M}_P) = \text{Sym}(\mathcal{T}_X) / (\sigma(P)).$$

□

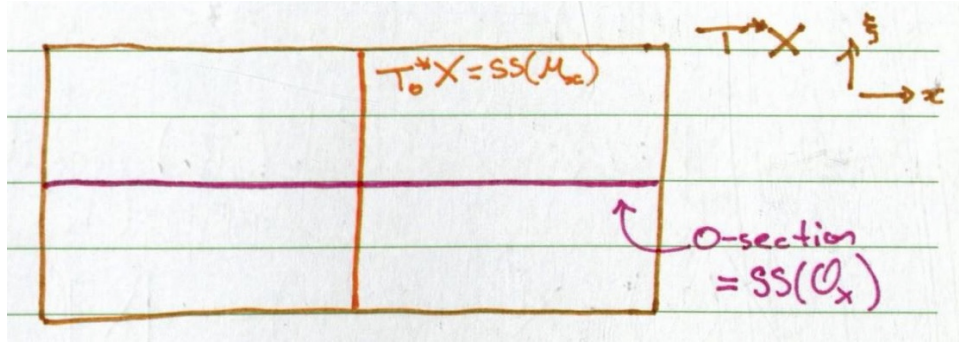
Example 75. Let $X = \Delta = \{|x| < 1\} \subset \mathbb{C}$. Take $P = \partial_x$, so $\mathcal{M}_P = \mathcal{O}_X$. Then

$$SS(\mathcal{O}_X) = V(\xi) = X \subset T^*X,$$

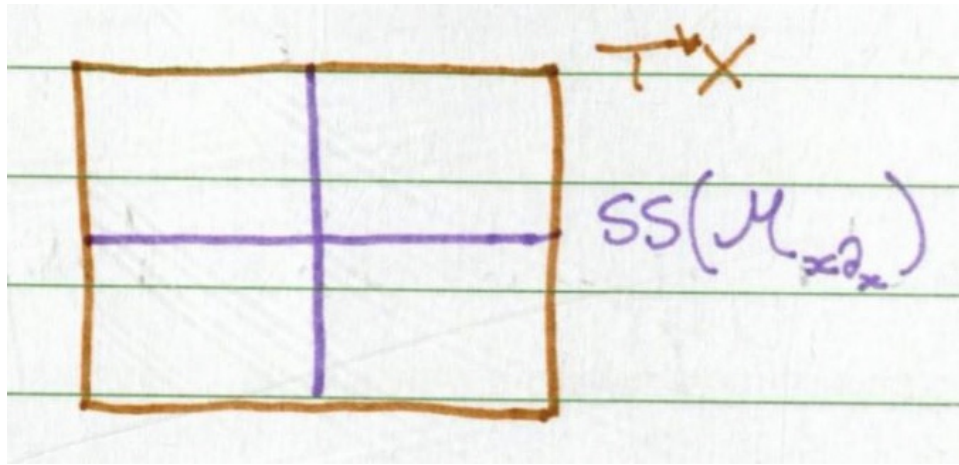
where X includes into T^*X as the zero section.

Example 76. Now take $P = x$. Then

$$SS(\mathcal{M}_P) = V(x) = T_0^*X \subseteq T^*X.$$

FIGURE 31. Singular supports of \mathcal{O}_X and \mathcal{M}_x in T^*X .

Example 77. Now take $P = x\partial_x$. Then $\sigma(P) = x\xi$, so $SS(\mathcal{M}_P) = V(x\xi) = X \cup T_0^*X$.

FIGURE 32. Singular support of the Euler operator $x\partial_x$.

In the above examples, the characteristic cycles are

$$CC(\mathcal{O}_X) = [X], \quad CC(\mathcal{M}_x) = [T_0^*X], \quad CC(\mathcal{M}_{x\partial_x}) = [X] + [T_0^*X].$$

Suppose (\mathcal{V}, Δ) is a flat connection, i.e. \mathcal{V} is a locally free \mathcal{O}_X -module of finite rank.

Proposition 12.4. $SS(\mathcal{V}) = X \subset T^*X$.

Proof. The induced filtration is

$$0 = F_{-1}\mathcal{V} \subseteq F_0\mathcal{V} = \mathcal{V} \subseteq \mathcal{V} \subseteq \mathcal{V} \subseteq \dots,$$

so $\text{Gr}^F(\mathcal{V}) = \mathcal{V}$. Locally we can choose a horizontal frame and express $\mathcal{V} = \mathcal{O}_X^{\oplus r}$ as a $\text{Sym}(\mathcal{I}_X)$ -module, where \mathcal{I}_X acts by 0. So, $\text{Ann}(\mathcal{V}) = (\mathcal{I}_X)$, and

$$SS(\mathcal{V}) = X, \quad CC(\mathcal{V}) = r \cdot [X].$$

□

In fact, the following are equivalent for a coherent \mathcal{D}_X -module \mathcal{M} :

- (1) \mathcal{M} is a flat connection (i.e. locally free \mathcal{O}_X -module).
- (2) $SS(\mathcal{M})$ is contained in the zero section of T^*X .

(3) \mathcal{M} is coherent as an \mathcal{O}_X -module.

Lemma 12.5 (Bernstein's Lemma). *If \mathcal{M} is a coherent \mathcal{D}_X -module,*

$$\dim(SS(\mathcal{M})) \geq \dim(X) = \frac{1}{2} \dim(T^*X).$$

We defer the proof to later.

Recall that if (W^{2n}, ω) is a symplectic vector space, $V \subseteq W$ a subspace, then V is called

- *isotropic* if $\omega|_V = 0$ (which implies that $\dim(V) \leq n$),
- *coisotropic* if $\omega|_{V^\perp} = 0$ (which implies that $\dim(V) \geq n$),
- *Lagrangian* if it is isotropic and coisotropic (in which case $\dim(V) = n$).

Theorem 12.6 (Gabber's Theorem). *$SS(\mathcal{M})$ is coisotropic in T^*X .*

Definition 38. A \mathcal{D}_X -module is called *holonomic* if $\dim(SS(\mathcal{M})) = \dim(X)$.

By Gabber's theorem, this is equivalent to $SS(\mathcal{M})$ being Lagrangian in T^*X .

13. HOLONOMIC \mathcal{D} -MODULES.

We now consider a generalization of the theory of differential equations.

If $Pu = 0$, $P \in \mathcal{D}_\mathbb{C}$, we have that the space of solutions $u \in \mathcal{O}_\mathbb{C}$ is finite dimensional. If X is a complex manifold, recall that a (coherent) \mathcal{D}_X -module \mathcal{M} is called *holonomic* if $SS(\mathcal{M}) \subseteq T^*X$ is Lagrangian (equivalently, $\dim SS(\mathcal{M}) = \dim(X)$).

Example 78. If $\dim X = 1$ and $\mathcal{D}_X = \mathcal{D}_X / \mathcal{D}_X \cdot P = \mathcal{M}_P$ for $P \in \mathcal{D}_X$, then

$$SS(\mathcal{M}_P) = V(\sigma(P)) \subseteq T^*X,$$

and $\dim SS(\mathcal{M}_P) = 1$ unless P is constant.

Theorem 13.1 (Kashiwara, PhD thesis). *Let \mathcal{M} be a holonomic \mathcal{D}_X -module. Then we have two complexes of sheaves,*

$$\begin{aligned} \text{Sol}(\mathcal{M}) &:= R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{O}_X), && \text{“solutions of } \mathcal{M} \text{”}, \\ \text{DR}(\mathcal{M}) &:= \mathcal{M} \xrightarrow{\nabla} \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^1 \rightarrow \cdots \rightarrow \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^n, && \text{“de Rham complex”}. \end{aligned}$$

These are both constructible complexes with regards to some “nice” analytic stratification of S . In particular, the stalks of both complexes are finite dimensional.

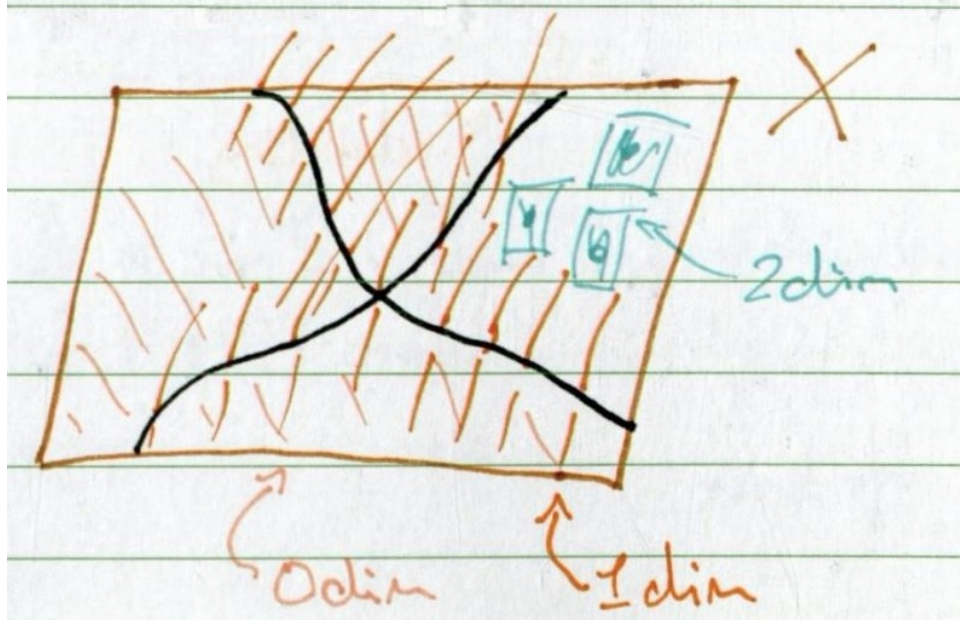


FIGURE 33. Picture of a constructible sheaf.

14. FUNCTORS FOR \mathcal{D} -MODULES.

Recall that for sheaves we had the “6-functor formalism”: $*$ - and $!$ - adjoint pushforwards and pullbacks, $\mathcal{E}xt$ and \otimes . We would like similar adjoint functors for \mathcal{D} -modules – we will see, however, that these may not always exist, and even when they do exist they will only be adjoint for holonomic \mathcal{D} -modules.

Given a holomorphic map of complex manifolds, $f : X \rightarrow Y$, we will define functors between the bounded derived categories of \mathcal{D} -modules

$$\begin{array}{ccc}
 & \xrightarrow{f^{\text{dR}}_*} & \\
 D^b(\mathcal{D}_Y) & & D^b(\mathcal{D}_X) \\
 & \xleftarrow{f^!} &
 \end{array}$$

Beware: In general these are **not** adjoint!

We recall and compare previous situations. Some notation has been changed from previous lectures to avoid overloading.

14.0.1. \mathbb{C}_X -modules.

$$\begin{array}{ccc}
 & \xrightarrow{f_\bullet} & \\
 \text{Sh}(X; \mathbb{C}) & & \text{Sh}(Y; \mathbb{C}) \\
 & \xleftarrow{f^{-1}} &
 \end{array}$$

f^{-1} is exact, and is left adjoint to f_\bullet (which is therefore left exact). These give rise to derived functors f^{-1} and Rf_\bullet .

14.0.2. \mathcal{O} -modules.

$$\begin{array}{ccc}
 & \xrightarrow{f_\bullet} & \\
 \mathcal{O}_X\text{-mod} & & \mathcal{O}_Y\text{-mod} \\
 & \xleftarrow{f_\bullet^*} &
 \end{array}$$

where

$$f_{\mathcal{O}}^*(\mathcal{F}) := \mathcal{O}_X \otimes_{f^{-1}(\mathcal{O}_Y)} f^{-1}(\mathcal{F}).$$

$f_{\mathcal{O}}^*$ is left adjoint to f_{\bullet} , so is right exact. \mathcal{O}_X is generally not $f^{-1}(\mathcal{O}_Y)$ -flat, so $f_{\mathcal{O}}^*$ is not exact. Thus, we have a left derived functor $Lf_{\mathcal{O}}^*$. Similarly, f_{\bullet} is left exact, so gives a right derived functor Rf_{\bullet} .

14.0.3. Some examples.

- (1) If V is a vector bundle on Y ,

$$\begin{array}{ccc} f^{-1}(V) = V \times_Y X & \longrightarrow & V \\ \downarrow & & \downarrow \\ X & \longrightarrow & Y \end{array}$$

and

$$\Gamma(-; f^{-1}(V)) = f_{\mathcal{O}}^*(\Gamma(-; V)).$$

- (2) If $i : \{x\} \hookrightarrow X$, $\mathcal{F} \in \mathcal{O}_X\text{-mod}$, then $i^{-1}(\mathcal{F}) = \mathcal{F}_x$, the stalk of \mathcal{F} at x . This is often an ∞ -dimensional space of convergent power series. Conversely and comparatively,

$$i_{\mathcal{O}}^*(\mathcal{F}) = \left(\frac{\mathcal{O}_{X,x}}{\mathfrak{m}_x} \right) \otimes_{\mathcal{O}_{X,x}} \mathcal{F}_x = \mathcal{F}_x / \mathcal{F}_x \cdot \mathfrak{m}_x,$$

which we call the *fibre of \mathcal{F} at x* . If \mathcal{F} is a vector bundle, this is literally the fibre.

14.0.4. \mathcal{D} -modules. Define a functor

$$f^{\circ} : \mathcal{D}_Y\text{-mod} \rightarrow \mathcal{D}_X\text{-mod}$$

as follows. Let

$$f^{\circ}(\mathcal{M}) = f_{\mathcal{O}}^*(\mathcal{M})$$

as an \mathcal{O}_X module. Then to define a \mathcal{D}_X -module structure, we need to say how $v \in \mathcal{T}_X$ acts on $m \in f_{\mathcal{O}}^*(\mathcal{M})$. Tangent vectors pushforward, $T_{X,x} \rightarrow T_{Y,f(x)}$, and these can be put together to give a map

$$\begin{array}{ccc} \mathcal{T}_X & \rightarrow & f_{\mathcal{O}}^*(\mathcal{T}_Y) \\ v & \mapsto & \tilde{v} \end{array}$$

$f_{\mathcal{O}}^*(\mathcal{M}) = \mathcal{O}_X \otimes_{f^{-1}(\mathcal{O}_Y)} f^{-1}(\mathcal{M})$. Given $g \otimes m$, $g \in \mathcal{O}_X$ and $m \in f^{-1}\mathcal{M}$,

$$v \cdot (g \otimes m) = v(g) \otimes m + g \otimes \tilde{v}(m).$$

Now define (since f° is right exact) a left derived functor

$$f^{\dagger} := Lf^{\circ}.$$

14.1. Transfer bimodule. Define

$$\mathcal{D}_{X \rightarrow Y} := f^{\circ}(\mathcal{D}_Y).$$

I.e.

$$\mathcal{D}_{X \rightarrow Y} = \mathcal{O}_X \otimes_{f^{-1}(\mathcal{O}_Y)} f^{-1}(\mathcal{D}_Y),$$

so this carries a *left* \mathcal{D}_X -module action, and a *right* $f^{-1}(\mathcal{D}_Y)$ -module action. Then we have functors (of *left* modules)

$$\begin{array}{ccc} \mathcal{D}_Y\text{-mod} & \xrightarrow{f^{-1}} & f^{-1}(\mathcal{D}_Y)\text{-mod} & \xrightarrow{\mathcal{D}_{X \rightarrow Y} \otimes_{f^{-1}(\mathcal{D}_Y)} (-)} & \mathcal{D}_X\text{-mod}. \\ & \searrow^{f^{\circ}} & & & \end{array}$$

We call $\mathcal{D}_{X \rightarrow Y}$ the *transfer bimodule*. Then

$$f^{\dagger} = \mathcal{D}_{X \rightarrow Y} \otimes_{f^{-1}(\mathcal{D}_Y)}^L (f^{-1}(-)),$$

the left derived tensor product. We also have a functor in the opposite direction, but for *right* modules:

$$\mathcal{D}_X^{\text{op}}\text{-mod} \xrightarrow{(-) \otimes_{\mathcal{D}_X} \mathcal{D}_{X \rightarrow Y}} f^{-1}(\mathcal{D}_Y)^{\text{op}}\text{-mod} \xrightarrow{f_{\bullet}} \mathcal{D}_Y^{\text{op}}\text{-mod}.$$

Recall that there is a nontrivial equivalence of categories between $\mathcal{D}_X\text{-mod}$ and $\mathcal{D}_X^{\text{op}}\text{-mod}$ (and that this is a special property of \mathcal{D} -modules, **not** something that holds for arbitrary noncommutative rings). To get a functor on *left* \mathcal{D} -modules we take

$$\begin{array}{ccc} \mathcal{D}_X^{\text{op}}\text{-mod} & \xrightarrow{(-)\otimes_{\mathcal{D}_X} \mathcal{D}_{X \rightarrow Y}} & f^{-1}(\mathcal{D}_Y)^{\text{op}}\text{-mod} & \xrightarrow{f_{\bullet}} & \mathcal{D}_Y^{\text{op}}\text{-mod} \\ \Omega_X^n \otimes_{\mathcal{O}_X} (-) \uparrow \sim & & & & \sim \uparrow \Omega_Y^n \otimes_{\mathcal{O}_Y} (-) \\ \mathcal{D}_X \otimes \text{-mod} & \xrightarrow{\quad f_{\circ} \quad} & & & \mathcal{D}_Y\text{-mod} \end{array}$$

Define

$$\begin{aligned} f_*^{\text{dR}} &: D^b(\mathcal{D}_X) \rightarrow D^b(\mathcal{D}_Y) \\ f_*^{\text{dR}}(\mathcal{M}) &:= Rf_{\bullet}(\mathcal{D}_{Y \leftarrow X} \otimes_{\mathcal{D}_X}^L \mathcal{M}) \end{aligned}$$

What is $\mathcal{D}_{Y \leftarrow X}$? There is an equivalence of categories

$$\mathcal{D}_X - f^{-1}(\mathcal{D}_Y)\text{-bimodules} \simeq \mathcal{D}_X^{\text{op}} - f^{-1}(\mathcal{D}_Y)^{\text{op}}\text{-bimodules} = f^{-1}(\mathcal{D}_Y) - \mathcal{D}_X\text{-bimodules}.$$

Then $\mathcal{D}_{X \rightarrow Y} \leftrightarrow \mathcal{D}_{Y \leftarrow X}$ under this equivalence.

14.2. Closed embeddings. Let $i : Z \hookrightarrow X$ be a closed embedding (recall that this implies i_{\bullet} is exact). Consider

$$\begin{aligned} i^{\circ} &: \mathcal{D}_X\text{-mod} \rightarrow \mathcal{D}_Z\text{-mod} \\ i^{\circ}(\mathcal{M}) &= \mathcal{D}_{Z \rightarrow X} \otimes_{i^{-1}(\mathcal{D}_X)} i^{-1}(\mathcal{M}), \end{aligned}$$

and

$$\begin{aligned} i^! &: \mathcal{D}_X\text{-mod} \rightarrow \mathcal{D}_Z\text{-mod} \\ i^!(\mathcal{M}) &= i^{-1} \mathcal{H}om_{\mathcal{D}_X}(\mathcal{D}_{X \leftarrow Z}, \mathcal{M}) \end{aligned}$$

Lemma 14.1 (Kashiwara's Lemma). *There is a pair of adjoint functors $(i_{\circ}, i^!)$*

$$\mathcal{D}_Z\text{-mod} \begin{array}{c} \xrightarrow{i_{\circ}} \\ \xleftarrow{i^!} \end{array} \mathcal{D}_X\text{-mod}$$

which induce an equivalence of categories between

$$\mathcal{D}_Z\text{-mod} \begin{array}{c} \xrightarrow{i_{\circ}} \\ \xleftarrow{i^!} \end{array} (\mathcal{D}_X\text{-mod})_Z$$

where the right hand side is the category of \mathcal{D}_X -modules supported on Z .

Remark This is **not** true for \mathcal{O} -modules.

Example 79. Consider the inclusion of a point $\{x\} \hookrightarrow X = \mathbb{C}$. Then $\mathcal{O}_{\{x\}}\text{-mod} = \text{Vect}$, while $(\mathcal{O}_X\text{-mod})_{\{x\}}$ contains nontrivial extensions, such as

$$0 \rightarrow \mathcal{O}_{X,x}/\mathfrak{m}_x \rightarrow \mathcal{O}_{X,x}/\mathfrak{m}_x^2 \rightarrow \mathcal{O}_{X,x}/\mathfrak{m}_x \rightarrow 0.$$

So $(\mathcal{O}_X\text{-mod})_{\{x\}}$ is not semisimple, thus not equivalent to Vect .

Lemma 14.2 (Kashiwara's Lemma part II). *$(i_{\circ}, i^!)$ also gives an equivalence on the level of derived categories.*

14.3. **Where do the transfer bimodules come from?** \mathcal{D}_X -modules “live on T^*X ”, as a deformed version of quasicohherent sheaves. Given a map $f : X \rightarrow Y$, we don’t get a map between cotangent bundles. Instead we get a *correspondence* or *span*

$$T^*X \xleftarrow{\rho_f} T^*Y \times_Y X \xrightarrow{\varpi_f} T^*Y.$$

In fact T^*X and T^*Y are symplectic, and thinking of the above as a map into the product $T^*X \times T^*Y$, the middle object is in fact Lagrangian. We then have

$$\begin{array}{ccccc} T^*X & \xleftarrow{\rho_f} & T^*Y \times_Y X & \xrightarrow{\varpi_f} & T^*Y \\ \downarrow & & \downarrow \text{quantization} & & \downarrow \\ \mathcal{D}_X & & \mathcal{D}_{X \rightarrow Y} \text{ or } \mathcal{D}_{Y \rightarrow X} & & \mathcal{D}_Y \end{array}$$

We can understand the reverse map, e.g. $\mathcal{D}_X \rightarrow T^*X$; \mathcal{D}_X has a filtration as a \mathcal{D}_X -module, and the associated graded is functions on T^*X .

14.3.1. *Case 1: $f = i : X \hookrightarrow Y$ a closed embedding.*

Example 80. See Figure 34.

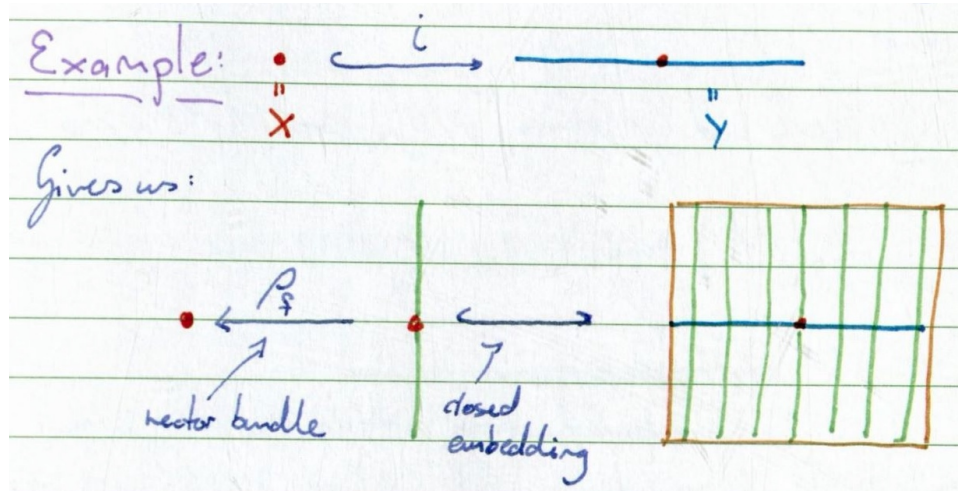


FIGURE 34. The span of a closed embedding.

In more generality, X is defined by a sheaf of ideals $\mathcal{I}_X \subseteq \mathcal{O}_Y$. Then

$$\begin{aligned} \mathcal{O}_X &= i^{-1}(\mathcal{O}_Y/\mathcal{I}_X) \\ \mathcal{D}_{X \rightarrow Y} &= \mathcal{O}_X \otimes_{i^{-1}\mathcal{O}_Y} i^{-1}\mathcal{D}_Y = i^{-1}(\mathcal{D}_Y/\mathcal{I}_X \cdot \mathcal{D}_Y) \end{aligned}$$

Exercise 14.1. Show that $\mathcal{D}_{Y \leftarrow X} = i^{-1}(\mathcal{D}_Y/\mathcal{D}_Y \cdot \mathcal{I}_X)$.

Definition 39. We define two underived functors:

$$\begin{aligned} i^\circ(\mathcal{N}) &= \mathcal{D}_{X \rightarrow Y} \otimes_{i^{-1}\mathcal{D}_Y} i^{-1}\mathcal{N} = i^{-1}(\mathcal{N}/\mathcal{I}_X \cdot \mathcal{N}), \\ i^\natural(\mathcal{N}) &= \mathcal{H}om_{i^{-1}\mathcal{D}_Y}(\mathcal{D}_{Y \leftarrow X}, i^{-1}\mathcal{N}) \in \mathcal{D}_X\text{-mod}. \end{aligned}$$

Remark Here and following, $\mathcal{N} \in \mathcal{D}_Y\text{-mod}$ and $\mathcal{M} \in \mathcal{D}_X\text{-mod}$.

Observe that

$$i_\circ(\mathcal{M}) = i_\bullet(\mathcal{D}_{Y \leftarrow X} \otimes_{\mathcal{D}_X} \mathcal{M});$$

there is no need to derive, since pushforward along a closed embedding is exact.

Remark • i° uses the forward facing bimodule $\mathcal{D}_{X \rightarrow Y}$.
 • i^\natural and i_\circ use the backwards facing bimodule $\mathcal{D}_{Y \leftarrow X}$.

Proposition 14.3. (1) i_\circ is exact ($\mathcal{D}_{Y \leftarrow X}$ is flat over \mathcal{D}_X), i° is right exact, and i^\natural is left exact.
 (2) $i^\natural = Li^\circ = Ri^\natural[d]$ where $d = \text{codim}(X \hookrightarrow Y)$.
 (3) i^\natural is right adjoint to i_\circ , and moreover Ri^\natural is right adjoint to $Li_\circ = i_*^{dR}$.
 (4) i_\circ induces an equivalence of categories

$$\mathcal{D}_X\text{-mod} \begin{array}{c} \xrightarrow{i_\circ} \\ \xleftarrow{i^\natural} \end{array} (\mathcal{D}_Y\text{-mod})_X$$

Again, there is a derived statement:

$$D^b(\mathcal{D}_X\text{-mod}) \begin{array}{c} \xrightarrow{Li_\circ = i_*^{dR}} \\ \xleftarrow{Ri^\natural} \end{array} D^b[(\mathcal{D}_Y\text{-mod})_X]$$

Example 81. Let's look at a special case:

$$X = \{z = 0\} \subseteq Y \quad \text{a hypersurface.}$$

We have local coordinates $y_1, \dots, y_n = z$ on Y (so the last coordinate cuts out the hypersurface X). In this case the transfer bimodule is

$$\mathcal{D}_{X \rightarrow Y} = i^{-1}(\mathcal{D}_Y/z \cdot \mathcal{D}_Y).$$

This is resolved by

$$i^{-1}(\mathcal{D}_Y/z \cdot \mathcal{D}_Y) \simeq (i^{-1}\mathcal{D}_Y \xrightarrow[-1]{\cdot z} i^{-1}\mathcal{D}_Y)_0$$

and similarly

$$\mathcal{D}_{Y \leftarrow X} \simeq (i^{-1}\mathcal{D}_Y \xrightarrow[-1]{\cdot z} i^{-1}\mathcal{D}_Y)_0.$$

So we have an explicit description

$$i^\natural(\mathcal{N}) = \mathcal{H}om_{i^{-1}\mathcal{D}_Y}(i^{-1}\mathcal{D}_Y/i^{-1}\mathcal{D}_Y \cdot z, \mathcal{N}) = \ker(z : \mathcal{N} \rightarrow \mathcal{N}).$$

Now, as a right \mathcal{D}_X -module,

$$\mathcal{D}_{Y \leftarrow X} = \mathbb{C}[\partial_z] \otimes_{\mathbb{C}} \mathcal{D}_X.$$

The difference between this and \mathcal{D}_Y is that we don't have functions of the coordinate z (which vanishes on X) – however, we still have vector fields in the ∂_z -direction. Note that $\mathcal{D}_{Y \leftarrow X}$ is free as a right \mathcal{D}_X -module.

Thus, the functor i_\circ is given by

$$i_\circ(\mathcal{M}) = i_\bullet(\mathcal{D}_{Y \leftarrow X} \otimes_{\mathcal{D}_X} \mathcal{M}) = \mathbb{C}[\partial_z] \otimes_{\mathbb{C}} \mathcal{M}.$$

Think: i_\circ is “fattening \mathcal{M} up” along the line $\langle \partial_z \rangle$.

What is the \mathcal{D}_Y -module structure on this?

$$i_\circ \mathcal{M} = \cdots \begin{array}{c} \xrightarrow{\cdot z} \\ \oplus \\ \xleftarrow{\partial_z} \end{array} \partial_z^2 \mathcal{M} \begin{array}{c} \xrightarrow{\cdot z} \\ \oplus \\ \xleftarrow{\partial_z} \end{array} \partial_z \mathcal{M} \begin{array}{c} \xrightarrow{\cdot z} \\ \oplus \\ \xleftarrow{\partial_z} \end{array} \mathcal{M} \xrightarrow{\cdot z} 0.$$

Claim that since $z\mathcal{M} = 0$, the action of the other $\cdot z$ is determined by commutations with the ∂_z . Define

$$E := z\partial_z \quad \text{the Euler operator.}$$

Claim that $\partial_z^i \mathcal{M}$ is the $(-i-1)$ th-eigenspace of E .

$$E = z\partial_z = \partial_z z - 1,$$

and $z\mathcal{M} = 0$. So E acts on \mathcal{M} as multiplication by -1 . Then we can check that

- multiplication by ∂_z lowers the eigenvalue by 1, and
- multiplication by z increases the eigenvalue by 1.

Claim: $i^{\natural}i_0\mathcal{M} \cong \mathcal{M}$.

Proof. The z and ∂_z operations are isomorphisms on $i_0\mathcal{M}$, except for in the last place where $z\mathcal{M} = 0$. So

$$i^{\natural}i_0\mathcal{M} = \ker(z : i_0\mathcal{M} \rightarrow i_0\mathcal{M}) = \mathcal{M}.$$

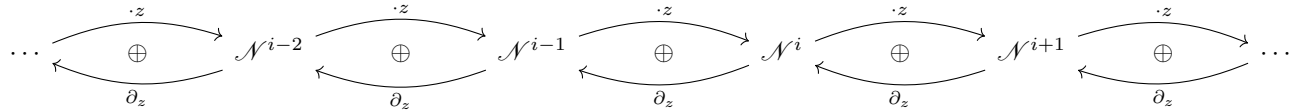
□

Remark $i^{\natural}i_0\mathcal{M} \leftarrow \mathcal{M}$ will be the unit for an adjunction.

Now suppose $\mathcal{N} \in \mathcal{D}_Y\text{-mod}$. Look at

$$\mathcal{N}^i := \{i^{\text{th}} \text{ eigenspace of } E \text{ acting on } \mathcal{N}\}.$$

- We have no guarantee that i is integral.
- We have no idea whether this is bounded at either end:



Note:

- This might not be all of \mathcal{N} (e.g. $\mathcal{N}^{i+\frac{1}{2}}$ could exist).
- $\ker(z) \subseteq \mathcal{N}^{-1}$, so we see that the counit for the adjunction is

$$\dots \oplus \partial_z \ker(z) \oplus \ker(z) = i_0 i^{\natural} \mathcal{N} \rightarrow \mathcal{N}.$$

Now assume $\text{supp}(\mathcal{N}) \subseteq X$. I.e.

$$z^N \cdot m = 0 \text{ for all } m \in \mathcal{N}, N \gg 0.$$

If $z \cdot m = 0$ then $m \in \mathcal{N}^{-1}$. By an induction argument, if $z^N \cdot m = 0$ then

$$m \in \mathcal{N}^{-N} \oplus \dots \oplus \mathcal{N}^{-1}.$$

Exercise 14.2. In this case, $i_0 i^{\natural} \mathcal{N} \xrightarrow{\sim} \mathcal{N}$.

Hence in this case we have shown an equivalence

$$\begin{array}{ccc} \{\mathcal{D}\text{-modules on } X\} & \xleftarrow{\sim} & \{\mathcal{D}\text{-modules on } Y \text{ supported on } X\} \\ \parallel & & \parallel \\ \mathcal{D}_X\text{-mod} & \begin{array}{c} \xleftarrow{i^{\natural}} \\ \xrightarrow{i_0} \end{array} & (\mathcal{D}_Y\text{-mod})_X \end{array}$$

Remark If $X \hookrightarrow Y$ is a closed embedding but *not* a hypersurface, it is cut out by a collection of functions (locally coordinate functions), $X = \{z_1 = \dots = z_r = 0\}$. Let

$$K(z_i) = (i^{-1}(\mathcal{O}_Y \xrightarrow{\cdot z_i} i^{-1}(\mathcal{O}_Y))).$$

Then we define the *Koszul complex* of $X \subseteq Y$ to be

$$K(z_1) \otimes \dots \otimes K(z_r).$$

14.4. **A concrete calculation.** Let's compute

$$p_*^{\text{dR}} : D^b(\mathcal{D}_X) \rightarrow D^b(\mathbb{C}),$$

where $p : X \rightarrow \text{pt}$. We have the transfer bimodules

$$\mathcal{D}_{X \rightarrow \text{pt}} = \mathcal{O}_X \quad \text{left } \mathcal{D}\text{-module, right module for constant sheaf)}$$

and

$$\mathcal{D}_{\text{pt} \leftarrow X} = \mathcal{O}_X \otimes \Omega_X^{\text{top}} = \Omega_X^{\text{top}} = \Omega_X^n,$$

where $n = \dim(X)$. So

$$p_*^{\text{dR}}(\mathcal{M}) = \Omega_X^n \otimes_{\mathcal{D}_X}^L \mathcal{M}.$$

How do we compute \otimes^L ? We either need to replace Ω_X^n of \mathcal{M} . To do this uniformly for all \mathcal{M} we will replace Ω_X^n by a complex of locally free $\mathcal{D}_X^{\text{op}}$ -modules (right \mathcal{D}_X -modules).

We do this by taking a left module resolution of \mathcal{O}_X , then we will use the dualizing sheaf to produce the desired resolution.

Lemma 14.4. *There are (locally free) resolutions*

$$\begin{aligned} \mathcal{D}_X \otimes_{\mathcal{O}_X} \wedge^n \mathcal{I}_X \rightarrow \cdots \rightarrow \mathcal{D}_X \otimes_{\mathcal{O}_X} \wedge^2 \mathcal{I}_X &\longrightarrow \mathcal{D}_X \otimes_{\mathcal{O}_X} \mathcal{I}_X \longrightarrow \mathcal{D}_X \rightarrow \mathcal{O}_X = \mathcal{D}_X / \mathcal{D}_X \cdot \mathcal{I}_X \\ P \otimes v &\longmapsto P \cdot v \\ P \otimes (v_1 \wedge v_2) &\longmapsto P v_1 \otimes v_2 - P v_2 \otimes v_1 \\ &\quad - P \otimes [v_1, v_2] \end{aligned}$$

and

$$\underbrace{\mathcal{D}_X = \Omega_X^0 \otimes_{\mathcal{O}_X} \mathcal{D}_X \rightarrow \cdots \rightarrow \Omega_X^{n-1} \otimes_{\mathcal{O}_X} \mathcal{D}_X \rightarrow \Omega_X^n \otimes_{\mathcal{O}_X} \mathcal{D}_X \rightarrow \mathcal{D}_X \text{DR}(\mathcal{D}_X)}_{\text{the de Rham complex of } \mathcal{D}_X \text{ thought of as a } \mathcal{D}_X\text{-module.}} \rightarrow \Omega_X^n$$

The proof of these claims reduces to the commutative case. I.e. equip everything with compatible good filtrations. Then take associated graded – you will see this is

$$i_* \mathcal{O}_X \in \mathcal{O}_{T^*X}\text{-mod},$$

where $i : X \hookrightarrow T^*X$ is the zero section.

Why is this enough? There is an algebraic lemma to prove: if you have a good filtered complex of \mathcal{D} -modules, it is exact iff its associated graded is exact. This is a common technique – reduce a non-commutative problem to a problem in the associated graded.

So, we now have a quasi-isomorphism (so equality in the derived category)

$$\Omega_X^n \otimes_{\mathcal{D}_X}^L \mathcal{M} \simeq (\Omega_X^\bullet \otimes_{\mathcal{O}_X} \mathcal{D}_X) \otimes_{\mathcal{D}_X} \mathcal{M} = \Omega_X^\bullet \otimes_{\mathcal{O}_X} \mathcal{M} = \text{DR}(\mathcal{M}).$$

Caution: We have changed out grading convention. Now, $\text{DR}(\mathcal{M})$ is concentrated in degrees $-n, -n + 1, \dots, 0$.

Now, to compute $p_*^{\text{dR}}(\mathcal{M})$ we take the pushforward, i.e.

$$p_*^{\text{dR}}(\mathcal{M}) = R\Gamma(\text{DR}(\mathcal{M})).$$

Think: Analogue/generalization of taking the de Rham cohomology.

Example 82. Let $\mathcal{M} = \mathcal{O}_X$. Then

$$\text{DR}(\mathcal{M}) = \mathcal{O}_X \rightarrow \Omega_X^1 \rightarrow \Omega_X^2 \rightarrow \cdots \rightarrow \Omega_X^n \rightarrow 0$$

$\quad \quad \quad -n \quad \quad -n+1 \quad \quad -n+2$

Without the grading shift, this is a resolution of the constant sheaf, i.e.

$$\text{DR}(\mathcal{O}_X) \simeq \mathbb{C}_X[n].$$

Then

$$p_*^{\text{dR}}(\mathcal{O}_X) = R\Gamma(X; \mathbb{C}_X[n]) = \underbrace{H^{*-n}(X; \mathbb{C})}_{\text{in degrees } -n \text{ to } n}$$

Remark This will make Poincaré duality look symmetric around 0.

Remark Could play the same game with \mathcal{O}_X replaced by a local system.

More generally, suppose $f : X \rightarrow Y$ is smooth (i.e. is a submersion – this is smoothness in the algebraic geometric sense). We define $\Omega_{X/Y}^1$ as

$$0 \rightarrow f^*\Omega_Y^1 \rightarrow \Omega_X^1 \rightarrow \Omega_{X/Y}^1 \rightarrow 0.$$

Locally (by the implicit function theorem) $X \cong Y \times Z$, so $\Omega_{X/Y}^1$ has elements of the form $f(y, z)dz$. Then we can form

$$\Omega_{X/Y}^k = \bigwedge_{\mathcal{O}_X}^k \Omega_{X/Y}^1,$$

which carries a de Rham differential $d_{X/Y}$ (apparent from the local form of the elements).

Proposition 14.5.

$$f_*^{\text{dR}}(\mathcal{M}) = Rf_*(DR_{X/Y}(\mathcal{M})).$$

Remark For any $f : X \rightarrow Y$ we can factor as

$$X \xrightarrow{\Gamma_f} X \times Y \xrightarrow{p_2} Y,$$

a closed embedding (via the graph of f) followed by a submersion.

Remark We say a submersion is smooth because the fibres have the structure of a smooth manifold – describing a map by the properties of its fibres is a general principle in algebraic geometry.

Let $f : X \rightarrow Y$ be smooth. Then we have

$$\begin{array}{ccc} & T^*Y \times_Y X & \\ \rho_f \swarrow & & \searrow \varpi_f \\ T^*X & & T^*Y \end{array}$$

- Proposition 14.6.**
- (1) $f^\circ : \mathcal{D}_Y\text{-mod} \rightarrow \mathcal{D}_X\text{-mod}$ is exact (so $f^\dagger \simeq f^\circ$).
 - (2) f° preserves coherent \mathcal{D} -modules.
 - (3) $SS(f^\circ \mathcal{M}) = \rho_f \varpi_f^{-1}(SS(\mathcal{M}))$.
 - (4) $f^\dagger[-d]$ is left adjoint to f_*^{dR} , where d is the relative dimension of f .

Example 83. Consider $X \rightarrow \text{pt}$. The singular support must lie in the zero section, as shown in Figure 35.

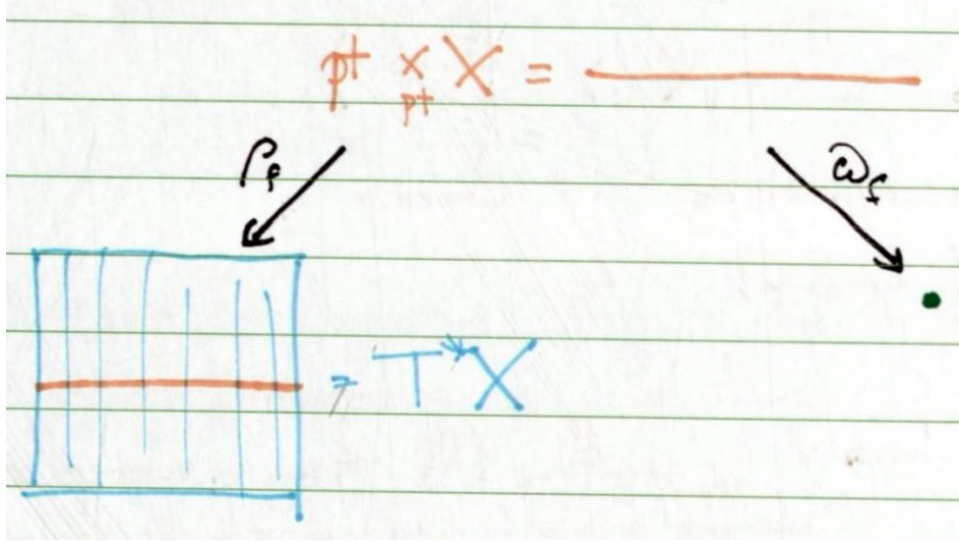


FIGURE 35. Correspondence for $X \rightarrow \text{pt}$. $\text{pt} \times_{\text{pt}} X \cong X$, so by the proposition $SS(p^* \mathcal{M}) \subseteq X \subset T^* X$.

In this case, observe that ρ_f is a closed embedding and ϖ_f is smooth.

Proof of part 1. When f is smooth it is in particular flat, so \mathcal{O}_X is flat as an $f^{-1}\mathcal{O}_Y$ -module. Thus f^* is exact. \square

We defer the rest of the proof to later.

15. (VERDIER) DUALITY FOR \mathcal{D} -MODULES.

Let $\mathcal{M} \in \mathcal{D}_X\text{-mod}$. We want to define a dual to \mathcal{M} , so our first obvious guess is

$$R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{D}_X).$$

This is a *right* \mathcal{D}_X -module; i.e. a $\mathcal{D}_X^{\text{op}}$ -module. To get a left \mathcal{D}_X -module, tensor with the inverse of the dualizing sheaf,

$$R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{D}_X) \otimes_{\mathcal{O}_X} (\Omega_X^n)^\vee \in \mathcal{D}_X\text{-mod}.$$

Define

$$\mathbb{D}_X(\mathcal{M}) := (R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{D}_X) \otimes_{\mathcal{O}_X} (\Omega_X^n)^\vee)[\dim X].$$

Example 84. Let $X = \mathbb{C}$, $\mathcal{M}_P = \mathcal{D}_X / \mathcal{D}_X \cdot P$, $P \in \mathcal{D}_X$. Then there is a quasi-isomorphism

$$\mathcal{M}_P \simeq \mathcal{D}_X \begin{array}{c} \xrightarrow{P} \\ -1 \quad 0 \end{array} \mathcal{D}_X.$$

So

$$\begin{aligned} R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}_P, \mathcal{D}_X) &= \mathcal{H}om_{\mathcal{D}_X}(\mathcal{D}_X \begin{array}{c} \xrightarrow{P} \\ -1 \quad 0 \end{array} \mathcal{D}_X, \mathcal{D}_X) \\ &= \mathcal{D}_X \begin{array}{c} \xrightarrow{P} \\ 0 \quad 1 \end{array} \mathcal{D}_X \end{aligned}$$

Definition 40. For $\mathcal{M} \in \mathcal{D}_X\text{-mod}$ and $\mathcal{N} \in \mathcal{D}_X^{\text{op}}\text{-mod}$, define

$$\begin{aligned} \mathcal{M}^r &= \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^n \in \mathcal{D}_X^{\text{op}}\text{-mod} \\ \mathcal{N}^l &= (\Omega_X^n)^\vee \otimes_{\mathcal{O}_X} \mathcal{N} \in \mathcal{D}_X\text{-mod} \end{aligned}$$

Since $\Omega_X^n \cong \mathcal{O}_X$ for $X = \mathbb{C}$, we therefore have

$$\mathbb{D}_X(\mathcal{M}_P) = \mathcal{D}_X/\mathcal{D}_X \cdot P^*,$$

in degree 0 due to the degree shift in the definition. Here P^* is the adjoint of P – recall that there is a nontrivial isomorphism

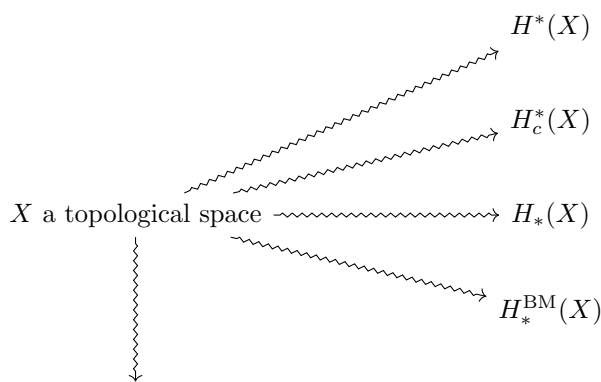
$$\begin{aligned} \mathcal{D}_X &\xrightarrow{\sim} \mathcal{D}_X^{\text{op}} \\ x &\longmapsto x \\ \partial_x &\longmapsto -\partial_x \\ x\partial_x &\longmapsto -\partial_x \cdot x \end{aligned}$$

and P^* is the image of P under this map.

Proposition 15.1. *Let $D_{\text{coh}}^b(\mathcal{D}_X)$ be the derived category of complexes of \mathcal{D}_X -modules with coherent cohomology. Then*

- $\mathbb{D}_X : D_{\text{coh}}^b(\mathcal{D}_X) \xrightarrow{\sim} D_{\text{coh}}^b(\mathcal{D}_X)^{\text{op}}$.
- $\mathbb{D}_X \circ \mathbb{D}_X \simeq \text{id}_X$.
- \mathcal{M} is holonomic (in degree 0) if and only if $\mathbb{D}_X(\mathcal{M})$ is in degree 0.

15.1. **Big Picture.** We started the semester with sheaves on a space X :



$D^b(\mathbb{C}_X)$, the derived category of sheaves on X .

The 6-functor formalism gave us a nice framework by which to perform calculations in topology: recall that given $f : X \rightarrow Y$ we had functors

$$Rf_*, \quad Rf_!, \quad f^*, \quad f^!,$$

where

- Rf_* is right adjoint to f^* , and
- $Rf_!$ is left adjoint to $f^!$.

There is also a duality functor, \mathbb{D}_X . Its cohomology sheaves $\mathcal{H}^i \mathbb{D}_X(\mathcal{F})$ are given by the sheafification of

$$U \mapsto H_c^i(U; \mathcal{F})^\vee.$$

We constructed $\mathbb{D}_X(\mathbb{C}_X) = \omega_X$. Then

$$\mathbb{D}_X(\mathcal{F}) = R\mathcal{H}om_{\mathbb{C}_X}(\mathcal{F}, \omega_X).$$

It is useful to use this duality functor to talk about relations between our functors. To do this we have to restrict the category we look at:

$D_c^b(\mathbb{C}_X) =$ bounded derived category of constructible complexes (with respect to *some* stratification).

Then \mathbb{D}_X gives an equivalence

$$\mathbb{D}_X : D_c^b(\mathbb{C}_X) \xrightarrow{\sim} D_c^b(\mathbb{C}_X)^{\text{op}}, \quad \mathbb{D}_X \circ \mathbb{D}_X \simeq \text{id}.$$

This is a **quite nontrivial** self-duality.

Example 85. $\mathbb{D}_X(\mathbb{C}_X) = \omega_X$, and $\text{Hom}(\mathcal{F}, \mathcal{G}) = \text{Hom}(\mathbb{D}\mathcal{G}, \mathbb{D}\mathcal{F})$.

Fact/slogan: Commuting past the duality functor turns $!$ into $*$,

- $Rf_* \circ \mathbb{D}_X \simeq \mathbb{D}_Y \circ Rf_!$.
- $f^* \circ \mathbb{D}_Y \simeq \mathbb{D}_X \circ f^!$.

This will, for instance, swap various kinds of (co)homology around. So this is a “sheafy” version of Poincaré duality.

Definition 41. \mathbb{D}_X is called the *Verdier duality functor*.

We would like a similarly nice (6 functor) formalism for \mathcal{D} -modules. As motivations, recall the picture of the Riemann-Hilbert correspondence (Figure 36).

Example 86. Given $f : \mathbb{C}^N \rightarrow \mathbb{C}$ a holomorphic function, consider $f^{-1}(0) = Z \subseteq \mathbb{C}^N$. Supposing some niceness properties (e.g. 0 an isolated singular value), we had some nice properties of the following functors and sheaves/ For instance, consider

$$Rf_*(\mathbb{C}_{\mathbb{C}^N}) \in D_c^b(\mathbb{C}_{\mathbb{C}}).$$

We considered the fibre Z as the central fibre X_0 in a family as per Figure 37.

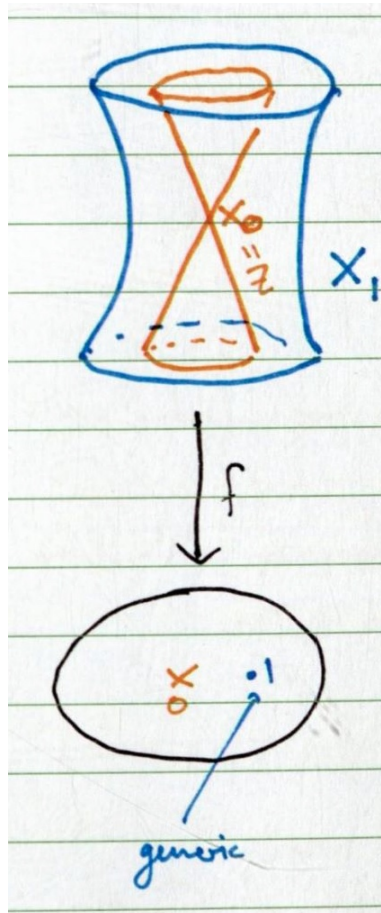


FIGURE 37. Studying a space Z as the central fibre in a family.

We then studied $Rf_*(\mathbb{C}_X)$, but also some more interesting sheaves of *vanishing* and *nearby* cycles, $\phi_f, \psi_f \in D_c^b(\mathbb{C}_{X_0})$.

To compute $f^!, f^*, Rf_*, Rf_!, \psi_f, \phi_f$, we will ask what they correspond to under the Riemann-Hilbert correspondence. We will also ask what the singular support $SS(\mathcal{M})$ of a \mathcal{D} -module corresponds to under Riemann-Hilbert.

Plan:

- Functoriality for coherent and holonomic \mathcal{D} -modules.
- Regular singularities, Riemann-Hilbert.
- Perverse sheaves, intersection cohomology.
- V -filtration, nearby and vanishing cycles, specialization to the normal cone.

15.1.1. *Aside: Algebraic versus analytic \mathcal{D} -modules.* We've been talking about X a complex manifold, with sheaves \mathcal{O}_X of holomorphic functions and \mathcal{D}_X of holomorphic differential operators.

We could instead have started with X a smooth algebraic variety (over \mathbb{C}). Then talking complex points gives a complex manifold, but this does not have a converse – e.g. the disk $\Delta = \{x \mid |x| < 1\}$ is not an algebraic variety.

X a complex manifold (complex topology)	X a smooth algebraic variety over \mathbb{C} (Zariski topology)
$\mathcal{O}_X^{\text{an}}$ holomorphic functions	$\mathcal{O}_X^{\text{alg}}$ algebraic functions
$\mathcal{D}_X^{\text{an}}$ holomorphic differential operators	$\mathcal{D}_X^{\text{alg}}$ algebraic differential operators

TABLE 1. Algebraic versus analytic comparison.

Example 87. $X = \mathbb{C}^n = \mathbb{A}^n \supset U_f = \mathbb{A}^n - \{f = 0\}$. Then²

$$\begin{aligned} \mathcal{O}_X^{\text{alg}} &= \mathbb{C}[x_1, \dots, x_n] \\ \mathcal{O}_X^{\text{alg}}(U_f) &= \mathbb{C}[x_1, \dots, x_n][f^{-1}]. \end{aligned}$$

This is manifestly a much smaller space than $\mathcal{O}_X^{\text{an}}$, the holomorphic functions on \mathbb{C}^n .

Now, $\mathcal{D}_X^{\text{an}}$ contains elements of the form

$$\sum_i f_i(x) \partial^i$$

where the f_i are holomorphic functions – i.e. elements which are a power series in x and a polynomial in ∂ . The description of $\mathcal{D}_X^{\text{alg}}$ is much simpler. For example, we can present it in terms of generators and relations:

$$\mathcal{D}_X^{\text{alg}} = \mathbb{C}\langle x_1, \dots, x_n, \partial_1, \dots, \partial_n \rangle / \sim, \quad [\partial_i, x_j] = \delta_{ij}, \quad [x_i, x_j] = 0 = [\partial_i, \partial_j].$$

15.2. **Base change for \mathcal{D} -module functors.** Given $f : X \rightarrow Y$, we produced

$$\begin{array}{ccc} & \xrightarrow{f_*^{\text{dR}}} & \\ D^b(\mathcal{D}_X) & & D^b(\mathcal{D}_Y) \\ & \xleftarrow{f_{\text{dR}}^!} & \end{array}$$

where $f_{\text{dR}}^! := f^{\dagger}[\dim X - \dim Y]$. **Warning:** Recall that these are not necessarily adjoint.

Consider the base change

$$\begin{array}{ccc} X' = X \times_Y Y' & \xrightarrow{\tilde{g}} & X \\ \downarrow \tilde{f} & & \downarrow f \\ Y' & \xrightarrow{g} & Y \end{array}$$

²Abusing notation by conflating a sheaf with its global sections – okay since we are working with affine varieties.

Theorem 15.2 (Base Change Theorem). $f_{dR}^! g_*^{dR} \simeq \tilde{g}_*^{dR} f_{dR}^!$.

There are two special cases:

- f is *proper* (e.g. f is a closed embedding).
 - f_*^{dR} will preserve *coherent* complexes.
 - f_*^{dR} is *left adjoint* to $f_{dR}^!$.
 - $f_*^{dR} \circ \mathbb{D}_X \simeq \mathbb{D}_Y \circ f_*^{dR}$.
- f is *smooth* (i.e. a submersion) of relative dimension d .
 - $f_{dR}^!$ will preserve coherent complexes.
 - $f_{dR}^![-2d]$ is *left adjoint* to f_*^{dR} .
 - $f_{dR}^! \circ \mathbb{D}_Y \simeq \mathbb{D}_X \circ f_{dR}^![-2d]$.
 - We have

$$f_{dR}^* = f^\dagger[-d] \quad \text{and} \quad f_{dR}^! = f^\dagger[d].$$

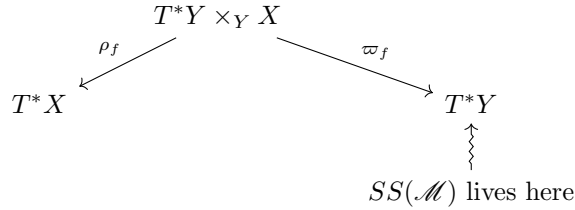
- f^\dagger is *exact*.

16. INTERPRETATION OF SINGULAR SUPPORT.

Question: What does $SS(\mathcal{M})$ mean?

Answer (to be explained): It measures directions in X for which solutions to \mathcal{M} propagate.

Let $f : X \rightarrow Y$, X, Y complex manifolds (working in the analytic setting). We have



Fix $\mathcal{M} \in (\mathcal{D}_Y\text{-mod})_{\text{coh}}$.

Definition 42. f is called *noncharacteristic* for \mathcal{M} if

$$\varpi_f^{-1}(SS(\mathcal{M})) \cap \overset{\circ}{T}_X^*Y = \emptyset.$$

Here $T_X^*Y = \ker(\rho_f)$ (a vector bundle on X , and

$$\overset{\circ}{T}_X^*Y = T_X^*Y - \{0\text{-section}\}.$$

If $X \hookrightarrow Y$ is a closed embedding, T_X^*Y is called the *conormal bundle* of $X \hookrightarrow Y$. Another way of understanding this in the closed embedding case is as:

$$\varpi_f^{-1}(SS(\mathcal{M})) \cap T_X^*Y \subseteq 0\text{-section}.$$

Example 88. If f is smooth (submersion) then

$$T_X^*Y = \{0\} \times X.$$

Thus f is noncharacteristic for any \mathcal{M} .

Example 89. If $SS(\mathcal{M}) = T_Y^*Y = 0\text{-section}$, any f is noncharacteristic for \mathcal{M} .

Example 90. Consider

$$\begin{array}{ccc}
 X & \xleftarrow{f} & Y \\
 & & \uparrow g \\
 & & Z
 \end{array}$$

where f and g are both closed embeddings. Let $\mathcal{M} = f_*^{\text{dR}}(\mathcal{O}_X)$. When is Z a noncharacteristic submanifold for \mathcal{M} (i.e. when is g noncharacteristic for \mathcal{M})?

Recall from a previous lecture that

$$SS(\mathcal{M}) = T_X^*Y.$$

This is noncharacteristic if and only if

$$\varpi_g^{-1}(T_X^*Y) \cap (T_Z^*Y) = 0\text{-section},$$

if and only if

$$(T_X^*Y)_x \cap (T_Z^*Y)_x = 0 \quad \text{for all } x \in Z \cap X.$$

I.e. $SS(\mathcal{M})$ is noncharacteristic if and only if $X \pitchfork Z$, as in Figure 38.

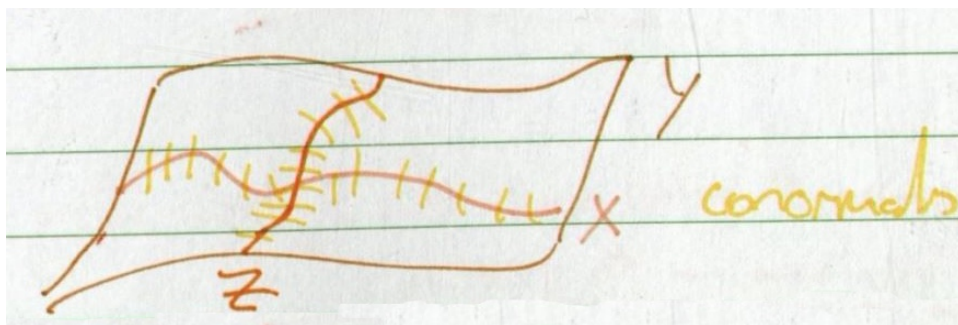


FIGURE 38. Transverse embedded submanifolds with their conormal bundles.

Theorem 16.1. *Suppose $f : X \rightarrow Y$ is noncharacteristic for \mathcal{M} .*

- (1) $f^\dagger(\mathcal{M}) = \mathcal{H}^0 f^\dagger(\mathcal{M}) = f^\circ(\mathcal{M})$ (concentrated in degree zero – i.e. not being concentrated in degree zero is a non-transversality condition).
- (2) $f^\dagger(\mathcal{M})$ is a coherent \mathcal{D}_X -module.
- (3) $SS(f^\dagger \mathcal{M}) = \rho_f(\varpi_f^{-1}(SS(\mathcal{M})))$.
- (4) $f^\dagger(\mathbb{D}_Y \mathcal{M}) \cong \mathbb{D}_X(f^\dagger \mathcal{M})$.

Recall:

- $f^\dagger(\mathcal{M}) = \mathcal{O}_X \otimes_{f^{-1}\mathcal{O}_Y} f^{-1}\mathcal{M}$.
- $f_{\text{dR}}^!(\mathcal{M}) = f^\dagger(\mathcal{M})[\dim(X) - \dim(Y)]$.

In general, f^\dagger (or $f_{\text{dR}}^!$) does not preserve coherence.

Example 91. $i : \{0\} \hookrightarrow \mathbb{A}^1$ induces $i^\dagger(\mathcal{D}_{\mathbb{A}^1})$, which is infinite dimensional.

Upshot: When is it reasonable to restrict coherent \mathcal{D} -modules as above? When the \mathcal{D} -module is *noncharacteristic*.

Remark The above theorem still makes sense in the algebraic setting – it might even be easier to prove there.

Theorem 16.2 (Cauchy-Kovalevskaya-Kashiwara). *Let $f : X \rightarrow Y$ be noncharacteristic for \mathcal{M} , then*

$$\text{Sol}_X(f^\dagger \mathcal{M}) = f^{-1} \text{Sol}_Y(\mathcal{M}).$$

Recall that

$$\text{Sol}_Y(\mathcal{M}) = R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{O}_Y).$$

Motivated by: $\mathcal{M} = \mathcal{D}_X/\mathcal{D}_X \cdot P$, where we interpret

$$\text{Sol}_X(\mathcal{M}) = \{u \mid Pu = 0\}.$$

Consider the special case (the general proof always reduces to this special case):

$$\begin{aligned} X &\subseteq Y \text{ a hypersurface,} \\ \mathcal{M} &= \mathcal{D}_Y/\mathcal{D}_Y \cdot P, \quad P \in \mathcal{D}_Y. \end{aligned}$$

Everything is local, so choose coordinates y_1, \dots, y_n on X such that

$$X = \{y_1 = 0\} \subseteq Y.$$

What does it mean for X to be noncharacteristic for \mathcal{M} (this should be some condition on the differential operator P)? Recall that

$$SS(\mathcal{M}) = V(\sigma_m(P)), \quad \text{where } P \text{ is of order } m.$$

Let $\xi = \sigma(\partial)$ (a function on the cotangent bundle), and write

$$\begin{aligned} P &= \sum_{|\alpha| \leq m} a_\alpha(y) \partial^\alpha \\ \sigma_m(P) &= \sum_{|\alpha|=m} a_\alpha(y) \xi^\alpha. \end{aligned}$$

X is noncharacteristic for \mathcal{M} (or for P) iff for all $\xi \in \mathring{T}_X^*Y$ $\sigma_m(P)(\xi) \neq 0$, iff

$$\sigma_m(P) = (0, y_2, \dots, y_n, 1, 0, \dots, 0) \neq 0.$$

(Here the first coordinate is 0 since we are on X , and consequently the only conormal direction to X is in the ξ^1 position.) In coordinates we write P as

$$P = \sum a_{\alpha_1, \dots, \alpha_n}(y_1, \dots, y_n) \partial_{y_1}^{\alpha_1} \cdots \partial_{y_n}^{\alpha_n}.$$

So the above condition means

$$a_{m, 0, \dots, 0}(0, y_2, \dots, y_n) \neq 0.$$

Looking in a neighbourhood of X , then, we can invert this term so that, without loss of generality,

$$P = \partial_1^m + (\text{lower order terms in } \partial_1).$$

So: X being noncharacteristic for P of order m means that P is m^{th} order in the X direction, plus (potentially) other terms in other directions.

So, consider the claims of the theorem. We have

$$f^\dagger(\mathcal{M}) = \mathcal{M} \xrightarrow{y_1 \cdot} \mathcal{M}_0.$$

This has potentially two cohomology groups. We want to show that $y_1 \cdot$ is injective. This would imply that

$$f^\dagger(\mathcal{M}) = f^\circ(\mathcal{M}) = \mathcal{M}/y_1 \mathcal{M} = \mathcal{D}_Y/(\mathcal{D}_Y \cdot P + y_1 \cdot \mathcal{D}_Y).$$

Claim:

$$\mathcal{D}_Y/(\mathcal{D}_Y \cdot P + y_1 \cdot \mathcal{D}_Y) \cong \mathcal{D}_X^{\oplus m}.$$

Example 92. Consider

$$f^\circ(\mathcal{M}) = \mathcal{D}_X[\partial_1]/\mathcal{D}_x[\partial_1] \cdot P.$$

Let $P = \partial_1^m$. Then we have that

$$f^\circ(\mathcal{M}) \cong \mathcal{D}_X^{\oplus m}.$$

In general,

$$1, \partial_1, \partial_1^2, \dots, \partial_1^{m-1} \quad \text{is a basis for } f^\circ(\mathcal{M}) \text{ as a } \mathcal{D}_X\text{-module.}$$

Let's pretend/assume that this corresponds to a proof of the first theorem we wrote down. What about the Cauchy-Kovalevskaya-Kashiwara theorem? The claim there was that

$$\begin{array}{ccc}
 f^{-1}\mathrm{Sol}_Y(\mathcal{M}) & \xrightarrow{\cong} & \mathrm{Sol}_X(f^\dagger \mathcal{M}) \\
 \parallel & & \updownarrow \cong \\
 f^{-1}R\mathcal{H}om_{\mathcal{D}_Y}(\mathcal{D}_Y/\mathcal{D}_Y \cdot P, \mathcal{O}_Y) & & R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{D}_X^{\oplus m}, \mathcal{O}_X) \\
 \mathcal{D}_Y \xrightarrow{-P} \mathcal{D}_Y \parallel \text{(use the 2 term free resolution)} & & \updownarrow \cong \\
 f^{-1}(\mathcal{O}_Y \xrightarrow{P(-)} \mathcal{O}_Y) & & \mathcal{O}_X^{\oplus m}
 \end{array}$$

The above map is then

$$\begin{array}{ccc}
 f^{-1}(\mathcal{O}_Y \xrightarrow{P(-)} \mathcal{O}_Y) & \longrightarrow & \mathcal{O}_X^{\oplus m} \\
 u \in \mathcal{O}_X & \longmapsto & (u|_X, \partial_1 u|_X, \dots, \partial_1^{m-1} u|_X)
 \end{array}$$

This isomorphism is essentially an existence and uniqueness statement for an m^{th} order boundary value problem:

Theorem 16.3 (Cauchy-Kovalevskaya). *The Cauchy problem*

$$\left\{ \begin{array}{l} Pu = 0 \\ u|_X = v_1 \\ \partial_1 u|_X = v_2 \\ \vdots \\ \partial_1^{m-1} u|_X = v_n \end{array} \right\} \text{ has a unique solution } u \in f^{-1}\mathcal{O}_Y.$$

(Here $P = \partial_1^m + \dots$ is noncharacteristic.)

To answer the question, “What does $SS(\mathcal{M})$ mean?”, we will need a variant of the Cauchy-Kovalevskaya theorem. Let $\phi : X \rightarrow \mathbb{R}$ be a C^∞ -function, X a complex manifold. Suppose

$$X_0 = \phi^{-1}(0) \text{ is a smooth real hypersurface.}$$

Let \mathcal{M} be a coherent \mathcal{D}_X -module such that

$$SS(\mathcal{M}) \cap \mathring{T}_{X_0}^*(X_{\mathbb{R}}) = \emptyset.$$

Remark This uses the identification

$$\begin{array}{ccc}
 (T^*X)_{\mathbb{R}} & \xrightarrow{\cong} & T^*(X_{\mathbb{R}}) \\
 (\partial\phi)_x & \longleftarrow & (d\phi)_x.
 \end{array}$$

Then

$$(R\Gamma_{X_{\geq 0}}(\mathrm{Sol}_X(\mathcal{M})))_{X_0} \simeq 0.$$

We can picture this as in Figure 39.

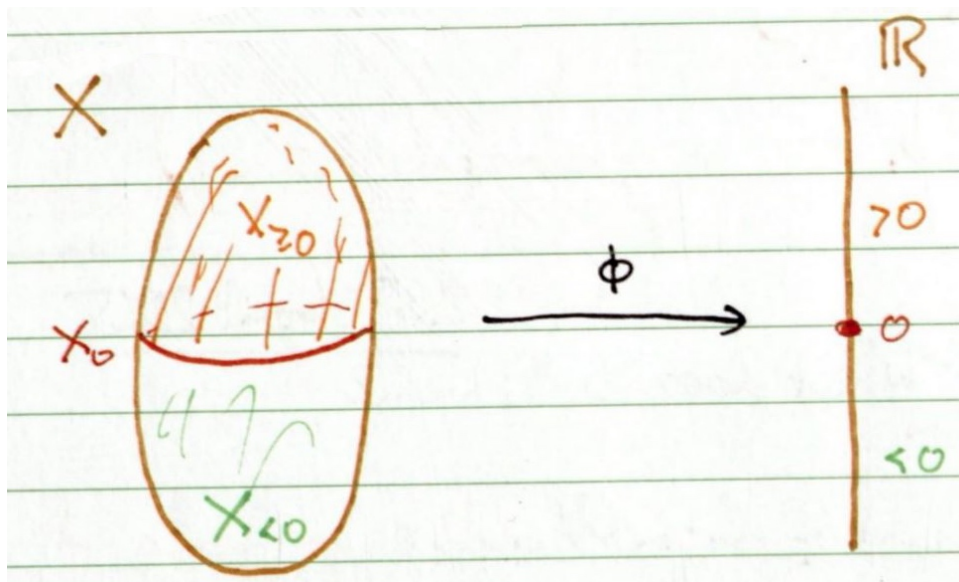


FIGURE 39. Solutions on $X_{<0}$ propagate across X_0 to solutions on $X_{>0}$.

Recall that if $k : W \hookrightarrow X$ is a locally closed embedding,

$$R\Gamma_W = Rk_*k^!, \quad (-)_W = Rk_!k^*.$$

We have a decomposition of our space into an open and a closed, so letting

$$\mathcal{F}^\bullet := \text{Sol}_X(\mathcal{M}),$$

we have an exact triangle

$$R\Gamma_{X_{\geq 0}}(\mathcal{F}^\bullet) \rightarrow \mathcal{F}^\bullet \rightarrow R\Gamma_{X_{< 0}}(\mathcal{F}^\bullet) \xrightarrow{+1}$$

Looking stalkwise we see that applying $(-)_X$ and using the theorem gives

$$(R\Gamma_{X_{\leq 0}}(\mathcal{F}^\bullet))_{X_{\leq 0}} = 0,$$

so,

$$(\mathcal{F}^\bullet)_{\leq 0} \xrightarrow{\sim} R\Gamma_{X_{\leq 0}}(\mathcal{F}^\bullet).$$

We interpret this as saying that (holomorphic) solutions to \mathcal{M} on $X_{<0}$ extend (to holomorphic solutions) over X_0 .

Meaning: Solution to \mathcal{M} on $X_{<0}$ can propagate over a “small” neighbourhood of X_0 . The proof of this involves reducing to the case

$$\mathcal{M} = \mathcal{D}_X / \mathcal{D}_X \cdot P,$$

then expressing the result as a Cauchy problem.

16.1. Microsupport.

Definition 43. Let $\mathcal{F} \in D^b(\mathbb{C}_X)$, X a $C^\infty_{\mathbb{R}}$ -manifold. Define the *microsupport* of \mathcal{F} , $\mu s(\mathcal{F})$ as follows. $\mu s(\mathcal{F}) \subseteq T^*X$, and

$T^*X \ni (x_0, \xi_0) \notin \mu s(\mathcal{F})$ if and only if there exists an open set $U \subseteq T^*X$ with $(x_0, \xi_0) \in U$ such that for all $x \in X$ and $\phi : X \rightarrow \mathbb{R}$ a smooth function with $\phi(x) = 0$, $(d\phi)_x \in U$, we have that $R\Gamma_{\phi \geq 0}(\mathcal{F}) \simeq 0$.

Theorem 16.4. If \mathcal{M} is a coherent \mathcal{D}_X -module, then

$$SS(\mathcal{M}) = \mu s(\text{Sol}_X(\mathcal{M})).$$

The generalized Cauchy-Kovalevskaya theorem provides $SS(\mathcal{M}) \supseteq \mu s(\text{Sol}_X(\mathcal{M}))$. The other direction is harder, and we omit it.

Recall that

$$\text{Sol}_X(\mathcal{M}) = R\mathcal{H}om_{\mathcal{D}_X}(\mathcal{M}, \mathcal{O}_X).$$

Example 93. Let $\mathcal{M} = \mathcal{O}_X$ and recall that there exists a resolution of \mathcal{O}_X as a \mathcal{D}_X -module, $\mathcal{D}_X \otimes_{\mathcal{O}_X} (\Omega_X^\bullet)$. Then

$$\begin{aligned} \text{Sol}_X(\mathcal{O}_X) &\simeq \Omega_X^\bullet \simeq \mathbb{C}_X, \quad (\text{by the Poincaré lemma}), \text{ so,} \\ SS(\mathcal{O}_X) &= X \subseteq T^*X. \end{aligned}$$

Example 94. Let $\mathcal{M} = \mathcal{D}_X$. Then $\text{Sol}_X(\mathcal{D}_X) = \mathcal{O}_X$ – remember this is *not* as a \mathcal{D} -module, it is as the sheaf of solutions to a \mathcal{D} -module. Recall that

$$SS(\mathcal{D}_X) = T^*X.$$

Then $\mu s(\mathcal{O}_X) = T^*X$. I.e. there are no directions in which $\text{Sol}_X(\mathcal{D}_X)$ looks like \mathbb{C}_X . So given holomorphic functions on some (open) domain with boundary, there will always be solutions that become singular on the boundary. Phrased another way:

$$\mathcal{O}_X(X_{\leq 0}) \rightarrow \mathcal{O}_X(X_{< 0}) \text{ is never an isomorphism.}$$

Exercise 16.1. Determine what $\mu s(\mathcal{F})$ is measuring for points $(x_0, 0) \in T^*X$.

16.2. Holonomic complexes. Suppose $\mathcal{M} \in \mathcal{D}_{\text{hol}}^b(\mathcal{D}_X)$, complexes of \mathcal{D}_X -modules with holonomic cohomology sheaves. Recall \mathcal{M} holonomic means that $SS(\mathcal{M}) \subseteq T^*X$ is Lagrangian. We can write

$$SS(\mathcal{M}) := \bigcup_i SS(\mathcal{H}^i(\mathcal{M})) = \Lambda = \bigcup_j \Lambda_j$$

where Λ is a conic Lagrangian, and the Λ_j are irreducible Lagrangians.

Example 95. See Figure 40.

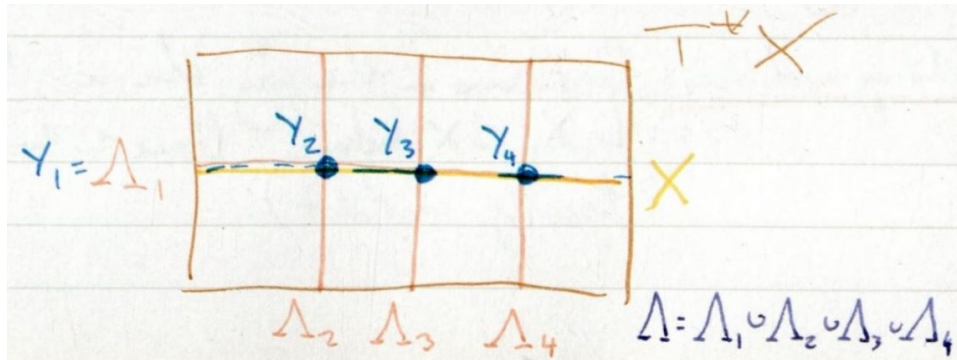


FIGURE 40. Decomposition of the singular support into irreducible Lagrangians.

Define

$$Y_i = \pi_X(\Lambda_i) = \Lambda_i \cap X,$$

some closed analytic irreducible subsets of X .

Lemma 16.5. $\Lambda_i = \overline{T_{Y_i}^* X}$.

Idea: The Y_i are giving a stratification on which solutions to \mathcal{M} are locally constant.

Theorem 16.6. *Given a conic Lagrangian Λ , there exists a Whitney stratification of X ,*

$$X = \coprod_j X_j, \quad X_j \text{ smooth},$$

such that each Y_i is a union of some X_j .

Corollary 16.7. $\Lambda \subseteq \bigcup T_{X_i}^* X$.

Whitney conditions: These are conditions on the way the normal bundles to $X_j \subset X$ behave (roughly, they have to look locally constant).

Proposition 16.8. *If \mathcal{M} is a holonomic \mathcal{D}_X -module, $\mathcal{F} = \text{Sol}_X(\mathcal{M}) \in D^b(\mathbb{C}_X)$, and $\mu s(\mathcal{F}) = \Lambda$ is a conic Lagrangian, then \mathcal{F} is constructible with regards to X_j . I.e. $\mathcal{H}^k(\mathcal{F})|_{X_j}$ is locally constant with finite dimensional fibres.*

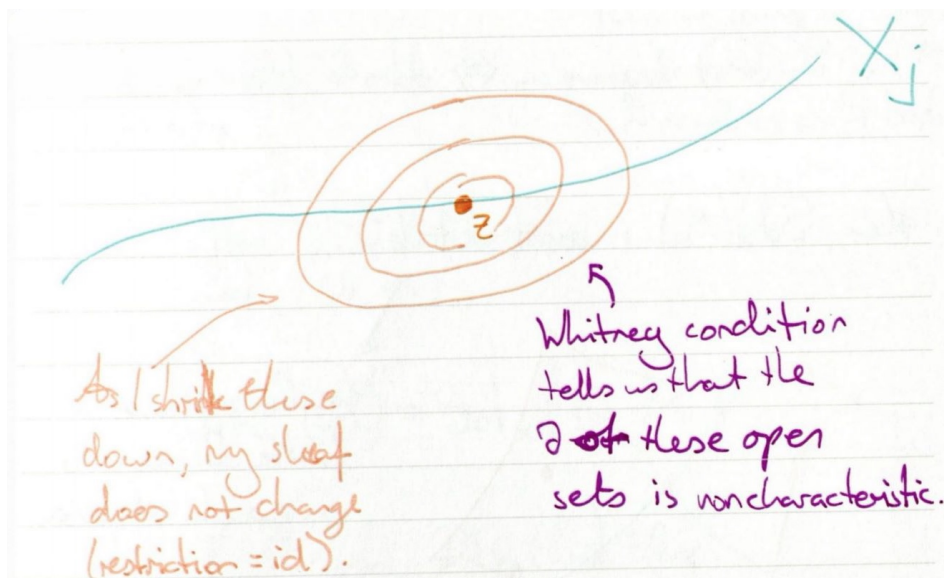


FIGURE 41. Rough picture of the Whitney condition.

17. REGULAR SINGULARITIES.

We have now seen that if \mathcal{M} is holonomic, then $\text{Sol}_X(\mathcal{M})$ is constructible (locally constant and finite dimensional on each stratum, see Figure 42). We use this fact to motivate a new class of \mathcal{D} -modules – those with *regular singularities*.

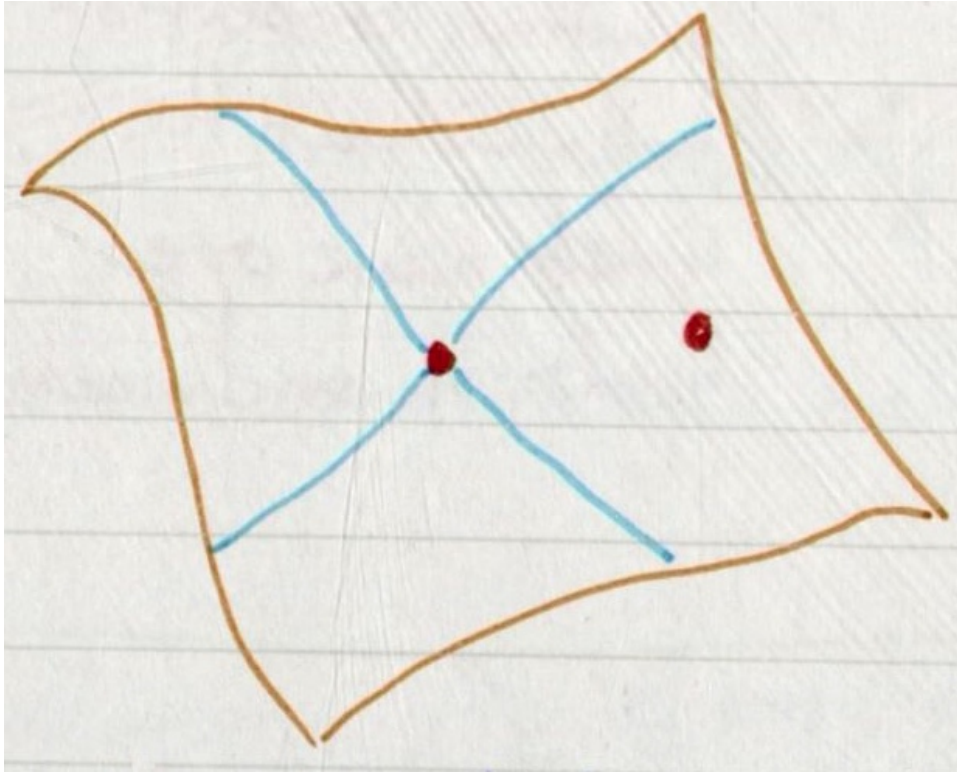


FIGURE 42. Stratification for a constructible sheaf.

Recall:

$$\mathrm{DR}_X(\mathcal{M}) = \mathcal{M} \underset{-n}{\overset{d}{\rightarrow}} \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^1 \underset{-n+1}{\rightarrow} \cdots \rightarrow \mathcal{M} \otimes_{\mathcal{O}_X} \Omega_X^n \underset{0}{\rightarrow}$$

We can identify this with

$$\mathrm{DR}_X(\mathcal{M}) = R\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{O}_X, \mathcal{M})[n].$$

How?

- \mathcal{O}_X has a resolution by free \mathcal{D}_X -modules

$$(\mathcal{D}_X \otimes_{\mathcal{O}_X} \bigwedge_{-n}^n \mathcal{T}_X \rightarrow \cdots \rightarrow \mathcal{D}_X \otimes_{\mathcal{O}_X} \bigwedge_{-2}^2 \mathcal{T}_X \rightarrow \mathcal{D}_X \otimes_{\mathcal{O}_X} \mathcal{T}_X \rightarrow \mathcal{D}_X \underset{0}{\rightarrow}) \xrightarrow{\sim} \mathcal{O}_X \underset{0}{\rightarrow}$$

- So taking homs from this resolution by free \mathcal{D}_X -modules, we can move polyvector fields from the LHS to its dual (forms) on the RHS. Then to agree with the degrees of $\mathrm{DR}_X(\mathcal{M})$ we need to shift back down by n .

Now applying Verdier duality,

$$R\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{O}_X, \mathcal{M})[n] = R\mathrm{Hom}(\mathbb{D}_X \mathcal{M}, \underbrace{\mathbb{D}_X \mathcal{O}_X}_{\mathcal{O}_X})[n] = \mathrm{Sol}_X(\mathbb{D}_X \mathcal{M}),$$

so,

$$\mathrm{DR}_X(\mathcal{M}) = \mathrm{Sol}_X(\mathbb{D}_X \mathcal{M}).$$

Example 96. If $\mathcal{M} = \mathcal{O}_X$, $\mathrm{DR}_X(\mathcal{O}_X) \simeq \mathbb{C}_X$. So we have a functor

$$\begin{array}{ccc}
 D_{\mathrm{coh}}^b(\mathcal{D}_X) & \xrightarrow{\mathrm{DR}_X} & D^b(\mathbb{C}_X) \\
 \uparrow & & \uparrow \\
 D_{\mathrm{hol}}^b(\mathcal{D}_X) & \xrightarrow{\text{essentially surjective}} & D_c^b(\mathbb{C}_X) \\
 \uparrow & & \\
 D_{\mathrm{rs}}^b(\mathcal{D}_X) & &
 \end{array}$$

where the bottom most category is the bounded derived category of \mathcal{D}_X -modules with *regular singularities*.

Definition 44. A holonomic \mathcal{D}_X -module \mathcal{M} has *regular singularities* at $x \in X$ if

$$\mathrm{Sol}_X(\mathcal{M})_x \xrightarrow{\sim} \widehat{\mathrm{Sol}}_X(\mathcal{M})_x \stackrel{\text{defn}}{=} \mathrm{Hom}_{\mathcal{D}_{X,x}}(\mathcal{M}_x, \underbrace{\widehat{\mathcal{O}}_{X,x}}_{\mathbb{C}[[x_1, \dots, x_n]]})$$

\uparrow
 “Formal solutions of \mathcal{M} .”

I.e. “every formal solution has a positive radius of convergence”.

Warning: This is a definition for analytic and **not** algebraic \mathcal{D} -modules.

Then we define $D_{\mathrm{rs}}^b(\mathcal{D}_X)$ to be complexes with cohomology objects regular singular \mathcal{D}_X -modules (i.e. regular singular at every point).

Theorem 17.1 (Riemann-Hilbert Correspondence).

$$\mathrm{DR}_X : D_{\mathrm{rs}}^b(\mathcal{D}_X) \xrightarrow{\sim} D_c^b(\mathbb{C}_X)$$

is an equivalence of triangulated categories.

Remark We no longer have the flat connections $\leftrightarrow \pi_1$ -reps correspondence with complexes. Instead we need to look at the *exit path category*. See, e.g. [AFR].

Example 97. Let

$$\mathrm{Conn}(X) = \left\{ \begin{array}{l} \text{vector bundles on} \\ X \text{ with flat connections} \end{array} \right\} \subseteq D_{\mathrm{rs}}^b(\mathcal{D}_X).$$

Then

$$\begin{array}{ccc}
 \mathrm{Conn}(X) & \xleftarrow{\sim} & \{\text{locally constant sheaves}\} \\
 (\mathcal{V}, \nabla) & \longmapsto & \mathrm{DR}_X(\mathcal{V}, \nabla) \\
 (\mathcal{F} \otimes_{\mathbb{C}_X} \mathcal{O}_X, d) & \longleftarrow & \mathcal{F}[n]
 \end{array}$$

There is a Poincaré lemma that says $\mathrm{DR}_X(\mathcal{V}, \nabla)$ has no higher cohomology – it is all concentrated in degree $-n$, thus

$$\mathrm{DR}_X(\mathcal{V}, \nabla) \simeq \ker(\nabla)[n].$$

Remark The Riemann-Hilbert correspondence was proven independently by Mebkhout (1979) and Kashiwara (1980).

17.1. What does “regular singularities” mean?

Example 98. Let

$$\mathcal{M} = \mathcal{D}_X / \mathcal{D}_X \cdot P \simeq (\mathcal{D}_X \xrightarrow{P} \mathcal{D}_X),$$

(we have an easy free resolution in this case). So

$$\mathrm{Sol}_X(\mathcal{M}) \simeq \mathcal{O}_X \begin{array}{c} P(-) \\ \longrightarrow \\ 0 \end{array} \rightarrow \mathcal{O}_X \begin{array}{c} \\ \longrightarrow \\ 1 \end{array}.$$

Hence

$$\begin{aligned} \mathcal{H}^0 \mathrm{Sol}_X(\mathcal{M}) &= \ker(P) \\ \mathcal{H}^1 \mathrm{Sol}_X(\mathcal{M}) &= \mathrm{coker}(P) \end{aligned}$$

We can localize everything to look at germs of solutions around $x \in X$,

$$\begin{aligned} \mathrm{Sol}_X(\mathcal{M})_x &\simeq \mathcal{O}_{X,x} \begin{array}{c} P(-) \\ \longrightarrow \\ 0 \end{array} \rightarrow \mathcal{O}_{X,x} \begin{array}{c} \\ \longrightarrow \\ 1 \end{array} \\ \mathcal{H}^0 \mathrm{Sol}_X(\mathcal{M})_x &= \ker P \\ \mathcal{H}^1 \mathrm{Sol}_X(\mathcal{M})_x &= \mathrm{coker} P \end{aligned}$$

Formal solutions are:

$$\widehat{\mathrm{Sol}}_X(\mathcal{M})_x = \widehat{\mathrm{Sol}}_x(\mathcal{M}) = \widehat{\mathcal{O}}_{X,x} \xrightarrow{P} \widehat{\mathcal{O}}_{X,x}.$$

Assume X is 1d (so that \mathcal{M} can be holonomic), and since we are working locally, without loss of generality let $X = \mathbb{C}$. Then

$$\begin{aligned} \mathcal{O}_{X,x} = \mathcal{O} &= \mathbb{C}\{\{x\}\} \\ \widehat{\mathcal{O}}_{X,x} = \widehat{\mathcal{O}} &= \mathbb{C}[[x]]. \end{aligned}$$

Example 99. Let $P = x\partial_x - \lambda$. Since $x\partial_x(x^n) = nx^n$, x^n is an eigenvalue for $x\partial_x$. So the solution to $Pu = 0$ is $u = x^\lambda$ – if λ is non-integral this requires a choice of branch of log (solution only makes sense on some small simply connected region). How can we think of this?

$$\begin{array}{ccc} \vdots & & \vdots \\ x^4 & \xrightarrow{4-\lambda} & x^4 \\ x^3 & \xrightarrow{3-\lambda} & x^3 \\ x^2 & \xrightarrow{2-\lambda} & x^2 \\ x & \xrightarrow{1-\lambda} & x \\ 1 & \xrightarrow{-\lambda} & 1 \\ & \xrightarrow{P} & \end{array}$$

How do the kernel and cokernel compare for power series versus formal power series?

Case 1: $\lambda \notin \mathbb{Z}_{\geq 0}$; then all of the maps above are isomorphisms, so

$$\mathrm{Sol}_X(\mathcal{M})_x \simeq \widehat{\mathrm{Sol}}_X(\mathcal{M})_x \simeq 0.$$

Case 2: $n = \lambda \in \mathbb{Z}_{\geq 0}$. Then x^n is in the kernel of P , and in fact

$$\ker(P) = \mathbb{C}x^n.$$

Also, x^n is **not** in the image of P , so

$$\mathrm{coker}(P) \cong \mathbb{C}x^n.$$

This holds for $\mathbb{C}\{\{x\}\}$ and $\mathbb{C}[[x]]$. Thus,

$$\mathcal{D}/\mathcal{D} \cdot (x\partial_x - \lambda) = \mathcal{D} \cdot x^\lambda$$

is *regular* for every λ .

Example 100. $P = x^2\partial_x - 1$. $e^{\frac{1}{x}}$ is a solution – this has an essential singularity in the analytic sense. Looking at this:

- **Observation 1:** $\ker(P) = \ker(\widehat{P}) = 0$. Why? $e^{\frac{1}{x}}$ is the unique solution (to this first order ODE), but it is not holomorphic at 0. So $\ker(P) = 0$.
- **Observation 2:** \widehat{P} is an isomorphism.
- **Observation 3:** P is not surjective.

For \widehat{P} :

$$\begin{aligned} \widehat{P}(a_0 + a_1x + a_2x^2 + a_3x^3 + \dots) &= -a_0 + (a_1x^2 - a_1x) + (2a_2x^3 - a_2x^2) + (3a_3x^4 - a_3x^3) + \dots \\ &= -a_0 - a_1x + (a_1 - a_2)x^2 + (2a_2 - a_3)x^3 + \dots \end{aligned}$$

Thus $\ker \widehat{P} = 0$ (solve the above equation term-by-term from a_0).

Moreover, given a power series we can algebraically recursively solve for the values of a_0, a_1, \dots . E.g. there exist a_0, a_1, \dots such that

$$\widehat{P}(a_0 + a_1x + a_2x^2 + \dots) = x.$$

Here we need

$$0 + \underset{(-1)}{a_1}x + \underset{a_2}{(-1)x^2} - 2x^3 + \dots \quad (\text{solving recursively}).$$

It is not hard to see that this will have 0 radius of convergence.

Conclusion: \widehat{P} is an isomorphism, so $\widehat{\text{Sol}}_x(\mathcal{M}) = 0$.

But $\text{Sol}_x(\mathcal{M})$ turns out to have cokernel generated by x ; so

$$\text{Sol}_x(\mathcal{M}) \cong \mathbb{C}[-1].$$

Thus,

$$\mathcal{M} = \mathcal{D}/\mathcal{D} \cdot (x^2\partial_x - 1) \text{ is irregular at } 0.$$

Continue assuming X is 1d, and since we are working locally, continue assuming $X = \mathbb{C}$ and $x = 0$.

Question: When is $\mathcal{D}/\mathcal{D} \cdot P$ regular?

Definition 45. $\delta(P) = m - \text{ord}_0(a_m)$, where

$$P = a_m(x)\partial + x^m + a_{m-1}(x)\partial_x^{m-1} + \dots + a_0(x),$$

and ord_0 is the order of vanishing at 0.

We can think of \mathcal{D} as $\mathcal{D} = \mathcal{O}[\partial]$.

Definition 46.

$$\widehat{\delta}(P) = \max_{0 \leq k \leq m} \{k - \text{ord}_0(a_k)\}.$$

By convention, $\text{ord}_0(0) = +\infty$.

Example 101. If $P = x^N \partial^m$, then $\delta(P) = \widehat{\delta}(P) = m - N$.

Definition 47. The *index* of P is

$$\begin{aligned} \chi(\mathcal{D}/\mathcal{D} \cdot P) &:= \chi(\text{Sol}_X(\mathcal{D}/\mathcal{D} \cdot P)_0) \quad (\text{which is a two term complex}), \\ &= \dim(\ker(P)) - \dim(\text{coker}(P)). \end{aligned}$$

Similarly we define

$$\widehat{\chi}(\mathcal{D}/\mathcal{D} \cdot P) = \chi(\widehat{\text{Sol}}_X(\mathcal{D}/\mathcal{D} \cdot P)).$$

Exercise 17.1. Show that $\mathcal{D}/\mathcal{D} \cdot P$ is regular if and only if $\chi(\mathcal{D}/\mathcal{D} \cdot P) = \widehat{\chi}(\mathcal{D}/\mathcal{D} \cdot P)$.

Theorem 17.2 (Index Theorem).

$$\begin{aligned} \delta(P) &= \chi(\mathcal{D}/\mathcal{D} \cdot P) \\ \widehat{\delta}(P) &= \widehat{\chi}(\mathcal{D}/\mathcal{D} \cdot P) \end{aligned}$$

Corollary 17.3. $\mathcal{D}/\mathcal{D} \cdot P$ is regular if and only if $\delta(P) = \widehat{\delta}(P)$.

17.2. **Regular singularities in the local setting.** Recall the notation:

$$\mathcal{O} := \mathbb{C}\{\{x\}\} \cong (\mathcal{O}_{\mathbb{C}})_0 \supset \mathfrak{m} = x\mathcal{O}, \quad \text{and} \quad \widehat{\mathcal{O}} := \mathbb{C}[[x]].$$

Remark $\mathbb{C}[x] \subsetneq \mathbb{C}\{\{x\}\} \subsetneq \mathbb{C}[[x]]$.

$$\mathcal{D} := \mathcal{O}[\partial] \cong (\mathcal{D}_{\mathbb{C}})_0, \quad [\partial, f] = \partial(f).$$

Define the *field of fractions* of \mathcal{O} to be

$$\mathcal{H} := \mathcal{O}[x^{-1}],$$

(i.e. local meromorphic functions).

Example 102. For $\mathcal{D}/\mathcal{D} \cdot P$ a \mathcal{D} -module,

$$\begin{aligned} \text{Sol}(\mathcal{D}/\mathcal{D} \cdot P) &= \mathcal{O} \xrightarrow{P} \mathcal{O}, \\ \widehat{\text{Sol}}(\mathcal{D}/\mathcal{D} \cdot P) &= \widehat{\mathcal{O}} \xrightarrow{\widehat{P}} \widehat{\mathcal{O}}. \end{aligned}$$

Notation convention: From now on,

$$\text{Sol}(P) := \text{Sol}(\mathcal{D}/\mathcal{D} \cdot P).$$

This is a two term complex, so we only have

$$\begin{aligned} \mathcal{H}^0(\text{Sol}(P)) &= \ker(P) \\ \mathcal{H}^1(\text{Sol}(P)) &= \text{coker}(P) \end{aligned}$$

Remark $\ker(P) \subseteq \ker(\widehat{P})$ and $\text{coker}(P) \rightarrow \text{coker}(\widehat{P})$.

Recall we defined $\mathcal{D}/\mathcal{D} \cdot P$ to be *regular* if

$$\text{Sol}(P) \xrightarrow{\sim} \widehat{\text{Sol}}(P) \quad (\text{quasi-isomorphism}).$$

This turns out to be equivalent to

$$\chi(P) = \widehat{\chi}(P).$$

Remark Our previous remark tells us that we always have $\chi(P) \leq \widehat{\chi}(P)$.

Let

$$P = \sum_{k=0}^m a_k(x) \partial^k, \quad a_m(x) \neq 0.$$

Then we defined

$$\begin{aligned} \delta(P) &= m - \text{ord}(a_m(x)) \\ \widehat{\delta}(P) &= \max_{0 \leq k \leq m} (k - \text{ord}(a_k(x))) \end{aligned}$$

Theorem 17.4. *We have that*

$$\delta(P) = \chi(P) \quad \text{and} \quad \widehat{\delta}(P) = \widehat{\chi}(P).$$

Proof. The proof for δ uses analysis. The idea is that $P - a_m(x)\partial^m$ is a compact operator between certain Banach spaces (recall that P is Fredholm). Then there is an index theorem that says $\chi(P) = \chi(a_m(x)\partial^m)$. See [B] for details.

The proof that $\widehat{\delta}(P) = \widehat{\chi}(P)$ is a purely algebraic computation in manipulating power series. □

Claim: $\delta(P) = \widehat{\delta}(P)$ if and only if

$$P = \sum_{i=0}^m b_i(x)\theta^i, \quad b_i(x) \in \mathcal{K}, \quad \theta = x\partial,$$

and

$$\frac{b_i(x)}{b_m(x)} \text{ is holomorphic.}$$

Why? Start with $a_m(x) = x^{m-\delta(P)}\tilde{a}_m(x)$, $\tilde{a}_m(x)$ nonvanishing. Observe that

$$x^m \partial^m = \theta(\theta - 1) \cdots (\theta - (m - 1)).$$

Example 103. $P_1 = x\partial - \lambda = \theta - \lambda$ is regular.

Example 104. $P_2 = x^2\partial - \lambda$,

$$\begin{aligned} \delta(P_2) &= -1 \\ \widehat{\delta}(P_2) &= 0 \end{aligned}$$

is not regular. What fails in this example?

$$P_2 = x(x\partial) - \lambda = x\theta - \lambda,$$

and $\frac{\lambda}{x}$ is not holomorphic.

Remark When we rewrite P in this form, $\text{ord}(b_i(x)) = \text{ord}(a_k) - k$.

Definition 48. A P of the type

$$P = \sum_{i=0}^m b_i(x)\theta^i, \quad b_i(x) \in \mathcal{K}, \quad \theta = x\partial,$$

with

$$\frac{b_i(x)}{b_m(x)} \text{ is holomorphic,}$$

is called *Fuchsian*.

Remark Locally, Fuchsian differential operators are regular. Globally, however, they may not be regular – this is in fact a failure of Hilbert’s 23rd problem!

17.3. Another approach (still in the local setting).

- (1) $Pu = 0$ an ODE.
- (2) $\frac{d}{dx}\vec{u}(x) = \frac{\Gamma(x)}{x}\vec{u}(x)$, where

$$\Gamma(x) = \begin{pmatrix} 0 & 1 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \vdots & \vdots \\ \vdots & \vdots & & \ddots & 1 & 0 \\ & & & & 0 & 1 \\ \frac{-b_0}{b_m} & \frac{-b_1}{b_m} & \cdots & \cdots & \cdots & \frac{-b_{m-1}}{b_m} \end{pmatrix}$$

is a matrix in rational canonical form.

Then solutions u of the first equation are in one-to-one correspondence with solutions of the second equation

$$\vec{u}(x) = \begin{pmatrix} u(x) \\ \theta u(x) \\ \vdots \\ \theta^{m-1}u(x) \end{pmatrix}.$$

The condition now becomes

P is Fuchsian if and only if $\Gamma(x)$ is holomorphic.

18. MEROMORPHIC CONNECTIONS.

Definition 49. A meromorphic connection is a finite dimensional \mathcal{K} -vector space \mathcal{M} , together with

$$\nabla : \mathcal{M} \rightarrow \mathcal{M}$$

satisfying the Leibniz rule

$$\nabla(fm) = \frac{df}{dx}m + f\nabla m, \quad f \in \mathcal{K}, m \in \mathcal{M}.$$

Let $\tilde{\mathcal{K}}$ denote the space of (possibly multivalued) holomorphic functions on $\Delta_\epsilon^* = \{0 < |x| < \epsilon\}$ for arbitrarily small ϵ . “Possibly multivalued” should be interpreted as *functions on the universal cover*.

This generalizes the space of meromorphic functions in two ways:

- We are allowing multivalued functions.
- We are allowing essential singularities at 0.

We will use this as a solution space, after a remark on meromorphic connections.

Remark If \mathcal{M} is a meromorphic connection, pick a \mathcal{K} -basis e_1, \dots, e_n of $\mathcal{M} \cong \mathcal{K}^n$. Then we can write

$$\nabla = d - A, \quad d \text{ the de Rham differential, } A \text{ a matrix.}$$

So horizontal sections \vec{u} of \mathcal{M} are the same as solutions to the equation

$$\frac{d}{dx}\vec{u}(x) = A(x) \cdot \vec{u}(x).$$

Fact: If $\mathcal{M} \cong \mathcal{K}^m$ is a meromorphic connection, then it has a complex m -dimensional space of solutions in $\tilde{\mathcal{K}}$.

If $\vec{u}_1(x), \dots, \vec{u}_m(x) \in \tilde{\mathcal{K}}$ is a basis of horizontal sections, then we say that

$$S(x) := (\vec{u}_1 \mid \vec{u}_2 \mid \cdots \mid \vec{u}_m)$$

is a *fundamental solution*.

Definition 50. We say that $f \in \tilde{\mathcal{K}}$ has *moderate growth* if for all open $(a, b) \subseteq \mathbb{R}$ and $\epsilon > 0$ such that f is defined on $S_{(a,b)}^\epsilon$ as shown in Figure 43, there exists $N \gg 0$ such that

$$|f(x)| \leq C|x|^{-N} \quad \text{for all } x \in S_{(a,b)}^\epsilon.$$

Note: \mathcal{M} is a \mathcal{D} -module via $\nabla \leftrightarrow \partial$.

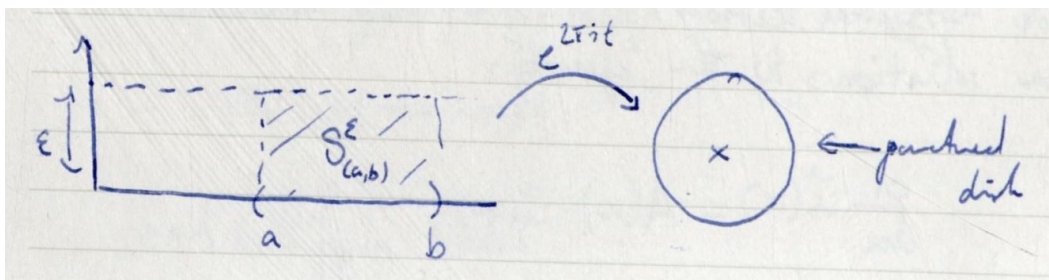


FIGURE 43. Universal cover of punctured disk, with strip $S_{(a,b)}^\epsilon$ shown.

Fact: If f is single valued, then moderate growth is equivalent to meromorphicity. (I.e. this is the way we say a multivalued function does not have essential singularities.)

Theorem 18.1. For \mathcal{M} a fixed meromorphic connection, the following are equivalent:

(1) \mathcal{M} is equivalent to a system of the form,

$$\frac{d}{dx}\vec{v}(x) = \frac{\Gamma(x)}{x}\vec{v}(x),$$

where $\Gamma(x) \in M_n(\mathcal{O})$ ($n \times n$ matrices).

(2) Same as above, but Γ is a constant matrix.

(3) All solutions to \mathcal{M} in $\tilde{\mathcal{X}}^m$ have moderate growth.

Also, all of these are equivalent to \mathcal{M} being regular.

Sketch that (3) implies (2). Let $S(x)$ be a fundamental solution matrix. Take

$$\lim_{t \rightarrow 1} S(e^{2\pi i t} x) = G \cdot S(x);$$

the LHS is another fundamental solution, so can be expressed in the form of the RHS. Call G the *monodromy matrix*. Let Γ be some matrix such that

$$e^{2\pi i \Gamma} = G,$$

where we can use the Jordan form for $G \in GL_n \mathbb{C}$ to make finding such a Γ easier. Note that $e^{\Gamma \log(x)}$ has the same monodromy as $S(x)$. So define

$$T(x) := S(x) \cdot e^{-\Gamma \log(x)}.$$

Then $T(x)$ is single valued with moderate growth (our original assumption), so $T(x)$ is meromorphic. Then $\vec{u}(x)$ is a solution of \mathcal{M} if and only if $T(x)^{-1}\vec{u}(x)$ is a solution of

$$\frac{d}{dx}(-) = \frac{\Gamma(x)}{x}(-)$$

where Γ is a constant matrix. □

Remark For those who are interested, the key ingredient in (1) \Rightarrow (2) is *Grönwall's inequality*. We will not be discussing this.

Example 105. (1) $\frac{d}{dx}u(x) = \frac{\lambda}{x}u(x)$ has solutions $u(x) = x^\lambda$. This is a multivalued function: to make sense of it, consider choosing a branch of log, or considering it as a function on the universal cover of Δ^* . This is regular.

(2) $\frac{d}{dx}u(x) = -\frac{1}{x^2}u(x)$ has as solution the single-valued function $u(x) = e^{\frac{1}{x}}$. This is non-regular – $e^{\frac{1}{x}}$ can grow faster than any meromorphic function.

Corollary 18.2. If $Pu = 0$ is an ODE (so $P \in \mathcal{D}$ – still considering the local situation) then P is Fuchsian if and only if all solutions to P in $\tilde{\mathcal{X}}$ have moderate growth.

Definition 51 (/Proposition). A meromorphic connection is *regular* if there exists a finitely generated \mathcal{O} -submodule $L \subseteq \mathcal{M}$ such that

$$\Theta L \subseteq L, \quad \Theta = x\partial,$$

and L generated \mathcal{M} over \mathcal{K} . We call L a *lattice*.

Remark This gives a coordinate free expression of regularity.

Given \mathcal{M} as in the theorem, take a basis e_1, \dots, e_m of \mathcal{M} such that the connection matrix looks like

$$\frac{\Gamma(x)}{x}, \quad \Gamma(x) \in M_n(\mathcal{O}).$$

Then take $L = \mathcal{O}e_1 + \dots + \mathcal{O}e_m$.

Lemma 18.3. *Given L as in the definition/proposition, we have that*

$$L \cong \mathcal{O}^m \quad (L \text{ is free}).$$

Thus we can think of L as a vector bundle on the unpunctured disk with connection

$$\nabla : L \rightarrow L \otimes \Omega^1(d \log(x))$$

induced from the original connection on \mathcal{M} .

I.e. L is a vector bundle with connection that has logarithmic poles. Here

$$d \log(x) = \frac{dx}{x}.$$

Example 106. From the first example above,

$$\mathcal{M} = \mathcal{H} \quad \text{and} \quad \nabla = d - \frac{\lambda}{x} dx.$$

We already (implicitly) chose a trivialization $e \in \mathcal{M}$ to write this, and then $L = \mathcal{O}e \subseteq \mathcal{M}$.

19. GLOBAL THEORY OF REGULAR SINGULARITIES.

There are two directions in which we could generalize this topic:

- *Irregular connections.* (Unfortunately we won't have time for this.)
- *Global theory.* (This will be our focus.)

Hilbert's 21st problem: *Let $\{a_1, \dots, a_k\} \subseteq \mathbb{A}^1 = \mathbb{C}$. Given $G_1, \dots, G_k \in GL_n \mathbb{C}$, does there exist a Fuchsian differential equation with singularities at $\{a_i\}$ and monodromy G_i at a_i ?*

Remark In the local case, given $G \in GL_n \mathbb{C}$ we can always find $\Gamma \in M_n(\mathbb{C}) = \mathfrak{gl}_n$ such that

$$e^{2\pi i \Gamma} = G \rightsquigarrow \frac{d}{dx} \vec{u}(x) = \frac{\Gamma}{x} \vec{u}(x).$$

Note that:

- (1) $\pi_1(\underbrace{\mathbb{A}^1 - \{a_1, \dots, a_k\}}_{=: U}) \cong F_k$, the free group on k letters.

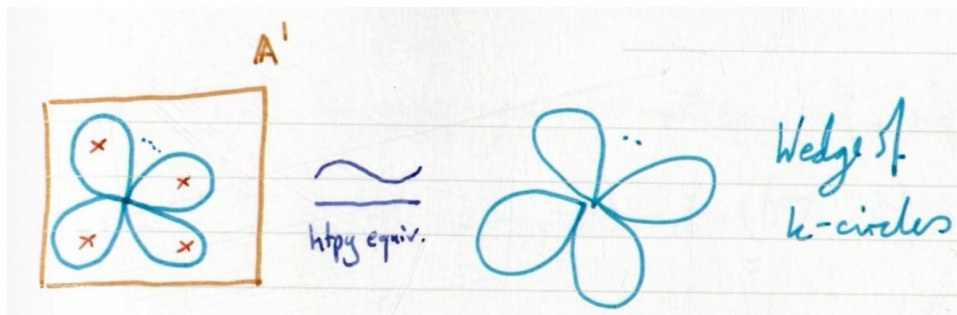


FIGURE 44. Determining $\pi_1(U)$.

So,

$$\{\text{Local systems on } U\} \simeq \text{Rep}(\pi_1(U)) \cong GL_n(\mathbb{C})^k / GL_n(\mathbb{C}),$$

i.e. a choice of k matrices up to simultaneous conjugation (change of basis).

- (2) $\mathbb{A}^1 = \mathbb{C} \subseteq \mathbb{P}^1 = \mathbb{C} \cup \{\infty\} \cong S^2$. So we could also demand in Hilbert's 21st problem that ∞ is not a singular point. For a long time, people thought that this problem would have a positive answer – in fact it does **not**, but something “very close” does.

19.1. Deligne's "solution" to Hilbert's problem.

First idea:

$$\text{Rep}(\pi_1(U)) \xleftarrow{\sim} \left\{ \begin{array}{c} \text{Locally constant} \\ \text{sheaves on } U \end{array} \right\} \xleftarrow{\sim} \{\text{Flat connections on } U\}$$

$$\mathcal{L} \longleftarrow \longrightarrow (\mathcal{O}_X \otimes_{\mathbb{C}_X} \mathcal{L}, d)$$

Given a flat connections $(\mathcal{V}^*, \nabla^*)$ on U , Deligne defined an extension \mathcal{M} a meromorphic flat connection on $(\mathbb{P}^1, \{a_1, \dots, a_k\})$. I.e. \mathcal{M} is a locally free $\mathcal{O}_{\mathbb{P}^1} \left[\frac{1}{x-a_1}, \dots, \frac{1}{x-a_k} \right]$ -module such that $\mathcal{M}|_U \cong \mathcal{V}^*$.

Note: For $j : U \hookrightarrow \mathbb{P}^1$ you can always take

$$j_*(\mathcal{V}^*) \in \mathcal{O}_{\mathbb{P}^1}\text{-modules.}$$

But in the world of analytic geometry, this sheaf allows for *essential singularities*, so is not a meromorphic connection. (This cannot happen in the algebraic world.) The \mathcal{M} we construct will be a subsheaf

$$\mathcal{M} \subseteq j_*(\mathcal{V}^*).$$

Turns out: \mathcal{M} has *regular* singularities at a_1, \dots, a_k ; i.e. there is $L \subseteq \mathcal{M}$ a vector bundle on \mathbb{P}^1 such that ∇ has log poles with respect to L .

Note: L may not be trivial! So this doesn't necessarily correspond to what one might think of as a system of differential equations on the plane.

I.e. This does **not** imply that Hilbert's 21st problem is true as stated above. But you could consider this the "correct" version (or "corrected" version) of the problem. Why? Because a differential equation is equivalent to

$$(\mathcal{M}, L, \nabla) \text{ together with a trivialization } L \cong \mathcal{O}^m.$$

But if L is not trivial, then the trivialization does not exist.

Remark \mathcal{M} is a \mathcal{D} -module: take its de Rham complex,

$$\text{DR}_{\mathbb{P}^1}(\mathcal{M}) = Rj_* \underbrace{(\text{DR}_U(\mathcal{V}^*))}_{\text{local system on } U \text{ in degree } -1}$$

19.2. **Higher dimensions.** If X is a complex manifold, $D \subseteq X$ a hypersurface, then Deligne proved

$$\begin{array}{ccc} \text{Conn}^{\text{reg}}(X, D) & \xleftarrow{\sim} & \text{Conn}(U) \\ \uparrow \text{⋮} & & \uparrow \text{⋮} \\ \text{flat connections on } X, \text{ meromorphic} & & \text{all flat connections on } U = X - D \\ \text{along } D, \text{ with regular singularities} & & \end{array}$$

We call this *Deligne's Riemann-Hilbert correspondence*.

20. ALGEBRAIC STORY.

As far as Sam knows, there is no self-contained algebraic story – it has to pass through the analytic story.

Suppose X is projective, $X \subseteq \mathbb{P}^N$. Then X is an algebraic variety (Chow's theorem). GAGA then implies that

$$\text{Conn}^{\text{reg}}(X^{\text{alg}}, D^{\text{alg}}) \simeq \text{Conn}^{\text{reg}}(X^{\text{an}}, D^{\text{an}}) \simeq \text{Conn}(U^{\text{an}}).$$

Of course we can also restrict

$$\text{Conn}^{\text{reg}}(X^{\text{alg}}, D^{\text{alg}}) \xrightarrow{\sim (\text{defn})} \text{Conn}^{\text{reg}}(U^{\text{alg}}) \subsetneq \text{Conn}(U^{\text{alg}}).$$

Example 107. On $\mathbb{A}^1 = \mathbb{C} = U$ define

$$\mathcal{V}^* = (\mathcal{O}_U, d - \lambda) \overset{\text{solutions}}{\longleftrightarrow} e^{\lambda x}.$$

$e^{\lambda x}$ is analytic and **not** algebraic (for $\lambda \neq 0$). But it *is* the solution to an algebraic equation. So $(\mathcal{O}_U, d - \lambda)$ is an *algebraic \mathcal{D} -module* on \mathbb{A}^1 ,

$$\mathcal{D}_U / \mathcal{D}_U(\partial - \lambda),$$

and these are all inequivalent for different λ . Analytically, however, $(\mathcal{V}^*)^{\text{an}} \simeq (\mathcal{O}_X^{\text{an}}, d)$ (i.e. we have equivalence for all λ).

Fact: This *algebraic \mathcal{D} -module* is not regular unless $\lambda = 0$.

Why? Need to embed $\mathbb{A}^1 \hookrightarrow \mathbb{P}^1$. Then $e^{\lambda x} \mapsto e^{\lambda \frac{1}{w}}$ near infinity, which has an essential singularity.

Note that $\mathcal{M}^{\text{alg}} = j_*^{\text{alg}}(\mathcal{V}^*)$ is a meromorphic connection, but is not regular unless $\lambda = 0$.

21. LAST REMARKS ON RIEMANN-HILBERT.

We work in the analytic setting. Let X be a complex manifold, $D \subseteq X$ a complex hypersurface, $U = X - D$. Consider Figure 45:

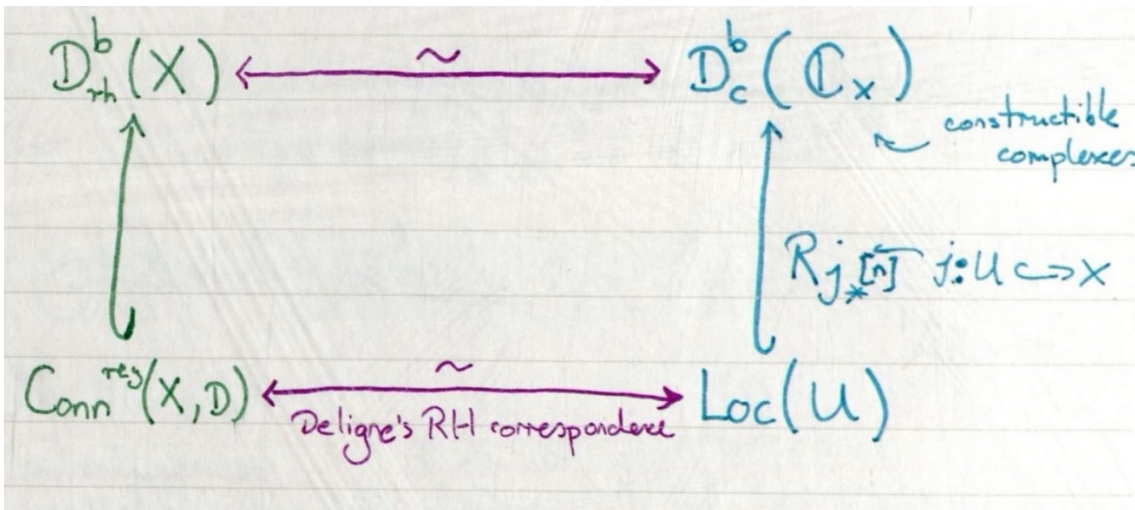
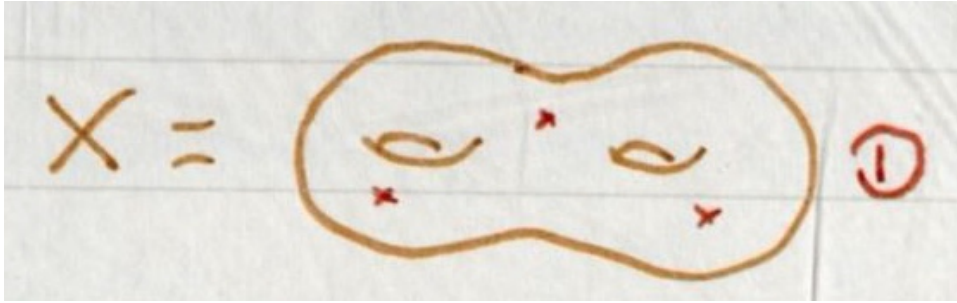


FIGURE 45. The Riemann-Hilbert correspondence.

Claim that this diagram in Figure 45 commutes.

Example 108. Some possible choices of (X, D) :

- (1) Punctured Riemann surface as in Figure 46.

FIGURE 46. Riemann surface X with punctures D .

(2) $Z \subseteq X$ a closed subvariety, $E \subseteq Z$ a hypersurface such that $Z - E =: V$ is smooth – see Figure 47.

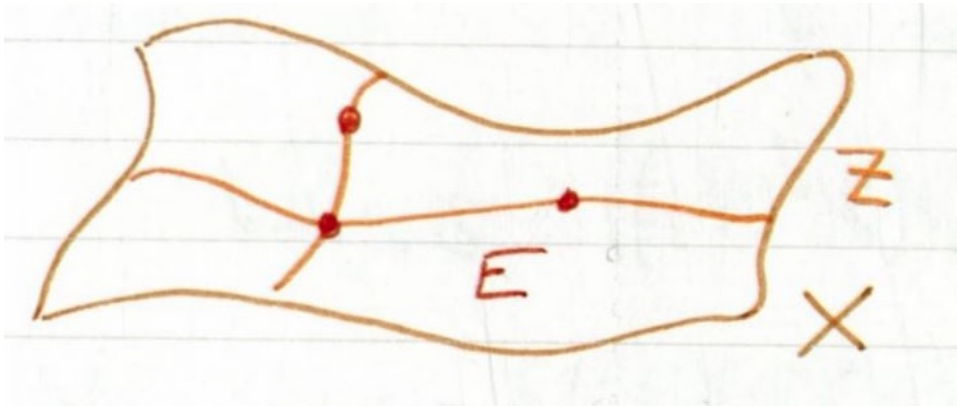


FIGURE 47. Situation described in example 2 above.

Let $k : V \hookrightarrow Z$, $i : Z \hookrightarrow X$. Given \mathcal{L} a local system on V , we produce

$$i_* Rk_*(\mathcal{L}) \in D_c^b(X).$$

In fact, these generate the category $D_c^b(X)$ as we range over all possibilities of (Z, E) .

We have an even more refined picture of the Riemann-Hilbert correspondence in Figure 48:

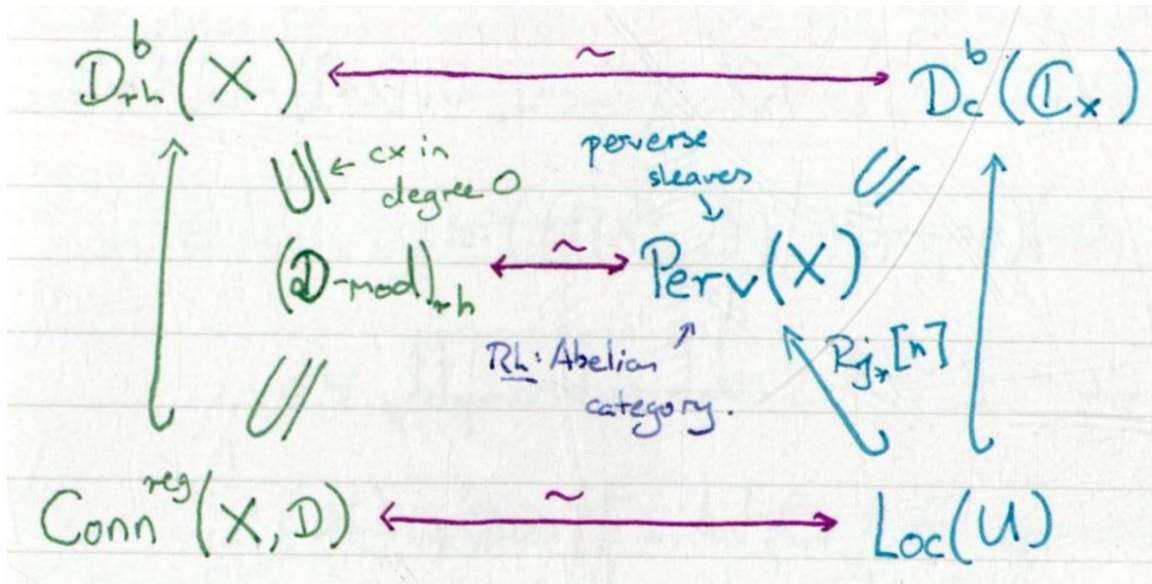


FIGURE 48. Refined Riemann-Hilbert correspondence.

We can define $\text{Perv}(X)$ to be the image of $(\mathcal{D}\text{-mod})_{\text{rh}}$ under Riemann-Hilbert, so that the equivalence in Figure 48 is tautological. But we can give an intrinsic characterisation as well.

Definition 52. An object $\mathcal{F} \in D_c^b(X)$ is called a *perverse sheaf* if

- $\dim(\text{supp}(\mathcal{H}^j(\mathcal{F}))) \leq -j$, and
- $\dim(\text{supp}(\mathcal{H}^j(\mathbb{D}_X \mathcal{F}))) \leq -j$.

Remark For X a \mathbb{C} -manifold with $\dim_{\mathbb{C}} X = n$,

$$\mathbb{D}_X(\mathcal{F}) = R\mathcal{H}om_{\mathbb{C}_X}(\mathcal{F}, \underbrace{\omega_X}_{\mathbb{C}_X[2n]}).$$

Example 109. $\mathbb{C}_X[n] \in \text{Perv}(X)$. (Recall: $\mathbb{C}_X[n] \cong \text{DR}_X(\mathcal{O}_X)$.)

- $\mathbb{D}_X(\mathbb{C}_X[n]) = R\mathcal{H}om(\mathbb{C}_X[n], \mathbb{C}_X[2n]) = \mathbb{C}_X[n]$.
- $\dim(\text{supp}(\mathcal{H}^{-n}(\mathbb{C}_X[n]))) = n$.

Example 110. Let $i : Z \subseteq X$ be a closed submanifold. Then

$$i_* \mathbb{C}_Z[\dim Z] \in \text{Perv}(X).$$

Remark All our shifts make it so that Poincaré duality is a “symmetric flip” across degree 0, rather than a “shifted flip”.

Fact: For irreducible $\mathcal{L} \in \text{Loc}(U)[n]$, there is a unique irreducible subobject of

$$Rj_*(\mathcal{L}) \in \text{Perv}(X).$$

We call it $IC(X, \mathcal{L}) \in \text{Perv}(X)$, the *minimal extension/intermediate extension/Goresky-MacPherson extension*. IC stands for *intersection cohomology*. This has the property that

$$IC(X, \mathcal{L})|_U \cong \mathcal{L}.$$

What does this correspond to in the \mathcal{D} -module world?

$$\mathcal{L} \in \text{Loc}(U) \leftrightarrow \mathcal{M} \in \text{Conn}^{\text{reg}}(X, D),$$

and there is a unique choice of lattice $L \subseteq \mathcal{M}$ such that the eigenvalues of $\Theta = f\partial_f$ have real part in $[0, 1)$ (a fundamental domain for the exponential function). Then

$$IC(X, \mathcal{L}) \leftrightarrow \mathcal{D}_X \cdot L \subseteq \mathcal{M},$$

the \mathcal{D} -module generated by L .

Remark $\text{Perv}(X)$ is an artinian abelian category. So *irreducible* means no nonzero subobjects, and such an object exists by the artinian property.

22. WIDER CONTEXT IN MATHS.

Want to understand the topology of complex varieties.

Example 111. $X \xrightarrow{f} C$ a flat proper family of varieties over a curve as in Figure 49:

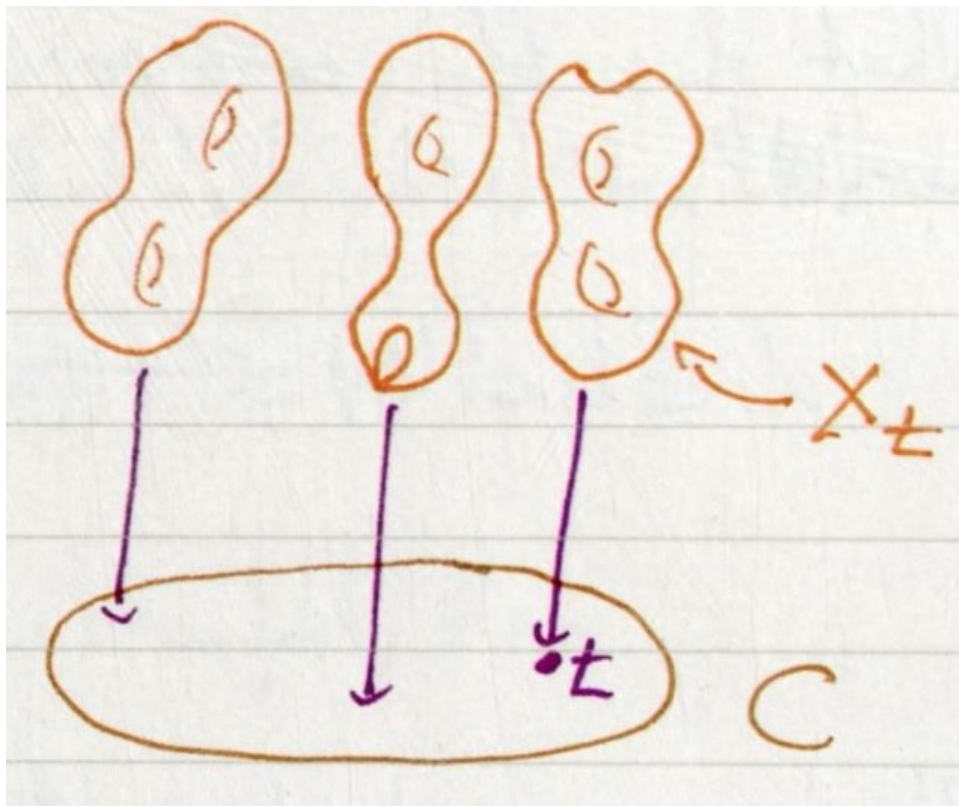


FIGURE 49. A flat proper family of varieties X over a curve C .

Under the Riemann-Hilbert correspondence we have

$$f_*^{\text{dR}}(\mathcal{O}_X) \longleftrightarrow Rf_*(\mathbb{C}_X) \in D_c^b(C).$$

Generically on C , this is a vector bundle with a flat connection (the *Gauss-Manin connection*), and we have

$$R^i f_*(\mathbb{C}_X)_t = H^i(X_t; \mathbb{C}).$$

Example 112. Take the family

$$X = \{y^2 = x(x-1)(x-t)\} \xrightarrow{f} (\mathbb{P}^1, \{0, 1, \infty\})$$

whose fibre over t are the solutions to the given equation. Then

$$R^1 f_* (\mathbb{C}_X) \leftarrow \rightsquigarrow \text{Picard-Fuchs equation on } \mathbb{P}^1.$$

It is a classical result that this equation has regular singularities at $\{0, 1, \infty\}$. Solutions of this differential equation are *hypergeometric functions*.

If X is a compact Kähler manifold, then

$$H^i(X; \mathbb{C}) = \bigoplus_{p+q=i} \underbrace{H^q(X; \Omega_X^p)}_{=: H^{p,q}(X)}.$$

This is called a *Hodge structure*. What happens to this structure as we vary X in a family?

Remark The Hodge structure also tells us how $H^i(X; \mathbb{Z}) \subseteq H^i(X; \mathbb{C})$ intersects with the decomposition.

Theorem 22.1 (A Torelli Theorem). *If X is an elliptic curve, then X is determined by $H^1(X)$ with Hodge structure:*

$$\begin{array}{ccc} H^1(X; \mathbb{Z}) & \longrightarrow & H^{0,1}(X) \xrightarrow{\text{quotient}} X \\ \parallel & & \parallel \\ \mathbb{Z}^2 & & \mathbb{C} \end{array}$$

Hodge filtration: (Warning: Check that the p 's and q 's are correct below!)

$$F^p H^i(X, \mathbb{C}) = \bigoplus_{\substack{p' \geq p \\ p'+q=i}} H^{p',q}(X).$$

As the fibres X_t vary with t , the $F^p H^i(X_t)$ form a holomorphic subbundle of the corresponding flat connection on, e.g., $\mathbb{P}^1 - \{0, 1, \infty\}$ (i.e. on the smooth locus).

This leads to the notion of a *variation of Hodge structure*,

$$\begin{array}{ccccc} (\mathcal{V}) & \nabla & F^\bullet & V_{\mathbb{Z}} & \alpha : \ker(\nabla) \xrightarrow{\sim} (V_{\mathbb{Z}} \otimes_{\mathbb{Z}} \mathbb{C}), \\ \uparrow & & \updownarrow & \up & \\ \text{vector bundle} & & \text{filtration of } \mathcal{V} & \text{locally const.} & \\ \text{w/ flat conn.} & & & \text{sheaf of free} & \\ & & & \text{abelian groups} & \end{array}$$

together with a condition called *Griffiths transversality*. ∇ does not preserve the filtration (since e.g. this would contradict the above Torelli theorem). Instead, we have the *Griffiths transversality theorem*:

$$\nabla F^i \subseteq F^{i-1}.$$

Then we have an analogy

$$\begin{array}{ccc} \mathcal{D}\text{-module} & : & \text{vector bundle with flat connection} \\ & \updownarrow & \\ \text{Hodge module} & : & \text{variation of Hodge structure} \end{array}$$

22.1. Further topics.

- Mixed Hodge modules (nearby/vanishing cycles)
- Moduli of flat connections/Moduli of Higgs bundles (Geometric Langlands)
- Beilinson-Bernstein (e.g. representations of \mathfrak{sl}_2 with trivial central character correspond to \mathcal{D} -modules on \mathbb{P}^1)

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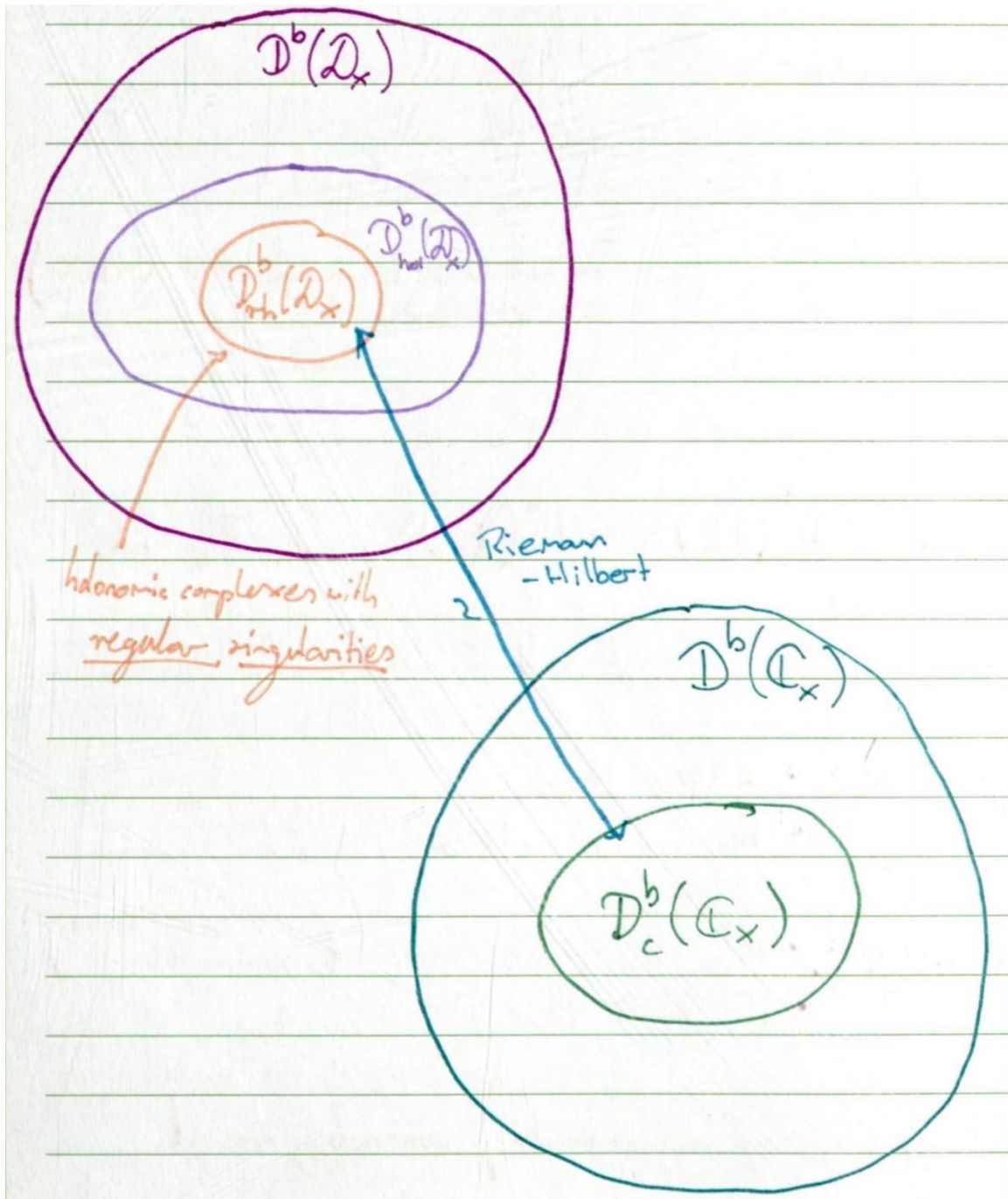


FIGURE 36. The Riemann-Hilbert correspondence.